# NAVAL POSTGRADUATE SCHOOL Monterey, California



## **THESIS**

APPLICATION OF NUMERICAL OPTIMIZAITON TECHNIQUES TO SURFACE COMBATANT DESIGN SYNTHESIS

by

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September 1998

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## APPLICATION OF NUMERICAL OPTIMIZATION TECHNIQUES TO SURFACE COMBATANT DESIGN SYNTHESIS

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Submitted in partial fulfillment of the requirements for the degree of

## MASTER OF SCIENCE IN MECHANICAL ENGINEERING

from the

NAVAL POSTGRADUATE SCHOOL September 1998

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This thesis presents the effort to incorporate a numerical optimizer into an existing ship design synthesis math model. The goal is to improve the functionality of the model while retaining the intrinsic value of the model's friendly user interface, which is greatly advantageous for its use as a learning tool. A description of the math model and its origin and intent are presented along with a discussion of numerical optimization techniques and tools. The integration and linking software is described along with the actual Integrated Ship Design System. Results of comparison and sensitivity studies are also presented.

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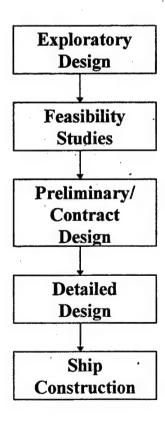
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#### I. INTRODUCTION

#### A. BACKGROUND

The process of designing a modern combatant ship is an exceptionally complicated and intricate undertaking. The challenge of the ship designer is to engineer a total ship system that fulfills rigorous requirements within certain constraints, such as the laws of nature, the limits of technology and especially in today's environment, limited budgets. This requires the ship designer to have an in depth knowledge of numerous engineering disciplines and possesses a special ability to bring together or synthesize these diverse areas to create a balanced ship design.

The ship design process can be divided into several phases, each which increases in detail and resource expenditure as the process proceeds;



A successful ship design starts with a set of operational requirements generated by the end user. These requirements typically include a nominal mission profile and payload specifics (i.e. combat systems). The next step requires defining the initial concepts for the overall ship configuration. While the operational requirements may dictate a specific ship type (i.e. an oil tanker should be a monohull to maximize cargo capacity), the surface combatant can take on many forms (monohull, multihull, wave piercer, etc.), each of which may have advantages and disadvantages but still fill the mission need. The same is true for the propulsion system; numerous permutations may meet the requirements, but the designer must choose wisely to produce the most balanced design. This leads to the implementation of feasibility studies, the objective of which is to conduct trade-off studies between capabilities, cost and risks which are then presented as whole-ship solutions. The whole-ship solution consists of the hull form type, its gross characteristics such as beam, draft, length, a gross cost estimate and the areas of major technical risk. These wholeship solutions come about through the use of a traditional iterative design spiral as shown in Figure 1. It is the improvement of this portion of the design process that is the focus of this thesis. The remainder of the design process is dedicated to refining the chosen design(s) and completing detailed engineering studies that eventually lead to the production of the ship [Ref.1].

It is during the feasibility study phase of the design process that having an ability to examine many different designs in a rapid, but consistent manner is highly desirable. A multitude of variables must be considered and evaluated using proven techniques that have been developed and refined through years of use. Sophisticated computer aided combatant ship design tools have been extensively developed over the years. The primary system

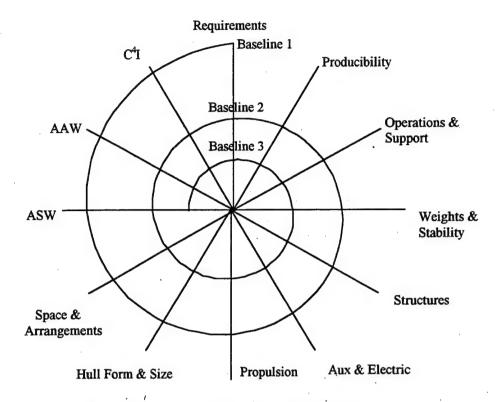


Figure 1. Iterative Ship Design Spiral [Ref. 1].

being used by the U. S. Navy is the Advanced Ship System Evaluation Tool (ASSET) [Ref. 2]. But for the student, these design tools are really too far removed from the basics needed to learn and understand the fundamentals of ship design.

Efforts at the Department of Ocean Engineering at the Massachusetts Institute of Technology in the 1970s produced several naval combatant ship synthesis models. Those developed by Reed [Ref. 3], and Graham and Hamly [Ref. 4] are particularly relevant in that they form the basis of the model used in this thesis. The Simplified Math Model for the Design of Naval Frigates was adapted from these original models and has been revised several times throughout the years to add additional features and to keep pace with rapidly changing software. The model in its current form is written in Mathcad, which presents an

easy to read and understand object oriented environment for equations, while maintaining powerful evaluation capabilities.

#### B. OBJECTIVES

The simplified math model generates the basic data for a first order design, though it requires the designer to check manually and adjust numerous parameters to ensure they fall within the feasible range designated within the model. It is then up to the designer to choose what parameters to change if the results are infeasible, and this can lead to extended or fruitless searches in the wrong direction. To aid the designer in more rapidly reaching a reasonable design, it is possible to use the techniques of numerical optimization to drive the model to the best design for a given specific objective and set of constraints. For example, the designer may wish to minimize the displacement of a ship given a fixed payload, and that the principle dimensions (beam, draft, length) are constrained so that the ship will fit into existing dry dock facilities. The objective function becomes the mathematical expression for displacement, which must be minimized such that it does not violate the constraints placed on beam, draft, and length. This approach has an added benefit that it aids the student in understanding what variables and constraints control the design.

The use of numerical optimization is not new in the realm of ship design, and the literature records numerous efforts to incorporate optimization techniques stretching back to the 1960s. MIT demonstrated early leadership in the efforts to apply the methods of numerical optimization to practical ship designs. Chryssostomidis [Ref. 5] investigated commercial containership preliminary design, choosing a least cost criterion as the optimization goal. His study found that payload (i.e. cargo) volume and weight were

driving the overall operational costs, and his optimization of design focused on the development of vessels designed to the discrete sizing of shipping containers.

This type of study lent itself well to the easily quantifiable economic factors considered in the design of single-purpose commercial ships. Optimizing economic factors alone for multi-mission naval vessels on the other hand, is not so easily done due to the difficulty of quantifying missions that are not of an economic nature. Holmes [Ref. 6], and Wagner [Ref. 7] attempted to apply the least cost criterion to the design of a naval auxiliary and salvage tug. They found that military mission effectiveness cannot be readily measured in economic terms unless each ship's missions are completely specified. Also a numeric value for effectiveness must be applied and remain consistent when selecting between different designs.

These early efforts to apply optimization to ship design shared a common optimization technique, the exponential random search method, developed by Mandel and Leopold [Ref. 8]. It is essentially a brute force method that randomly generates guesses within the constrained design space for the design variables, and computes the objective function and compares it to the previous value. If the new value is less that the old, the new value replaces the old and the process is repeated until convergence. Development of more sophisticated optimization algorithms in the 1980s permitted further applications to ship design.

Jenkins [Ref. 9] applied the COPES/CONMIN optimization program developed by Vanderplatts [Ref. 11] to the Reed Ship Synthesis Model [Ref. 3]. This optimization program utilized more advanced techniques such as the method of conjugate directions for locally unconstrained problems and the method of feasible directions for the locally

constrained problem [Ref. 10]. The use of this sophisticated code permitted more rapid convergence of the ship synthesis program, which fulfilled the goal of allowing more designs to be considered during the preliminary design phase.

Improving the functionality of the MIT Simplified Math Model by adding an optimization capability is the central challenge of this research effort. The objective then, of this thesis is to incorporate proven numerical optimization tools into the MIT Simplified Math Model and have the system deliver an optimal and reasonable design under various payload conditions.

#### C. COMPUTER PROGRAM OVERVIEW

To successfully meet the objective requires the integration of several distinct computer modules, each in its own computer language, which alone cannot communicate with each other. The ship's payload data is generated using an Excel spreadsheet, the Simplified Math Model uses Mathcad to evaluate the ship design and the numerical optimizer is a Matlab program. To enable these disparate modules to pass data among themselves in a logical and meaningful manner, an integration and linking program called MathConnex is utilized. Through the use of MathConnex, all the necessary design variables can be generated, passed between modules and selected results displayed, all while remaining in a consolidated and user friendly work space. A MathConnex representative overview of the computer program is shown in Figure 2.

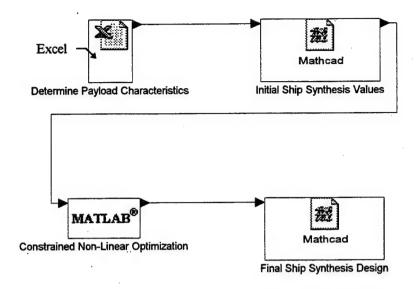


Figure 2. MathConnex Computer Program Overview.

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#### II. MIT SIMPLIFIED MATH MODEL

#### A. ORIGIN AND INTENT

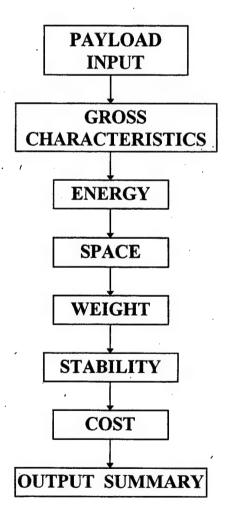
In the past, students of naval engineering were required to wade through pages of hand calculations, and stacks of tables and charts, (examples are contained in the Appendix C which are part of the Math Model documentation), to complete each iteration in the ship design spiral. The modern personal computer presents a means by which some of the drudgery can be eliminated while still providing a meaningful learning experience. The Department of Ocean Engineering at the Massachusetts Institute of Technology (MIT) has spent the past two decades developing a simplified math model for ship design. The current model traces its origins to the work completed by Reed [Ref. 3], which in turn drew heavily upon the Navy's destroyer design model, DD07, and the Center for Naval Analyses Conceptual Design of Ships Model (CODESHIP) developed in the 1960s. Since the personal computer has become ubiquitous and more powerful, the model has been converted from a main frame environment and major revisions have continued to be made to keep pace with hardware and software developments throughout the 1980s and 1990s.

The model is the central design tool utilized in the Principles of Naval Ship Design course offered at MIT. In its current form, the model is presented in a programming language called Mathcad [Ref. 13], which displays equations and relations in an easy to read object oriented format, while still performing high powered mathematical calculations. The visual interface allows students to work through problems as they would on a sheet of paper, but they can easily vary different parameters and quickly see the impact on the design, while not getting bogged down in routine calculations. This

allows more designs to be evaluated, and the student gains a greater appreciation for the ship design process.

#### **B.** PROGRAM DESCRIPTION

The Mathcad display of the model is very easy to read and understand, since it looks just like a sheet of equations, with actively updated graphs, tables and a summary of output. Mathcad reads from left to right, and from the top to bottom of the page, which allows the model to be organized according to the following macro flow diagram.



Most of the user-supplied payload data is generated using an Excel spreadsheet which contains weight, center of gravity, area and electrical power requirements for

current and near future surface combatant systems. Additional inputs such as crew size, type of power plant and speed requirements are generated by the user and all this data is then manually input to the model. The gross characteristics of the ship are then generated using the form coefficient values and displacement, which are varied by the user in the output summary section. Energy requirements for propulsion and electrical service load are calculated to ensure the installed power plant is sufficient and to provide the fuel weight and volume for the given endurance. Area, volume and weight calculations for the rest of the ship follow. Finally, the static, intact stability is calculated and a simplified cost model generates the lead ship cost.

The model's summary section contains the ship design form coefficients that are set by the designer. These coefficients are limited in range due to the constraints imposed when using Taylor Standard Series hull resistance data [Ref. 12]. There are four coefficients that are manipulated by the designer; the Prismatic Coefficient  $C_P$ , the Maximum Transverse Section Coefficient  $C_M$ , the Beam-to-Draft Ratio  $C_{BT}$ , and the Displacement-to-Length Ratio  $C_{\Delta L}$ . These coefficients are assigned as global variables and fix the basic characteristics for the design being considered. The model uses these fixed values along with a designer-provided estimate of the displacement,  $W_{FL}$ , to generate values for the beam, draft, and length, which in turn generates a new displacement,  $W_T$ .

To initiate use of the model, all the user-supplied data is input in the first section and in the output summary page. For the first iteration, the displacement is calculated assuming the payload weight is ten percent of the full load displacement and is entered in the summary page as W<sub>FL</sub>. The model then generates a new displacement, W<sub>T</sub> which is compared to the previous displacement, W<sub>FL</sub>. After each iteration, several values in the

model must be checked to ensure the design is valid, and these are highlighted by the double pound sign (##) in the right margin. If all the checks are satisfactory, the next iteration is completed by changing W<sub>FL</sub> to the value in W<sub>T</sub>. Once the displacement error is sufficiently small, usually around one percent, and the checks throughout the model are satisfactory, the model has converged. If the values to be checked in each iteration are not satisfactory, then the designer must change one or more of the variables to bring the design into compliance. The form coefficients are the variables that are manipulated for a fixed payload, and it is here that the student can best see the impact of these on the overall design. Once a form coefficient is altered, the design iteration process is repeated until convergence is reached. A detailed model description containing the symbol lists and micro flow diagrams is contained in Appendix C.

#### C. LIMITATIONS AND MODIFICATIONS

The model clearly fills its intended purpose of providing an easy to use and understand design tool for the student of naval engineering. It requires the designer to pay close attention to the details of each iteration, preventing a "black box" mentality where numbers are input in one end and get spit out the other, without knowing what really goes on in between. The drawback is that all this manual manipulation does not lend itself to the inclusion of a numerical optimizer, which by definition must search through the entire design space and is iteration intensive. If each iteration required the designer to manually check for compliance within the design variable constraints, the optimization process would be agonizingly slow and its use would be deterred.

To best leverage the advantages of the model in conjunction with the optimizer and the payload generation spreadsheet, the transfer of data between them must be

improved. The MathConnex program fills the very well. MathConnex provides the channels through which the data flows between the different applications using simple variable designators and click-and-drag connections. The Mathcad model was modified so that the entire payload is automatically loaded from the Excel spreadsheet each time the model is run. Likewise, the values of the design variables generated by the optimizer are passed back into the model for the final design synthesis.

One of the checks required in the model is to ensure that the depth at the midship station,  $D_{10}$  is greater than the minimum calculated for the sheer line (see Section IV of the model). This was modified so that  $D_{10}$  will always be one foot larger than  $D_{10\text{min}}$ , thus ensuring compliance with the sheer line criterion. The remainder of the model remains in its original form.

#### III. NUMERICAL OPTIMIZER

#### A. OPTIMIZATION THEORY AND TECHNIQUES

The desire to provide the best solution to a design problem has always been a primary goal of designers. As our engineered systems have increased in complexity, producing just a feasible design can require significant effort. With the advent of the high speed computer, numerical mathematical methods have evolved that permit the designer to produce not only a feasible design, but through proper application of these mathematical methods, the designer can find the best or optimal solution to the problem with little additional effort.

For proper analysis, the design problem must be posed in a manner consistent with typical numerical optimization methods. A widely accepted form for a nonlinear constrained optimization problem is presented by Vanderplatts [Ref. 10];

Minimize:	$F(\mathbf{X})$		objective function
Subject to:	$g_j(\mathbf{X}) \leq 0$	<i>j</i> =1, <i>m</i>	inequality constraints
	$\mathbf{h}_k(\mathbf{X})=0$	k=1,l	equality constraints
	$X_i^I \leq X_i \leq X_i^u$	<i>i</i> =1, <i>n</i>	side constraints
	$\mathbf{X} = \{X_1 \ X_2 \ X_3 \dots$	$X_n$	design variables

The vector X contains the minimum number of design variables that describe the system to be optimized. The objective function is the relationship that expresses the interdependence of the design variables and is the function to be optimized. The constraint functions, explicit or implicit functions of the design variables, limit the design space that is searched to ensure feasibility of the solution. It should be noted that these functions and their first derivatives must be continuous in X.

Nonlinear constrained optimization requires the use of sophisticated algorithms which for the purposes of this research are described in detail in the Matlab Optimization Toolbox Handbook [Ref. 14]. It is worthwhile, though, to investigate a simple constrained optimization problem to demonstrate the basic concepts in the hope of creating a better understanding of the larger problem.

As a hypothetical example, consider the two dimensional problem using the ship's beam (B) and draft (T) as the design variables. The side constraints require the beam to be greater than 30 feet but less than 70 feet, and the draft greater than 10, but less than 30 feet. An inequality constraint uses the beam to draft ratio, which is no less than 2.8 and no greater than 3.7. In the standard form the problem would be expressed like this;

Minimize: F(B,T) objective function

Subject to:  $2.8 \le B/T \le 3.7$  inequality constraint

 $30 \le B \le 70$ 

 $10. \le T \le 30$  side constraints

 $X = \{B \mid T\}$  design variables

The objective function can be any continuous function of the design variables B and T. This usually represents some characteristic of the ship, such as displacement, cost, or payload fraction, which is to be optimized. The constraints bound the region of the design space and control the search so that only feasible solutions are returned. An unconstrained search might return the mathematical minimum as a negative displacement, which is obviously is infeasible. Figure 3 defines the design space, and it is easy to see that the feasible range for the objective function is contained within the outlined area and that the optimal minimal value is unique. This graphical representation clearly shows the

location of the optimum, but most design problems are much more complex and do not lend themselves to such an easy solution. As complexity of the design space increases, the only reasonable means to solve the optimization problem lies in the use of numerical methods.

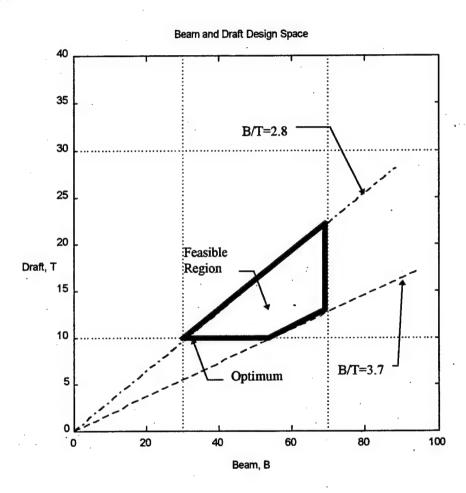


Figure 3. Two Dimensional Design Space

The optimization problem requires a sequential search of the design space to find the optimum, and this causes the process to be iterative by nature. The problem can then be reduced to two remaining tasks; find in which direction to search, and how big a step to take in that direction. The iterative form is then defined as;

$$\mathbf{X}^q = \mathbf{X}^{q-1} + \boldsymbol{\alpha}^* \mathbf{S}^q$$

where q is the iteration number, S is a vector search direction, and  $\alpha^*$  is a scalar that defines the step size of the move in the direction S. The search direction must be chosen so that it will reduce the objective function while not violating any constraints. The step size must be appropriately chosen so that the problem converges efficiently but accurately. The core remainder of optimization theory is therefore concerned with the details of choosing the best search direction and step size. References 10 and 14 provide in-depth discussion and analysis on this and many other optimization topics. Reference 14 is particularly helpful in describing the algorithms used within the Matlab optimizer.

#### B. MATLAB OPTIMIZER DESCRIPTION

Matlab invokes the constrained nonlinear optimizer by using the command "constr". The problem is posed in the standard form and is input into Matlab in the following format;

x = constr('function', x0, options, vlb, vub, [], p1, p2...)

- x is the vector of returned optimized design variables.
- 'function' is the M-file containing the objective function and constraints.
- x0 is the initial guess of the design variables.
- options controls output displays and termination criteria.
- vlb/vub are the upper and lower boundaries on the design variables or the side constraints.
- p1, p2 are additional variables to be passed into the 'function' M-file.

The 'function' M-file must be properly formatted to work with the optimizer;

### function [f,g]=function name(input variables)

- f is the value of objective function.
- g is the value of the constraint vector.

#### C. OPTIMIZER FUNCTION DESCRIPTION

#### 1. Objective Function

The choice to use full load displacement as the objective function was reached by weighing several factors. Previous optimization studies provided very good rationale for using displacement as the objective function when designing surface combatants [Ref. 9]. Additionally, the calculation of the displacement requires the use of all the major modules within the math model, which have subsequently been incorporated into the Matlab optimizer as function M-files. This will ease future research by allowing use and modification of existing function M-files and permitting them to be tailored to calculate different objective functions.

#### 2. Design Variables

The choice of design variables is derived from the choice of the objective function. A close study of the math model uncovered that all the derived weights that make up the displacement are a function of only five variables; beam, draft, length at waterline, prismatic coefficient and the maximum transverse section coefficient. Working carefully through the model, calculations that were independent of the design variables are calculated in the math model and passed as-is to the optimizer, while those calculations that are dependent on the design variables are calculated in separate Matlab function M-files and all are brought together as the objective function to be optimized. The design

variables change names between the different applications so Table 1 provides a cross reference of the variable names to aid in navigating though the different applications.

Design Variable	Mathcad Variable Name	Matlab Variable Name
Beam	В	x(1)
Draft	T	x(2)
Length at Waterline	LWL	x(3)
Prismatic Coefficient	C <sub>P</sub>	x(4)
Maximum Transverse Section Coefficient	C <sub>X</sub>	x(5)

Table 1. Design Variable Description.

#### 3. Constraints

The constraints that are incorporated into the optimizer are real, rational, engineering limitations on the design variables. They define what is a feasible design. The math model provides acceptable ranges for several coefficients and ratios and displays them in parentheses next to the current value on the summary page. These ranges are necessary to keep the designs within the valid range of the Taylor Standard Series [Ref. 12] for resistance calculations. The ranges are then converted to constraints for use in the optimizer. Inequality constraints include, Beam-to-Draft ( $C_{BT}$ ), Length-to-Beam( $C_{LB}$ ), GM-to-Beam ( $C_{GMB}$ ), and Displacement-to-Length ( $C_{AL}$ ). The acceptable ranges for the design variables  $C_P$  and  $C_X$  are included as side constraints in the "vlb, vub" command in Matlab. The side constraints for the remaining design variables are generated from design experience. Table 2 contains a summary of the constraints used in the optimizer. Note that Matlab requires the ranges to be split up and formatted as upper and lower inequality constraints.

Coefficient or Ratio	Range	Mathcad	Matlab Constraint Equation
Beam-to-Draft Ratio	2.8 - 3.7	C <sub>BT</sub>	g(1)=(2.8*x(2)/x(1))-1
			g(2)=(x(1)/(3.7*x(2)))-1
Length-to-Beam Ratio	7.5 - 10	$C_{LB}$	g(3)=((x(1)*7.5/x(3)))-1
			g(4)=(x(3)/(x(1)*10))-1
GM-to-Beam Ratio	0.09 - 0.122	C <sub>GMB</sub>	g(5)=(0.09*x(1)/GM)-1
			g(6)=(GM/(0.122*x(1)))-1
Displacement-to-Length	45 - 65	$C_{\Delta L}$	g(7)=(45*((x(3)/100)^3/f)-1
			$g(8)=(f/(((x(3)/100)^3)*65))-1$
Prismatic Coefficient	0.54 - 0.64	$C_P$	vlb = 0.54, vub = .064
Max Transverse Section	0.7 - 0.85	C <sub>X</sub>	vlb = 0.7, vub = 0.85

Table 2. Constraint Summary.

## IV. INTEGRATION AND LINKING OF COMPUTATIONAL SYSTEMS

#### A. MATHCONNEX PROGRAM DESCRIPTION

The MathConnex environment allows the user to integrate and link several types of application programs and data sources to form a single computational system. It uses a visual interface and it greatly simplifies the task of creating an integrated ship design synthesis program, which could otherwise be hobbled by the cumbersome data transfer requirements of the disparate computational elements.

MathConnex is capable of handling the three different applications used in the ship design program; Excel spreadsheets for the payload, Mathcad worksheets for the design synthesis, and the Matlab numerical optimizer. Each application is displayed as an icon on the worksheet with the associated data transfer "wires" connecting it to the other applications, see Figure 3. This plainly defines the program logic flow which follows the arrows on the wires. To view the contents of an application, one need only double click on the icon and the contents are displayed within the fully functional application window. When one is done with an application, clicking elsewhere on the worksheet collapses it back into an icon. This allows the inclusion of large application files and makes them easy to manipulate while keeping the overall program uncluttered on the MathConnex worksheet.

The data to be passed between applications is calculated and collected within each application for transfer to the next. It should be noted that each application is restricted to only four input and output ports, thus requiring most data to be gathered into arrays and assigned an appropriate transfer variable name, i.e. Input1, Ouput0, etc. Data transfer between the applications is handled by using click-and-drag wire connections between the

input/output ports on each icon. Once the data has been transferred, a similar variable transformation is accomplished to reassign the elements of the transfer arrays to the appropriate variable names in the next application.

At certain points during program processing it is desirable to view the intermediate results to ensure that the applications are generating useful data. The manner in which this is accomplished is the same as data transfer between applications, except the desired data is output to a view box on the worksheet.

MathConnex has enabled the integrated ship design system to fulfill the original intent of providing the student a design tool with a user friendly interface while greatly expanding the capabilities of the MIT Simplified Math Model through the addition of the numerical optimizer.

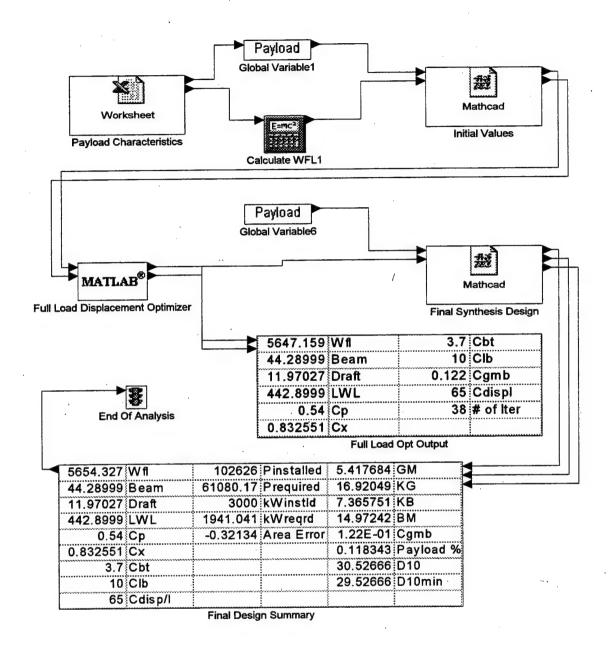


Figure 4. MathConnex Worksheet.

#### V. INTEGRATED SHIP DESIGN SYSTEM

#### A. PROGRAM DATA AND LOGIC FLOW

The previous section presented the general view of the operation and layout of the MathConnex worksheet. This section will present the detailed, step-by-step procedures that are executed in the Integrated Ship Design System (ISDS) worksheet as shown in Figure 4. Appendix G is a user's manual for the designer that provides the hands-on mechanics for proper set-up and use of the ISDS.

The ISDS MathConnex worksheet starts in the upper left hand corner with the Payload Characteristics contained in an Excel spreadsheet. By double-clicking on the icon, the Payload Characteristics spreadsheet is displayed on the screen. The designer then proceeds through the list of combat systems, modifying it to meet the specific payload for the desired design. The Excel spreadsheet then generates weight, area, stability and power data for the payload and transfers the array to Global Variable 1 and 6, "Payload", in the MathConnex worksheet. The total payload weight from the Excel spreadsheet is passed to the "Calculate WFL1" module to provide an initial guess of displacement.

The payload array and the displacement are then passed to the first Mathcad module, "Initial Values". This uses the math model to generate the initial values of the design variables and the non-design variable dependent weights and center of gravity information for use in the optimizer. Range, speed and manning data input by the designer are also passed to the optimizer and the "Final Synthesis Design" Mathcad module.

The Matlab module uses the transferred data to initialize the non-linear constrained optimizer to calculate the optimal minimal displacement and the associated design variable

values. This data, along with the constraint values and the number of optimizer iterations are output to the worksheet to provide intermediate evaluation of the design, and for later comparison to the final design synthesis results to check consistency. Additional detailed output from the optimizer can be viewed in a Matlab editor screen outside of the MathConnex environment. This data file, "outopt", contains important input data such as the initial guess for the design variables, and their side constraints. Output data includes updates of the objective function value for every six iterations, the magnitude of the constraint violation, and specifics regarding the algorithm search method. A message is also displayed which indicates if the optimization has successfully converged and identifies which constraints are active.

The optimal values of the design variables along with the original payload are transferred to the "Final Synthesis Design" Mathcad module. The math model calculates the final design and outputs selected design attributes to the screen. The complete design summary and all the calculations can be viewed by simply double-clicking on the "Final Synthesis Design" Mathcad module and scrolling through the pages. The stop light automatically toggles off the calculation.

#### B. DESIGN EXAMPLE

### 1. Payload Description

The effort required to define the payload and mission profile that the ship must fulfill is no trivial task. The guiding document, which is developed by the end user, is the Mission Needs Statement (MNS). This far-reaching document provides critical guidance, not only for the ship designer, but other acquisition programs, formulators of service and joint doctrines and cooperative efforts with our allies. The MNS that is utilized in this design example provides the requirements for expeditionary force surface combatants for the 21<sup>st</sup> century (i.e. SC-21) as modified at MIT for use in the Principles of Naval Ship Design (Course 13.412) when it was offered in the fall of 1997. The MNS lays the foundation for the DD-13A Background and Requirements Document, which provides a summary of combat systems that are arrayed into three variants to meet escalating needs.

This design example uses the DD-13A Medium Variant (Payload #2) with the following additional modifications;

- ⇒ Manning: 15 Officers, 135 Enlisted
- ⇒ Average Deck Height: 9 feet
- ⇒ Sustained Speed: 27 knots
- ⇒ Endurance: 7500 nautical miles
- ⇒ Stores Period: 45 days
- ⇒ Fin Stabilizers: None
- ⇒ CPS System: Full
- ⇒ Propulsion: Mechanical Drive LM-2500, 2 per shaft, 2 shafts, no APU's

⇒ Ship's Service Power: DDA 501-K34

The MNS, the DD-13A Background and Requirements Document, and the payload spreadsheet are contained in Appendix B.

### 2. Optimized Design Results

Before the initial run through the optimizer, the designer must assign values to the side constraints for the first three design variables in the Matlab module on the MathConnex worksheet. An upper and lower value for the beam, waterline length and draft will come from experience, but can be guided by real world constraints such as limiting the maximum beam to allow passage through the Panama Canal, or restricting maximum draft to allow transit to different ports around the world. The setting of these side constraints limits the design space to be searched by the optimizer, and creates the possibility that a local, vice global minimum may be returned if the side constraints are too limiting. Expanding and contracting the side constraints to investigate the full design space should be attempted for every design considered. The side constraints for C<sub>P</sub> and C<sub>X</sub> are fixed by the acceptable ranges permitted in the math model.

The optimizer should be sufficiently robust that any initial guess of the design variables returns the same optimum value of the objective function and design variables. The ISDS uses the data generated by the "Initial Values" Mathcad module for the first guess of the design variables ("x0") in the optimizer. This first guess can be easily changed by toggling on the designer-provided guess line in the Matlab module.

The optimizer will return a solution to the MathConnex worksheet even if the constraints force an infeasible solution, though the Matlab command window output data file will print a warning that no feasible solution has been found. The designer must

remain keenly aware when reviewing solutions in MathConnex to cross check the command window to ensure the optimizer has returned a feasible solution that has converged.

Six different runs with the ISDS were completed using the previously described payload to capture all the above possibilities. Detailed results of the Mathcad math model and optimizer outputs are in Appendix E, the combined results are in Table 3.

Design		Initial Run		Expand	<b>Expand Side Constraints</b>	raints	High Va	High Value Initial Guess	ssan
Attribute	Results	qnv-qlv	0x	Results	qnv-qlv	0×	Results	qnv-qjv	0x
Displacement, Wfl (Iton)	6123.424			6123.424			6123.424		
Beam, B (ft)	45.50163	40 to 70	55.745	45.50163	20 to 90	55.745	45.50163	20 to 90	100
Draft, T (ft)	12.29774	2.29774 10 to 30	16.892	12.29774	5 to 40	16.892	12.29774	5 to 40	100
Waterline Length, LWL (ft)	455.0163	455.0163 400 to 700	495.3	455.0163	455.0163 200 to 800	495.3	455.0163	455.0163 200 to 800	1000
Prismatic Coefficient, Cp	0.54	.54 to .64	9.0	0.54	.54 to .64	9.0	0.54	.54 to .64	10
Max Transverse Section, Cx	0.787983	.70 to .85	0.75	0.787983	.70 to .85	0.75	0.787983	.70 to .85	10
Beam-to-Draft, Cbt	3.7			3.7			3.7		
Length-to-Beam, Clb	10			10			10		
GM-to-Beam, Cgmb	0.122			0.122			0.122		
Displacement-to-Length, Cdl	99			65			65		
Number of Iterations	31			31			109		

		44444		_	_	_	_					
Optimum	0×		55.745	16.892	495.3	9.0	0.75		ng:	sible	found.	
Constrained Below Optimum	vlb-vub		20 to 90	5 to 10	406.4662 200 to 800	0.121007 .54 to .64	.70 to .85		Warning:	No feasible	solution found	
Constrai	Results	4729.255	40.22113	10.41899	406.4662	0.121007	0.281007	3.860366	10.10579	-0.33549	70.42378	37
Optimum	0x		55.745	16.892	495.3	9.0	0.75					
Constrainted Above Optimum	qnv-qlv		50 to 90	15 to 40	500 to 800	.54 to .64	.70 to .85					
Constrain	Results	7182.628	20	15	200	0.54	0.770449	3.333333	10	0.122	57.46102	32
ness	0×			0	0	0	0					
Low Value Initial Guess	vlb-vub		40 to 70	10 to 30	55.0163 400 to 700	.54 to .64	.70 to .85					
Low Va	Results	6123.424	45.50163	12.29774	455.0163	0.54	0.787983	3.7	10	0.122	65	49
Design	Attribute	Displacement, Wfl (Iton)	Beam, B (ft)	Draft, T (ft)	Waterline Length, LWL (ft)	Prismatic Coefficient, Cp	Max Transverse Section, Cx	Beam-to-Draft, Cbt	Length-to-Beam, Clb	GM-to-Beam, Cgmb.	Displacement-to-Length, Cdl	Number of Iterations

Table 3. Results from Optimizer Using Constant Payload.

The initial run used the output values from the "Initial Value" Mathcad model to provide the first guess of the design variables. The side constraints were set assuming a sufficient range to cover the expected size of the ship. The optimization converged successfully with four constraints remaining active (g(2), g(4), g(6), g(8)). To ensure that this was not a local minimum, the next run increased the range of the side constraints to cover more of the design space, while keeping the initial guess constant. The results were exactly the same, so this does appear to be a global minimum.

To check the performance capabilities of the optimizer, unrealistically high values for the initial guess were used, while the side constraints remained constant. The optimizer performed very well; it found the same optimum, but it took almost four times the number of iterations to converge on the solution. Correspondingly, the initial guess was set at zero to see if it would find the same optimum from below, which it did using only half the number of iterations required for the high initial guess.

As a final check of the capabilities of the optimizer, the side constraints were changed to exclude the location of the global minimum in the design space. When the lower side constraints were moved above the global minimum, a new local minimum was found that was equal to the new lower side constraints. This is an expected and feasible result, and one which should alert the designer to expand the design space and continue to search for the global optimum. Finally, the upper side constraint for draft was set lower than the optimal value. This resulted in no feasible solution being found, and the optimizer discontinued the search and printed the appropriate warning message. Note that the optimizer did output results, but that most of the constraints are quite obviously violated

and this should alert the designer to double check the Matlab command window data file output for warning messages.

The previous effort has definitively located the global minimal displacement for the given payload and constraints using the Matlab optimizer. A few additional checks must be made to ensure that the final design is feasible within the constraints of the math model. The final design summary in MathConnex contains data that needs to be compared to ensure the design is feasible; these include the installed versus required propulsion power and ship service electrical power and area and weight errors. If any of these are outside the designer-defined limits, adjustments to the characteristic inputs in the payload and math model must be made and the optimization process started again.

### 3. Comparison of Optimized versus Non-Optimized Design Results

The previous section demonstrates the ability of the ISDS to successfully link the Matlab optimizer with the MIT Math Model and produce a feasible design. The ISDS also behaved predictably when tested with unrealistic constraints and initial design variable guesses. The next logical question is does the ISDS produce a ship design of less displacement than if one used the MIT Math Model alone?

When using the MIT Math Model without the optimizer, several of the coefficient values are held fixed. The values assigned to these coefficients are chosen at the middle of the acceptable range to reduce any bias for this example;

$$C_P = .59$$
,  $C_X = .775$ ,  $C_{BT} = 3.25$ ,  $C_{\Delta L} = 55$ .

Six iterations were required to bring the weight error below one percent and Table 4 shows the results of the optimized versus non-optimized design.

The non-optimized design is nearly feasible with the exception that C<sub>GMB</sub> is outside of the acceptable range, the ship's service power requirement is slightly high and the area requirement is overstated by 20 percent. Though it is nearly feasible, it is not optimal, there is a 36 percent difference in displacement, a 26 percent reduction in payload fraction and almost an eight and one half percent increase in cost. The greatest difference between the optimized and non-optimized models is in the value of GM, a 127 percent difference. GM is defined as;

$$GM := KB + BM - KG$$

A closer look reveals that KG has a minimal difference between the two methods, the biggest changes are in KB and BM. BM is a cubic function in beam;

$$BM := \frac{LWL \cdot B^3 \cdot C_{IT}}{12 \cdot V_{FL}}$$

so small changes in beam result in large changes in BM. Beam is a function of displacement and the variable form coefficients C<sub>P</sub>, C<sub>X</sub>, and C<sub>BT</sub>;

$$B = \sqrt{\frac{C_{BT} V_{FL}}{C_{P} C_{X} LWL}}$$

and by fixing the values of the form coefficients in the middle of the range the, beam is forced to remain fairly large.

To demonstrates the sensitivity of B, BM, and GM, the starting displacement is held constant from before and moderate changes to the values of the form coefficients ( $\pm 10\%$ ) are made and the results tabulated in Table 5. The results show that changes to the form coefficients are almost one-for-one to changes in the beam (-15%), while draft and length remain essentially constant. The greatest difference though is in stability; GM

and BM drop dramatically, 55% and 31% respectively and these changes produce a feasible design, with the exception of area which can be adjusted for with minimal overall impact to the rest of the design.

This clearly demonstrates the influence of the coefficients of form in the math model, and how advantageous it is to have an ability to easily manipulate them during the design process. The ISDS provides this capability through its use of the optimizer which enables the entire design space to be considered simultaneously, instead of one small piece when the MIT Math Model is used alone.

Non-Optimized	Design Attribute	Non-Optimized	Percent Difference
8359.500026	Wfl (Iton)	7879.850351	-5.73777946
62.24414674	Beam (ft)	53.12115024	-14.65679422
19.15204515	Draft (ft)	18.97183937	-0.940921866
532.1307151	LWL (ft)	533.66969	0.289209927
0.59	Ср	0.64	8.474576271
0.775	Cx	0.85	9.677419355
3.25	Cbt	2.8	-13.84615385
8.549088436	Clb	10.04627512	17.51282251
55 (fixed)	Cdisp/l	55 (fixed)	
102626	Pinstalled (hp)	102626	
85806.67845	Prequired (hp)	85232.82952	-0.668769539
3000	kWinstld (kW)	3000	
3023.538718	kWreqrd(kw)	2745.998472	-9.179318373
0.204919419	Area Error	0.264553987	
-0.008626356	Weight Error	0.060870401	
12.68761149	GM (ft)	5.654802214	-55.43052198
19.66127644	KG (ft)	19.66713065	0.029775361
11.95711557	KB (ft)	11.34806536	-5.093621459
20.39177236	BM (ft)	13.9738675	-31.47301148
2.04E-01	Cgmb	1.06E-01	-47.77618486
8.064060715	Payload %	7.994497279	-0.862635325
1103.21963	Cost, \$Mil	1087.107089	-1.46050164
6	# of Iterations	1	

Table 5. Comparison of Modified Coefficients of Form in MIT Math Model.

(Note, shaded results violate model constraints.)

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#### VI. CONCLUSIONS AND RECOMMENDATIONS

#### A. CONCLUSIONS

The goal of this research effort was to improve the functionality the MIT Simplified Math Model by adding a numerical optimization capability that would deliver optimal and reasonable ship designs. This goal has been met, and even exceeded in some respects. MathConnex enables the ISDS to use all three application programs simultaneously in a singular, user friendly environment and presents consolidated results that can be easily checked for reasonableness and accuracy. This aids the designer in the ability to investigate more designs in the same amount of time than when using the MIT Math Model alone.

The ISDS and the MIT Math Model both produce feasible and reasonable designs, though they solve the problem in a fundamentally different way. The MIT Math Model takes a displacement and calculates the gross characteristics of beam, draft and length for a given set of fixed coefficients of form. The ISDS, though using the same mathematical basis for calculation, uses the gross characteristics and variable, but constrained, coefficients of form to calculate the displacement. This makes the ISDS a more flexible design tool through its ability to consider the entire design space during the feasibility study.

It is the Matlab optimizer that permits ISDS this flexibility. Its ability to take a multivariable, constrained design problem and return an optimum displacement value using fairly simple user supplied algorithms is key to the system's success. It is the positive synergistic effects of mating the math model with the optimizer that makes this such a powerful design tool.

#### B. RECOMMENDATIONS

This study was limited to investigating only one objective function, displacement. Efforts were focused on successfully integrating the different applications in the MathConnex environment and translating the Mathcad algorithms into Matlab function M-files in the optimizer. Fine tuning the optimizer to return consistent results with the MIT Math Model also required significant effort. The function M-files in the optimizer should lend themselves to easy manipulation for follow-on studies to develop different objective functions for optimization. A particularly relevant objective function in the current fiscal environment would be cost minimization. Another interesting area would be investigating the feasibility of power limited designs and comparing them to the current practice payload limited designs.

In conclusion, the ISDS is a design tool that possesses numerous characteristics that make it very attractive to the student and designer. As with any software program, understanding how the elements operate and interact is crucial to ensuring valid results. Gaining a thorough working knowledge of the MIT Math Model and ISDS User's Guide in Appendix G is the best way to guarantee that the optimum design is returned.

#### APPENDIX A. GLOSSARY

<u>Coefficients of Form:</u> Geometric qualities of the ship that can be related as ratios or dimensionless coefficients. Useful in comparing certain performance characteristics associated with hydrodynamic phenomena.

<u>Prismatic Coefficient (C<sub>P</sub>):</u> The ratio of the volume of displacement ( $\nabla$  or V<sub>FL</sub>) to the volume of a prism having waterline length (LWL) and a cross section equal in area to that of the maximum section at the designated waterline.

<u>Maximum Transverse Section Coefficient  $(C_X)$ :</u> The ratio of the maximum transverse section area to the product of the beam (B) and draft (T) at this section.

Beam-to-Draft Ratio (C<sub>BT</sub>): Ratio of the beam (B) to the draft (T).

<u>Displacement-to-Length Ratio ( $C_{AL}$ ):</u> The ratio of the full load displacement, in long tons, ( $\Delta_{FL}$  or  $W_{FL}$ ) to the waterline length (LWL) in feet.

$$C_{\Delta L} := \frac{\Delta_{FL}}{\left(\frac{LWL}{100}\right)^3}$$

Length-to-Beam Ratio (CLB): Ratio of the waterline length (LWL) to the beam (B).

Sheer Line: The line of intersection of the main or weather deck with the side of the ship.

Objective Function: The relationship that expresses the interdependence of the design variables and is the function to be optimized.

<u>Constraint Function</u>: Explicit or implicit functions of the design variables that limit the design space that is searched to ensure feasibility of the solution.

Active Constraint: An active constraint is one where the optimal solution lies on the constraint boundary.

<u>Function M-file:</u> Matlab file that allows the designer to create new mathematical functions that are added to the existing library of Matlab functions. A function M-file passes arguments in and out of its local workspace to reduce clutter in the main working environment.

GM: The distance between the ship's vertical center of gravity and its metacenter.

KB: The distance between the ship's baseline or keel and the vertical center of buoyancy.

BM: The distance between the ship's vertical center of buoyancy and its metacenter.

KB: The distance between the ship's baseline or keel and the vertical center of buoyancy.

<u>Transverse Waterplane Inertia Coefficient (C<sub>IT</sub>)</u>: The ratio of the moment of inertia of the waterplane area to that of the circumscribing rectangle in the transverse direction.

<u>Underwater Volume (V<sub>FL</sub>):</u> The volume of water displaced at full load.

## APPENDIX B. MIT SIMPLIFIED MATH MODEL PAYLOAD SPREADSHEET

## DD13A PAYLOAD

PAYLOAD NAME	WT KEY	wr	VCG	VCG	AREA	HULL	DKHS	CRUISE	BATTLE
			DATUM	FT AD	KEY	FT2	FT2	KW	KW
STEEL LANDING PAD (ON HULL) - SH-60 CAPABLE	W111	10.7		0.20		0			
128 CELL VLS ARMOR - LEVEL III HY-80	W164		38.31575	-10		0			
VGAS HY-80 ARMOR LEVEL II	W164 W165	85.7		18.3 -1.5		0			
SQS-53C 5M BOW SONAR DOME GROUP 100	WP100	155.4		-1.5	NONE	0			
dilot ito		100.4							
CIC W/UYQ-44 & 2X LSD	W410	19.34	0	35.58	A1131	1953	448	45.03	45.0
NAVIGATION SYSTEM	W420	7.29			A1132	0		55.99	53.
ADVANCED DIGITAL C4I (JTIDS/LINK 16/LINK22/TADIXS/TACINTEL)	W440	37.91	51	-46.84		1230.6		35.76	39.6
SPS-67 SURFACE SEARCH RADAR	W451	1.81	51	-10.00	A1121	0	70	8	
ADVANCED IFF	W455	2.32	51	-5.00	NONE	0	0	3.2	
SPY-1D MFAR SINGLE TRANSMITTER	W456	58.67	33.4	15.84		0		291.4	345.1
X-BAND RADAR AND FOUNDATION, 110 FT ABOVE BL	W456	4.11	0	113.00		0			220.1
SQS-53C 5M BOW SONAR DOME ELEX	W463	57.7	0	9.3		1942			3
LIGHTWEIGHT BROADBAND VARIABLE DEPTH SONAR (LBVDS)	W464	0.24		-6.20		200	0		4.
SSQ-61 BATHYTHERMOGRAPH	W465	0.31		-10.90		85.5		0	
SQQ-28 SONOBUOY PROCESSING SYSTEM	W466	5.26		-44.86		0		1.15	1.1
ADVANCED INTEGRATED ELECTRONIC WARFARE SYSTEM (AIEWS)  AN/SLQ-25A NIXIE	W472 W473	0.24		20.60 -6.20		200			6.
MK36 DLS W/6 LAUNCHERS	W474	0.96		5.39		200		3 2.4	4.
MINEHUNTING AUV / REMOTE MINEHUNTING SYSTEM	W478	0.24		-6.20		200		3	2.
AEGIS-BASED VGAS GFCS [UYQ-21 + UYK-44]	W478 W481	3.32		0.00		200			11.7
AN/SWG-1 HARPOON CONTROL IN CIC	W482		38.31575	10.80		0		9.64	4.9
MK99 GMFCS W/CEC W/3 SPG-62 ILLUM	W482	14.29			A1220	0		13.4	30.8
VLS WEAPON CONTROL SYSTEM	W482		38.31575		A1220	56		13.62	19.6
ADVANCED TACTICAL WEAPON CONTROL SYSTEM (ATWCS)	W482	5.6		-7.80		0		13.27	13.2
ASW CONTROL SYSTEM W/SSTD [ASWCS]	W483	3.75		-12.60		320			8.6
COMBAT DF	W495	8.26		21.00		020		15.47	19.3
ELECTRONIC TEST & CHECKOUT	W499		38,31575	10.80		0			
GROUP 400	WP400	238.96		122	100.00	6187.1		791.7	877.5
FWD 64-CELL VLS MAGAZINE DEWATERING SYSTEM	W529	7	35.0585	-0.46	NONE	0	0	0	
AFT 64-CELL VLS MAGAZINE DEWATERING SYSTEM	W529	7		-0.46		0			
COOLING EQUIPMENT FOR SPY-1D	W532	9		-34.00		0		0	
COOLING ADJUSTMENT FOR X-BAND RADAR	W532	4,43		9.81		47.85			13.6
LAMPS MKIII AVIATION FUEL SYS	W542	4.86	35.0585	-11.00	A1380	30	0	2	2.
LAMPS MKIII RAST/RAST CONTROL/HELO CONTROL	W588	31.1	35.0585	-1.60	A1312	219	33	4.4	4.
GROUP 500	WP500	63.39				296.85	993.8	20.04	20.9
SQS-53C 5M BOW SONAR DOME HULL DAMPING	W636	6.7	0	-2.5		0		0	
LAMPS MKIII AVIATION SHOP AND OFFICE	W665	1.04		-4.50	A1360	194	75	0	
GROUP 600	WP600	7.74				194	75	0	(
VGAS 155 MM	W710	10.2	33.4	18.30		0		10	34
2X HARPOON SSM QUAD CANNISTER LAUNCHERS	W721 W721	4.1			A1220	0			1.4
FWD MK41 VLS 64-CELL AFT MK41 VLS 64-CELL	W721	107.72		1.14		128 128	0	69.65	69.6
2X MK32 SVTT ON DECK	W750	5.55		2.20		0		69.65	69.6
GROUP 700	W7	235.29		2.20	A1244	256		151.3	179.
		200.20				250	301	151.5	173.
VGAS AMMO 680 RDS	WF21	11.3	33.4	13.60	NONE	0	0	0	
HARPOON MISSILES 8 RDS IN CANNISTERS	WF21	3.78		5.00		0		0	
AFT MK 41 LAUNCHER MISSILE LOADOUT (ESSM, SM. VLA, TLAM, ATACMS)	WF21	144		0.34		1420		0	
FWD MK 41 LAUNCHER MISSILE LOADOUT (ESSM, SM, VLA, TLAM, ATACMS)	WF21	144		0.34		1420	720	0	
MK46 LWT ASW TORPEDOES 6 RDS IN SVTT TUBES	WF21	1.36		2.50		368	720	0	
MK36 DLS SRBOC CANNISTERS - 100 RDS	WF21	2.2		11.60		0			
SMALL ARMS AMMO - 7.62MM + 50 CAL + PYRO	WF21	4.1		-6		0		ď	
LAMPS MKIII 18 X MK46 TORP & SONOBUOYS & PYRO	WF22	9.87		4.80		0		9	
LAMPS MKIII 2 X SH-60B HELOS, UAV'S, AND HANGAR (BASED)	WF23		35.0585		A1340	0		5.6	
LAMPS MKIII AVIATION SUPPORT AND SPARES	WF26		35.0585		A1390	357			
BATHYTHERMOGRAPH PROBES	WF29	0.21		-6.00	NONE	0			
GROUP WF20	WF20	342.97				3565	5434	5.6	
LAMPS MKIII:AVIATION FUEL (JP-5)	WF42	63.8	0	10.4	A1380	0	0	0	
VARIABLE MILITARY PAYLOAD (WF20+WF42)	WVP	406.77							
ARMAMENT (WP500, WP600, W7, WF20)						4311.85	7403.8		
								KWP	
TOTAL PAYLOAD	WP	1107.6				10499	13585.5	968.64	1083.9
DATUM DEFINITIONS:									
	DEPTHO	47.445		VCG P:	0.00				
	DEPTH3	43.232		VCG VP:	0.00				
	DEPTH6.5	38.316							
	DEPTH10	33.4							
	DEPTH15	35.059							
	DEPTH20	36.717							
	DEPTH20 BL MAST BAS	0							

# APPENDIX C. MIT SIMPLIFIED MATH MODEL MATHCAD WORKSHEET SUPPORTING DOCUMENTATION

# MASSACHUSETTS INSTITUTE OF TECHNOLOGY Department of Ocean Engineering

13.412 Handout

## SIMPLIFIED MATH MODEL FOR THE DESIGN OF NAVAL FRIGATES

Adapted from the US Navy Synthesis Model by C. Graham R. Hamly September, 1975

Revised by C. Graham and J. Reed: September, 1986

D. Peer: 16 July 1990

C.B. Sweeney: August, 1991

## LIST OF REVISIONS

Rev	Author	Date	Description
1	G. Hottel K. McCoy	24 Dec 88	General Revision
2	D.Peer	4 Jun 90	-Added table of Revision -Changed L/D limit to 15 -Corrected hull vol avail to account for volume of auxiliaries -Moved donar dome water from load weights to weight group 4 -Changed bearing weight to account for propeller weight
3	C.B Sweeney	1 Aug 91	Clarifications added, general revision and conversion to Word Perfect 5.1 files
	•		
			•
·			

## **List of Enclosures**

Enclosure (1): Math Model Macro Flow Diagram

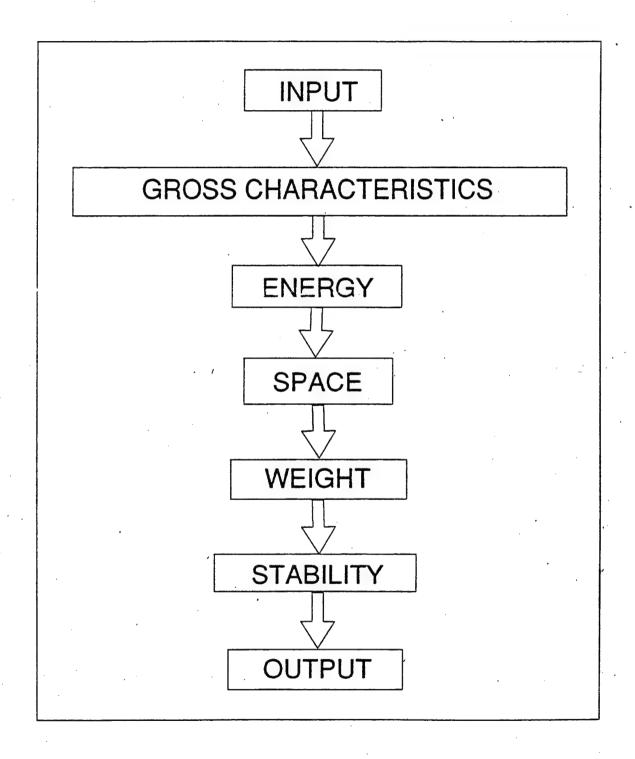
Enclosure (2): Symbols Used in Math Model

Enclosure (3): Micro Flow Diagrams for Frigate Math Model

Enclosure (4): Taylor Standard Series Made Easy

Enclosure (5): Energy Balance Module

## MATH MODEL MACRO FLOW DIAGRAM



Math model 1 Enclosure [1]

## SYMBOLS USED IN MATH MODEL

### L INPUT SYMBOLS

L HITUI	SIMBULS
ADPA	Payload deck area in deckhouse - armament, ft <sup>2</sup>
ADPC	Payload deck area in deckhouse - command/control, ft <sup>2</sup>
A <sub>HPA</sub>	Payload deck area in hull - armament, ft <sup>2</sup>
A <sub>HPC</sub>	Payload deck area in hull - command/control, ft <sup>2</sup>
B <sub>MB</sub>	Width of machinery box, ft
C <sub>A</sub>	Correlation coefficient = 0.0005
E	Endurance range at Ve, nautical miles
EPCHL	Endurance period chilled provisions, days
EPDRY	Endurance period dry goods, days
EPFRZ	Endurance period frozen provisions, days
EP <sub>OSM</sub>	Endurance period general stores, days
FR	Propulsion fuel rate at V, lbs/SHP-hr
FR <sub>c</sub>	Generator fuel rate, lbs/kW-hr
. H <sub>T</sub>	Height between decks, ft
H <sub>MB</sub>	Height of machinery box, ft
kW <sub>B</sub>	Battle electrical load, kW
kW <sub>24</sub>	Average 24 hour electrical load, kW
L <sub>MB</sub>	Length of machinery box, ft
N <sub>E</sub>	Number of enlisted accommodations
No	Number of officer accommodations
N <sub>s</sub>	Number of shafts
N <sub>T</sub>	Total number of accommodations
PC	Propulsive coefficient
Pi	Installed shaft horsepower
v.	Endurance speed, knots
, V,	Maximum sustained speed, knots
W <sub>A</sub>	Ammo weight, tons
W <sub>H</sub>	Helo weight, tons
W <sub>HP</sub>	Weight of helo fuel, tons
WLO	Weight of lube oil, tons

W <sub>MT</sub>	Weight of masts, tons
W <sub>P</sub>	Payload weight
WPA	Payload weight - armament, tons
$W_{PC}$	Payload weight - command and control, tons
$W_{SD}$	Weight of sonar dome, tons
$W_{gw}$	Weight of sea water in sonar dome, tons
γ	Specific volumes, ft³/ton
$\nabla_{ ext{void}}$	Tankage volume, voids, ft <sup>3</sup>

## II. GROSS CHARACTERISTICS SYMBOLS

A <sub>m</sub>	Area of maximum section, ft <sup>2</sup>
В	Ship beam, ft
C <sub>M</sub>	Midship section coefficient, $C_M = C_X$
C <sub>r</sub>	Prismatic coefficient, $\nabla_{HV}/(A_{k}\cdot L)$
C <sub>v</sub>	Volumetric coefficient
C <sub>x</sub>	Maximum section coefficient, A <sub>M</sub> /(B•T)
L.	Ship length, ft
T	Ship draft, ft
V/L <sup>5</sup>	Speed to length ratio, knot ∕√ft
$\Delta_{FL}$	Full load displacement, tons
$\Delta_{\mathtt{L}}$	Displacement to length ratio, ton/ft <sup>3</sup>
$\Delta_{HV}$	Underwater hull volume, ft <sup>3</sup>

## **III.ENERGY SYMBOLS**

$D_{P}$	Propeller diameter, ft
Ps	Effective horsepower = PC*SHP = V*R <sub>T</sub> /325.6
EHPBH	Bare hull effective horsepower
EHPBHT	Bare hull effective horsepower predicted by Taylor Series
. P.	Propulsive power at Ve, shaft horsepower
$P_{I}$	Installed power, shaft horsepower
$P_{lr}$	Shaft horsepower required to be installed to meet demand
P,	Propulsive power at V <sub>s</sub> , shaft horsepower
R <sub>T</sub>	Total ship resistance, lbs
$W_{\mathbf{F}}$	Endurance fuel weight, tons

#### IV. SPACE SYMBOLS

IV. SPACE	SYMBOLS
A <sub>DA</sub>	Deck area available in deckhouse, ft <sup>2</sup>
A <sub>DE</sub>	Deck area in deck house for bridge and chartroom, ft <sup>2</sup>
A <sub>DL</sub>	Deck area in deck house for living, ft <sup>2</sup>
A <sub>DM</sub>	Deck area in deck house for maintenance and access, ft <sup>2</sup>
A <sub>DPR</sub>	Total payload deck area required in deck house, ft <sup>2</sup>
A <sub>DR</sub>	Total arrangement deck area required in deck house, ft <sup>2</sup>
ADSF	Deck area in deck house for "ship" functions, ft <sup>2</sup>
A <sub>HA</sub>	Deck area available in hull, ft <sup>2</sup>
A <sub>HAB</sub>	Habitability allowance, ft²/man
A <sub>HL</sub>	Deck area in hull for living, ft <sup>2</sup>
A <sub>HPR</sub>	Total payload deck area required in hull, ft <sup>2</sup>
A <sub>HR</sub>	Total arrangement deck area required in hull, ft <sup>2</sup>
A <sub>HS</sub>	Stores deck area in hull, ft <sup>2</sup>
A <sub>HSF</sub>	Deck area in hull for "ship" functions, ft <sup>2</sup>
A <sub>MB</sub>	Cross sectional area of machinery box, ft <sup>2</sup>
Apro	Projected area of hull above water, ft <sup>2</sup>
CN	Cubic number = L* B * $D_{AV}$ * $10^{-5}$ , $ft^{3}$
C <sub>PMB</sub>	Prismatic coefficient of machinery box =V <sub>MB</sub> /(L <sub>MB</sub> *A <sub>MB</sub> )
D <sub>AV</sub>	Average hull depth, ft
D <sub>MB</sub>	Hull depth in vicinity of machinery box, ft
D <sub>o</sub>	Depth at station 0, ft
D <sub>10</sub>	Depth at station 10, ft
Dior	Depth at station 10; roll criteria, ft
D <sub>10MB</sub>	Depth at station 10; machinery box criteria, ft
D <sub>10 BC</sub>	Depth at station 10; bending moment criteria, ft
D20	Depth at station 20, ft
faux	Auxiliary space factor; class dependent
$\mathbf{f}_{t}$	Flare factor
F <sub>AV</sub>	Average freeboard, ft
F <sub>o</sub>	Freeboard at station 0, ft
F <sub>10</sub>	Freeboard at station 10, ft
F <sub>20</sub>	Freeboard at station 20, ft

H <sub>A</sub>	Helo deck area in the hangar, ft <sup>2</sup>
$I_{VD}$	Intake volume, deckhouse, ft³
$I_{v_H}$	Intake volume, hull, ft <sup>3</sup>
K <sub>1</sub>	Allowance factor for structure
K <sub>2</sub>	Allowance factor for expansion
$\mathbf{w}_{\mathbf{w}}$	Weight of potable water, tons
V <sub>sux</sub>	Volume of auxiliary spaces, ft <sup>3</sup>
$V_{D}$	Deck house volume, ft <sup>3</sup>
V <sub>DR</sub>	Total arrangement volume required in deck house, ft <sup>3</sup>
$V_{HA}$	Hull arrangement volume available, ft <sup>3</sup>
V <sub>HAW</sub>	Hull volume above water, ft <sup>3</sup>
V <sub>HR</sub>	Total arrangement volume required in hull, ft <sup>3</sup>
V <sub>HT</sub>	Total hull volume available, ft <sup>3</sup>
V <sub>MB</sub>	Volume of machinery box, ft <sup>3</sup>
$V_{\tau}$	Total ship volume available, ft <sup>3</sup>
V <sub>TA</sub>	Total arrangement volume available, ft <sup>3</sup>
V <sub>TK</sub>	Tankage volume, ft <sup>3</sup>
V <sub>TR</sub>	Total arrangement volume required, ft <sup>3</sup>

## V. WEIGHT SYMBOLS (All weights in long tons, 2240 lbs)

£	Deck house material factor
· kW <sub>I</sub>	Installed electrical capacity, kW
W <sub>B</sub>	Shaft bearing weight
$W_{BA}$	Weight of basic auxiliary systems
$W_{BH}$	Weight of basic hull
$W_{BM}$	Weight of basic machinery
$\mathbf{w_c}$	Weight of crew
W <sub>cc</sub>	Weight of cable for command and control equipment
$W_{co}$	Weight of gyro and interior communications equipment
$\mathbf{W}_{\infty}$	Weight of other command and control equipment
$W_{DH}$	Weight of deck house
$W_{ extsf{FD}}$	Weight of foundations

W,	Weight margin
W <sub>GSM</sub>	Weight of general stores
WL	Light ship weight
WLD	Weight of load items
W <sub>mergin</sub>	Weight margin factor
Worh	Weight of hull related outfit and furnishings
Worr	Weight of personnel related outfit and furnishings
WPR	Propeller weight
WPRV	Weight of provisions
· w,	Shafting weight per unit length, tons/ft
Ws	Shafting weight
W <sub>ss</sub>	Weight of auxiliary steam system
W <sub>sT</sub>	Weight of total shaft system
W <sub>sw</sub>	Weight of seawater in sonar dome
W <sub>T</sub>	Total weight
$\mathbf{W}_{\mathbf{w}}$	Weight of potable water
W <sub>1</sub>	Hull structure weight
W <sub>2</sub>	Propulsion machinery weight
W,	Electrical plant weight
W <sub>4</sub>	Communications and control weight
$W_5$	Auxiliary systems weight
· W <sub>6</sub>	Outfit and furnishings weight
W,	Armament weight

## VI. STABILITY SYMBOLS

$A_{w}$	Area of waterplane, ft <sup>2</sup>
ВМ	Metacentric radius, ft
C <sub>rr</sub>	Transverse (area) inertia coefficient= I <sub>w</sub> /(L*B <sup>3</sup> )
C <sub>w</sub>	Waterplane area coefficient = $A_w/(B^*L)$
GM	Ship transverse metacentric height, ft
$I_{\mathbf{w}}$	Transverse area moment of inertia of the waterplane= $BM^*\nabla_{HV}$
KB	Ship vertical center of buoyancy, ft

KG	Ship vertical center of gravity, ft
$KG_L$	KG of Light Ship with KG margin
KGLD	KG of loads
KG <sub>Leen</sub>	KG of Light Ship without KG margin
KG <sub>margin</sub>	Margin on light ship KG
M <sub>LD</sub>	Moment of loads relative to base line, ft-tons (use subscripts corresponding to individual load item)
$M_{T}$	Total moment of all weight groups (includes margins), ft-tons
$M_{wo}$	Moment of weight group relative to baseline, ft-tons (use subscripts corresponding to individual weight group)
VCG <sub>wg</sub>	Vertical Center of gravity of weight group above baseline, ft (use subscripts corresponding to individual weight group)

### MICRO FLOW DIAGRAMS FOR FRIGATE MATH MODEL

### I. INPUT

Input: Owner - Performance Requirements, Constraints, and Design Philosophy expressed in Top Level Requirements

> Designer - Component/Subsystem Selection, Design Standards and Practices, Specific Design Parameters and Design Philosophy

> > TLR (Owner)
> > Design Philosophy

I1.	"Design to" Requirements (Goals, Thresholds)
	"Design to" Constraints"
	<b>↓</b>
I2.	Component/Subsystems
	Design Philosophy
	<b>↓</b>
	Adjustment to Model
	<b>\</b>
I3.	Design Practices and Standards
	Design Philosophy
	<b>↓</b>
	Adjustment to Model
I4.	Specific Design Parameters
•	Design Philosophy
	Adjustment to Model
	↓

Useful Output: Input file for specific ships

## II. GROSS CHARACTERISTICS

Input: W<sub>P</sub>, V<sub>s</sub>

$$W_P = W_{PA} + W_{PC} + W_A + W_H + W_{HF}$$

II1.  $W_P/\Delta_{FL}$ 

(Figure 1)  $\downarrow$   $\Delta_{FL}$ 

II2.  $V_s$ 

II3.  $C_{P} = f(V_{S}/\sqrt{L})$ 

 $C_X = f(V_s/\sqrt{L})$ (Figures 3 and 4)

 $C_{\mathbb{P}}, C_{\mathbb{X}}$ 

II4. L/B

(Tables 1 - 4)

B

↓

II5. B/T

(Tables 1 - 4)

↓

T

II6. Final Check:  $\Delta_{FL} = \rho \cdot g \cdot C_P \cdot C_X \cdot L \cdot B \cdot T/2240$ 

Useful Output :  $\Delta_{FL,C_P,C_X}$ , L,B,T, $\Delta_{L,C_V}$ 

# Micro Flow Diagrams (Continued)

## II. GROSS CHARACTERISTICS RELATIONSHIPS

II1. 
$$W_P = Given$$

$$\Delta_{FL}$$
 = Pick  $V_s$  = Given

II2. 
$$\Delta_{L} = \Delta_{FL}/(0.01 \cdot L)^{3}$$

II3. 
$$L = Pick$$

$$C_P$$
=Pick  $C_X$ =Pick

II6. 
$$g=Given$$
 $\rho=Given$ 

$$\begin{array}{l} \nabla_{\mathsf{HV}} \! = \! C_{\mathsf{P}} \! \bullet \! C_{\mathsf{X}} \! \bullet \! \mathsf{L} \! \bullet \! \mathsf{B} \! \bullet \! \mathsf{T} \\ C_{\mathsf{V}} \! = \! \nabla_{\mathsf{HV}} \! / \! \mathsf{L}^{3} \end{array}$$

Final Check:  $\Delta_{FL} = \rho \bullet g \bullet C_P \bullet C_X \bullet L \bullet B \bullet T/2240$ 

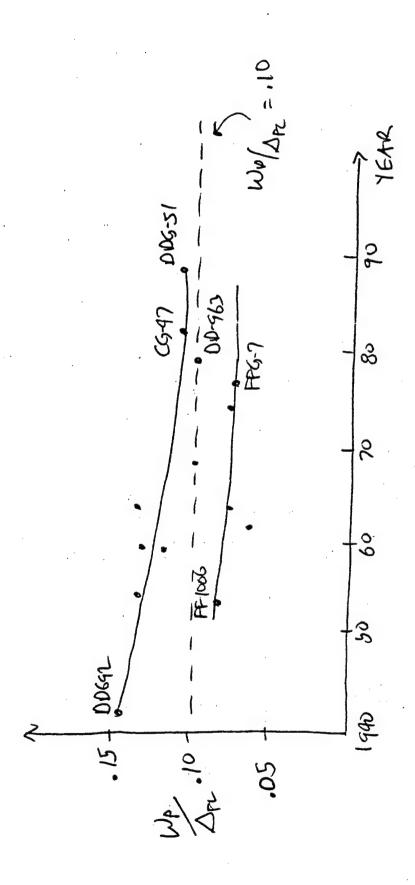
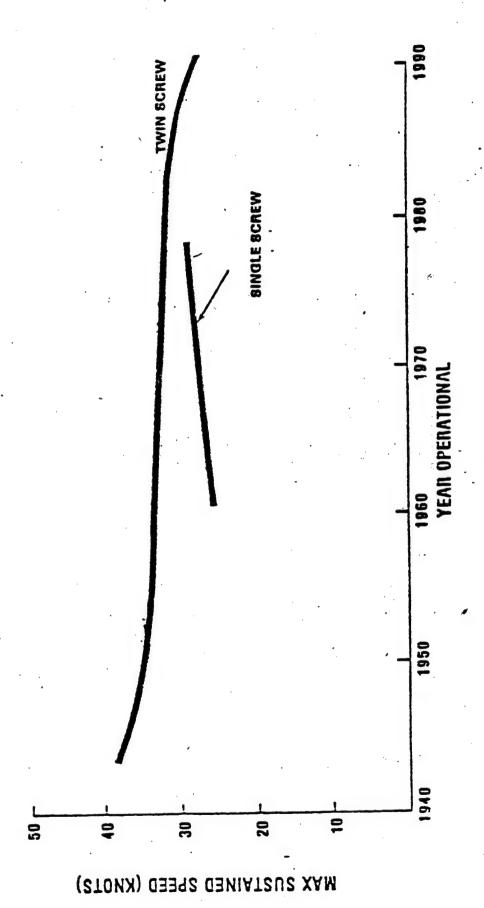


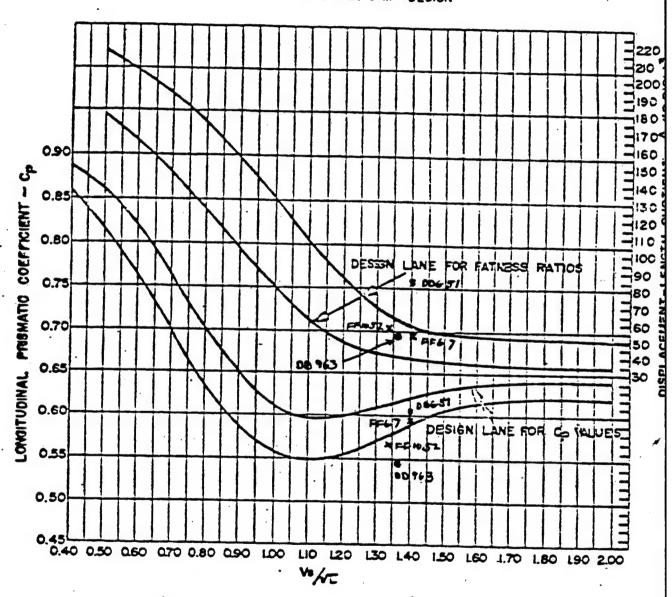
Fig. 1. PAYLOAD WEIGHT FRACTION

SPEED TREND



DESIGN LANES FOR A + CD

### HYDRODYNAMICS IN SHIP DESIGN

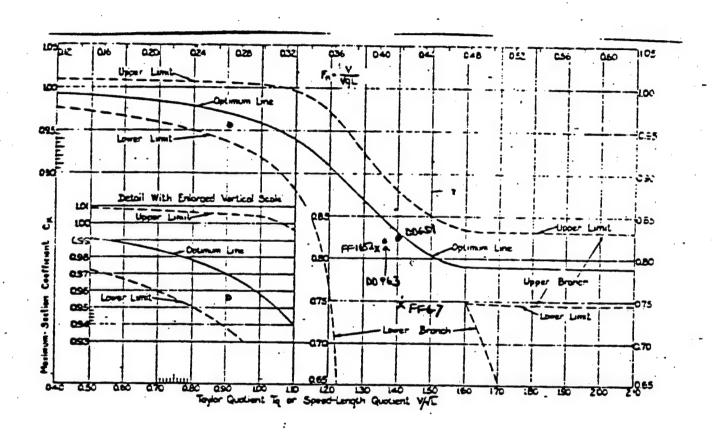


52.1

Rof. Soundary, Hydrodynamich in Ship Design. Swalle 1957 Vol II A 466

Fig 4

DESIGN LANES FOR MAXIMUM SELTION COEFFICIENT, Cx



Ref. Sounders Will II p 469

Table 1

### VARIATION OF PARAMETERS FOR POST WWII U.S. NAVAL FRIGATE/ DESTROYER/CRUISER DESIGNS

			•	
PARAMETER	RANGE	FFG7	DD963*	DDG51
(5)	6.975-8.95	7.36	7.86	7.19
L/B	7.92-9.92	9.1	9.6	7.5
B/T	2.87-3.21	3.1	3.1	3.1
c <sub>p</sub>	.56636	.593	.547	.604
c <sub>*</sub>	.747835	.747	.823	.825
<b>£</b>	43.4-65.6	49	46	81
L/D	10.75-17.81	13.6	12.6	11.1
GM/B	.07471227	•		
V/VI	1.24-1.978	1,41	1.37	1.40
C <sub>WP</sub>	.656795	.727	.727	.780
Wp/A	.08991329	.08	.082	.11
A/VOL #/Pt <sup>3</sup>	15.1-28.84		•	-

<sup>\*</sup>Data represents hull forms with a "no-dome" bow.

TABLE 2

Selected Characteristics of Existing Frigates and Frigate Designs

							• •
Country	Ships	LWL (ft)	Ľ/B	B/T	Cp	Cx	Δ/(0.01L) <sup>3</sup>
USA	DE 1006	308	8.4	3.0	0.60	0.80	65
•	DE 1037	350	8.7	3.0	-		62
	DE 1040	390	8.9		0.61		58 -
•	DE 1052	415	8.9				53
	FFG-7	408		_	0.59		49
••	USCG Hamilton	350	8.3	3.1	0.58	0.83	. 63
U.K.	Leander	360	8.8	3.0		-	63
	Type 21	360	8.6	3.3	-	-	59
	Type 22	410	8.5		0.59		55
	Type 42	392	8.5	3.7	0.62	0.90	59
Canada	DDH 261	.356	8.5	3.0	_	_	63
	DDH 280	398		3.2	_	_	73
France	C-67A	468	9.4	3.4	0.63	0.81	48
	C-70	423			0.63		49
	C-74		•				
Netherlands	G.M. Frigate	430	8.9	3.2	_	-	53
	Std. Frigate	400	8.6		0.59	0.78	55
Germany	Type 101	421	9.6	2.8	_		62
	Type 120	_	9.6		_	_	66
	Type 122	400	8.6	3.3	0.59	0.78	55
Norway	Oslo	308	8.5	3.2	_	-	60
Italy	Audace	432	9.1	3.1	_	-	. 55
-,	Lupo	348			0.63	0.79	49
	Maestrale	373			0.62	U.78	57
USSR	Krivak	384	8.8	2.8	0.62	0.80	62
	Kashin	440		3.2	0.62	0.86	58
					-		

<sup>\*</sup>In some cases, values given are approximate; the data sources are, at times, confusing.

TABLE 3

Comparison of FFG 7 Secondary Hull Form Characteristics and
Those Recommended for Small (3000-ton) Frigates

Parameter	FFG 7	Recommended for Minimum Resistance
Forward Section Shape	"uv"	Mild "V", or "UV"
A/A <sub>X</sub> Curve Entrance	Very slightly "hollow"	Slightly "hollow"
te Taylor entrance param	utur -	≈ 0.90
Section Coefficient at Station 1.0	≈ 0.64	₹ 0.60
A <sub>20</sub> /A <sub>x</sub>	0.028	0.01 to 0.03
ie Entrang holf-angle	8.0°	6.7° to 8.7°
CHPP Foreboly welevilane co	<b>4.</b> 0.610	< 0.62
FF/LWL	0.556	<b>5</b> 0.57
B20 / BX	0.513	0.50 to 0.70 ·
CVPF Forebody prismatic a	eg. 0.720	<b>5</b> 0.70
CVPA Actubaly would prise	مار 0.650	<b>5</b> 0.58
Aft buttock shape	Almost straight	Little or no "hook"
CPA/CWPA	0.706	<b>5</b> 0.72

Taken from:

PF6-7 Review of Hydrodynamic Design and Performance NAUSEA Report -3213-81-20 Sept 1981

Primary Characteristics of Selected Destroyer-Type Hull Porms (Ordered by Lpp) TABLE

Hull Porm	lipp (ft)	<sup>l</sup> rp Βχ (ft) (ft)	TX (ft)	* ո	చ	Diepl Bil*	Ler/ Dx	$^{B}_{\rm X}/^{\rm T}_{\rm X}$	Lpp/ Tx	LPP / D10	Disp1/* (L/100)3	م حم
HCH (CD)	202.0	38.50	9.50	0.597	0.817	1,030	5.2	4.1	21.3	8.4	125	0.768
исн (q.1)	240.0	43.88	11.83	0.575	0.842	1,724	5.5	3.7	20.3	8.3	125	0.756
WHEC	255.0	37.90	13.00	0.508	992.0	1,615	6.7	2.9	19.6	10.9	97	0.768
) 95C 3G	300.0	35.5	10.00	0.620	0.811	1,530	8.5	3.6	30.0	15.0	57	
nc 1006	308.0	36.50	12.10	0.604	0.803	1,890	8.4	3.0	25.5	15.0	. 29	0.754
DE 1037	350.0	40.32	13.50	0.580	0.801	2,530	8.7	3.0	25.9	11.8	29	0.721
DE, SCB 199	350.0	39.60	13.00	0.573	0.778	2,297	8.8	3.0	26.9	11.7	54	0.710
DD 692	369.0	40.59	13.00	0.616	0.827	2,833	9.1	3.1	28.4	16.0	26	0.745
Huestrale	374.0	41.01	12.80	0.620	0.780	2,712	9.1	3.2	29.2	13.7	. 52	0.764
PY 61-DE	375.0	40.40	13.80	0.584	0.781	2,731	9.3	2.9	27.2	12.5	52	0.710
012 00	383.0	40.59	13.00	0.634	0.815	2,982	9.4	3.1	29.5	16.7	23	0.75%
Krivak	303.6	43.31	14.76	0.610	0.020	3,506	8.9	5.9	26.0	11.7	2 29	0.776
PP 1040	390.0	43.70	14.50	0.580	0.794	3,245	υ.	υ. :	26.9	13.0	55	0.728
Type 42	392.1	45.93	12.14	0.620	0.900	3,486	8.5	3.8	32.3	13.5	85	0.760
Work Study DE	395.0	44.50	14.20	0.562	0.823	3,290	8.9	3.1	27.8	1		1.77.0
SW Frigate	399.6	47.25	13.65	0.612	0.744	3,353	8.5	3.5	29.3	13.4		0.720

\* For ships/devigns which had a bow-mountal sonar dome, this data represents such hull forms with a "no-dome" bow.

TABLE 4 (Continued)

Wull Form	(11) (12)	(ft) (ft) (ft)	τχ (ει)	<b>¢</b> ժ၁	×	Dispi <sub>nt</sub> *	Lpp/ BX	$_{\rm X}/_{\rm X}$	TX	1,pp/ D10	Diep1/2 (1/100) <sup>3</sup>	d d
166 00	407.0	44.38	14.50	0.630	0.828	3,901	9.2	3.1	28.1	16.1	58	0.768
FEG 7	0.80%	45.00	14.30	0.593	0.747	3,336	9.1	3.1	28.5	13.6	64	0.727
PPC	410.1	48.23	14.21	0.610	0.800	3,918	8.5	3.4	28.9	13.3	57	0.770
FF 1052	415.0	46.50	15.00	0.569	0.812	3,020	8.9	3.1	1.72	14.4	54	0.734
DDG 2	420.0	47.00	15.00	0.634	0.835	4,477	6.9	.3.3	28.0	16.8	09	0.760
C70	423.3	45.93	13.45	0.620	0.793	3,673	9.2	3.4	31.5	14.1	9,5	0.753
DUGX	433.1	54.06	17.05	0.601	0.847	5,807	8.0	3.2	25.4	13.1	72	0.784
000 51 (6.1)	465.9	62.00	20.00	0.604	0.825	8,229	7.5	3.1	23.3	11.1	18	0.780
DL 2	476.0	48.00	14.04	119.0	0.801	4,480	9.9	3.4	33.9	16.9	42	0.746
9 270	490.0	50.13	15.75	0.562	0.768	4,775	7.6	3.2	31.1	16.2	41	0.712
FTFE	490.0	49.90	15.80	0.560	0.771	4,770	9.8	3.2	31.0	16.3	41	0.710
91 92	510.0	53.00	16.50	0.585	0.810	6,041	9.6	3.2	30.9	13.2	94	0.720
1 10	520.0	53.77	17.62	0.566	0.808	6,435	7.6	3.1	29.5	15.1	94	0.703
CG 26	524.6	54.40	18.80	0.604	0.818	7,561	9.6	2.9	27.9	13.6	53	0.740
DOG FY 67	525.0	61.00	18.25	0.560	0.831	7,780	. 9.8	3.3	28.8	11.5	. 24	0.710
DD 963	529.0	55.00	18.00	0.547	0.823	6,731	9.6	3.1	29.4	12.6	94	0.727
DI.C(H) 25	540.0	98.99	18.50	0.584	0.794	7,527	9.5	3.1	29.3	13.3	/tů	0.744
					•	•						

<sup>\*</sup> For ships/designs which had a bow-mounted sonar dome, this data represents such bull forms with a "no-dome" bow.

TABLE 4 (Concluded)

	(ft)	(ft)	(ft)	<b>4</b> ສັ	ಕ	Dispibul	1.1. 13.X	$_{\rm X}/_{\rm X}$	T <sub>X</sub>	LFF/ D10	01ap1/4 (L/100) <sup>3</sup>	8
CGN 35	540.0	57.03	20.30	0.614	0.818	8,999	9.5	2.8	26.6	13.3	15	0 37. 0
GGN 38	560.0	61.85	20.50	0.623	0.808	10,210	9.1	3.0	27.3	13.2		767
CGN 42	560.0	62.50	22.00	0.629	0.845	11,695	0.6	2.8	25.5	13.2	? 29	0 776
9E NOO	570.0	60.00	20.50	0.603	0.810	9,783	9.5	2.9	27.8	13.9		0 7 60
DLGN (TYPION)	0.009	62.80	20.50	0.568	0.845	10,595	9.6	3.1	29.3		67	0.77
CSGN (Conv.)	0.999	76.70	76.70 22.15	0.582	0.897	16,885	8.7	3,5	30.1	15.7	÷ 5	25.00
CSCN (VSTOL)**	0.999	80.77	26.60	0.578	0.901	21,308	8.2	3.0	25.0	,	3 2	967.0
6 NOO	8.169	71.00	21.50	0.578	0.807	14,080	9.1	3.3	32.2	15.4		261.0
CA 139	700.0	74.80	24.00	919.0	0.868	0.868 19,200	9.4	3.1	29.2	17.6	. ys	01/10

# Note

(e.g., in some cases the characteristics apply to the hall form up to a waterline at which the hall was model The buil form characteristics listed in this table are, in some cases, based on the bull form up to the DWL and, in other cases, based on the hull form up to a particular waterline near to, but other than, the DWL tested) or up to a waterilue representing the ship draft in the full-load condition. \* For ships/designs which had a bow-mounted sonar dome, this data represents such hull forms with a "no-dome"

\*\* Hull form was based on that of the Large-Vaterplane version of the CSCN design.

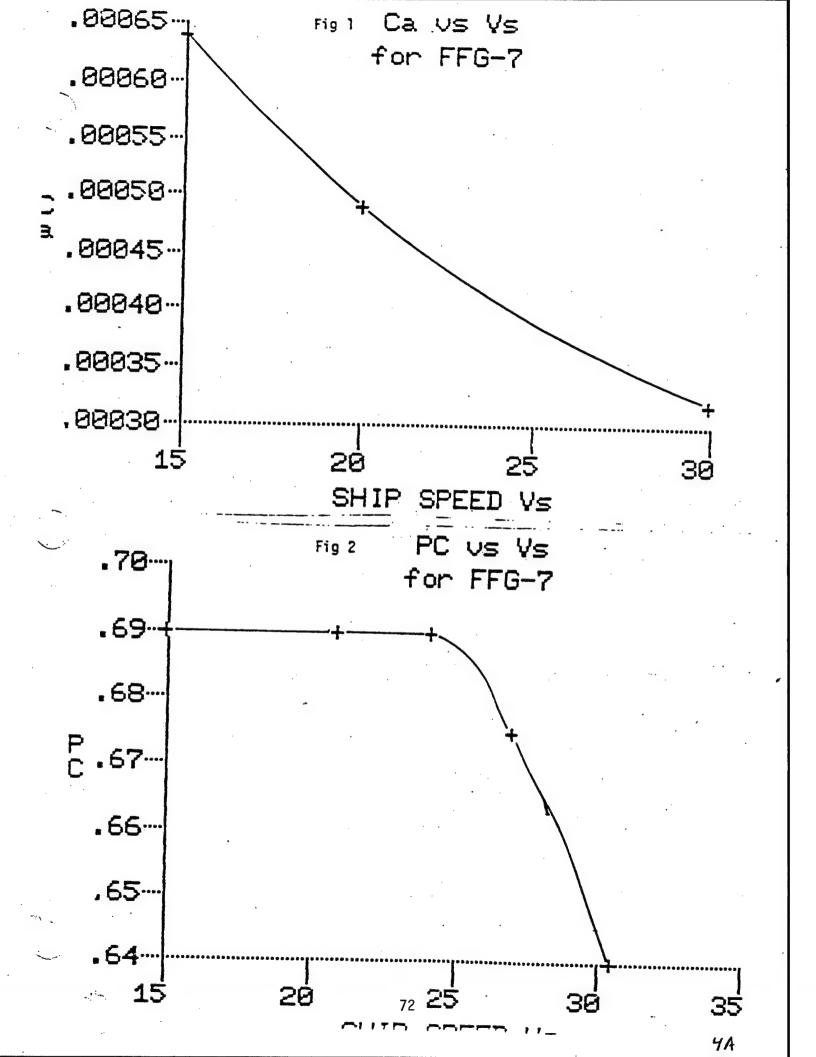
### NAVIGATIONAL RESTRICTIONS

A.	Ports	Draft (ft)	Length (ft)	Par
	Baltimore, Maryland	23-40	600-810	Bei
	Baton Rouge, Louisiana	40	no limit	
	Beaumont, Texas	34	600-760	
	Boston, Massachusetts	30-38	575-1200	
	Brownsville, Texas	34.5	no limit	
	Charleston, S. Carolina	30-35	600-705	
	Chicago, Illinois	27	000-705	
	Eureka, California	10-31	200-500	
	Freeport, Texas	36	670	
	Gulfport, Mississippi	30-32	700	
	Hampton-Roads, Virginia	15-38	700	
	Houston, Texas	30-40	600	
	Jacksonville, Florida	31-36	600	
	Long Beach, California	54	1200	
	Los Angeles, California	35-51	226-1895	_
	New York, New York	20-40	170-1280	
	Providence, Rhode Island	34	600	
	San Prancisco, California	25	300	•
ъ	·			
<b>D</b> •	<u>Canals</u> Panama	38.5	835	104
c.	Drydocks ·			
	Long Beach Naval Shipyard	•	1092	144
	Norfolk Naval Shipyard		1092	143
	National Steel & Shipbuilding Corp., San Diego, CA		965 -	170
	Newport News Shipbuilding and Drydock Corp., Newport News,			
	Virginia		1600	230

#### III.ENERGY (Use enclosures 4 and 5 to calculate energy needs)

Useful Output: P<sub>s</sub>, P<sub>e</sub>, P<sub>I</sub>, kW<sub>24avg</sub>, kW<sub>I</sub>, W<sub>F</sub>

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#### IV. SPACE

Input: L,B,T,C<sub>P</sub>,C<sub>x</sub>,L<sub>MB</sub>,H<sub>MB</sub>,Liquid Densities,W<sub>F</sub>,W<sub>LO</sub>,W<sub>HF</sub>,N<sub>T</sub>  $A_{HPA},A_{HPC},A_{DPA},A_{DPC},EP_{DRY},EP_{CHL},EP_{FRZ},EP_{GSM},f_{MB}$ 

#### A. Available

L, B, T, C<sub>P</sub>, C<sub>x</sub> Underwater Hull Volume IVA1.  $\nabla_{\mathbf{HV}}$ IVA2.  $H_{MB}$ Depth Functions Sheer Line  $(D_0, D_{10}, D_{20})$ IVA3.  $F_0, F_{10}, F_{20}$  $D_{av} \\$ CN Above Water Volume  $\nabla_{\mathrm{HAW}}$ Total Hull Volume  $abla_{
m HT}$ IVA4. Deck House Criteria Deck House Volume Available

 $\begin{array}{c} \nabla_{\rm D} \\ \text{Total Ship Volume Available} \\ \nabla_{\rm T} \end{array}$ 

#### B. Required

L, B, T, C<sub>P</sub>, D<sub>MB</sub>, A<sub>MB</sub>, L<sub>MB</sub>(pick), H<sub>MB</sub>, f<sub>MB</sub>

IVB1.

 $C_{PMB} = f(C_P, L_{MB}/L)$ 

 $\nabla_{_{\mathbf{MB}}}$ 

IVB2.

Liquid Weights
Liquid Densities

 $\nabla_{\mathsf{TK}}$ 

IVB3.

Payload Areas

A<sub>HPR</sub>, A<sub>DPR</sub>

IVB4.

IN<sub>T</sub>, L

 $A_{HL}$ ,  $A_{DL}$ 

IVB5.

**Endurance Periods** 

A<sub>HS</sub>

IVB6.

 $A_{DPR}$ ,  $A_{DL}$ , B, CN

IVB7.

A<sub>HSF</sub>, A<sub>DSF</sub>
Total Required Deck House Arrangement Area

 $A_{DR}$ Total Required Hull Arrangement Area  $A_{HR}$ 

#### C. Balance

IVC1.

$$\nabla_{\rm TK}$$
 ,  $\nabla_{\rm MB}$  ,  $\nabla_{\rm HT}$ 

Hull Arrangement Volume Available

 $abla_{\mathtt{HA}}$ 

IVC2.

Hull and Deck House Arrangement Area Available

 $\mathbf{H}_{\mathtt{T}}$  ,  $\!\nabla_{\mathtt{HA}}$  ,  $\nabla_{\mathtt{D}}$ 

A<sub>HA</sub>, A<sub>DA</sub>

· IVC3.

Compare  $A_{HR}$  and  $A_{HA}$ Compare  $A_{DR}$  and  $A_{DA}$ 

Useful Output: Machinery box dimensions, deck areas for functions in deck house and hull, tankage volumes and total ship volumes

#### IV. SPACE ESTIMATING RELATIONSHIPS

A. Available

IVA1. 
$$\nabla_{HV} = L \cdot B \cdot T \cdot C_P \cdot C_X$$

IVA2.

$$F_{10R} \ge 0.21 \text{ B}$$
 $D_{10R} = F_{10R} + T$ 
 $D_{10MB} \ge H_{MB}$ 
 $D_{10BC} \ge L/15$ 

Select  $D_{10}$  as largest of  $D_{10R}$ ,  $D_{10MB}$ ,  $D_{10BC}$ 

$$D_0 \ge 1.011827 \cdot T - 6.36215 \times 10^{-6} \cdot L^2 + 2.780649 \times 10^{-2} \cdot L + T$$
  
 $D_{20} \ge .01 \cdot L \cdot (2.125 + 1.25 \times 10^{-3} \cdot L) + T$ 

Draw faired line through  $D_0$ ,  $D_{10}$  and  $D_{20}$  and submit with report

$$\begin{split} F_0 &= D_0 - T; \ F_{10} = D_{10} - T; \ F_{20} = D_{20} - T \\ A_{PRO} &= L \bullet (F_0 + 4 \bullet F_{10} + F_{20}) \ / \ 6 \\ F_{AV} &= A_{PRO} \ / \ L \\ D_{AV} &= F_{AV} + T \\ CN &= L \bullet B \bullet D_{AV} \times 10^{-5} \\ C_w &= 0.236 + 0.836 \bullet C_P \\ f_f &= 0.714599 + 0.18098 \bullet D_{AV} / T - 0.018828 \bullet (D_{AV} / T)^2 \\ If \ f_f &< 1.0 \ then \ use \ f_f = 1.0 \\ \nabla_{HAW} &= L \bullet B \bullet F_{AV} \bullet C_W \bullet f_f \end{split}$$

$$\nabla_{\rm HT} = \nabla_{\rm HV} + \nabla_{\rm HAW}$$

Deck house sizing : 
$$0.001 L^3 < D_{10} < 0.0015 L^3$$

$$\nabla_{\rm T}\,=\,\nabla_{\rm HT}\,+\,\nabla_{\rm D}$$

#### B. Required

Math Model

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#### C. Balance

IVC2. 
$$A_{HA} = \nabla_{HA} / H_{T}$$
  
 $A_{DA} = \nabla_{D} / H_{T}$ 

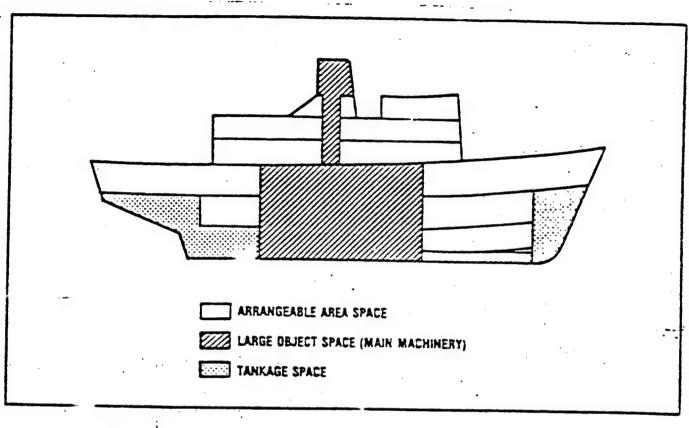
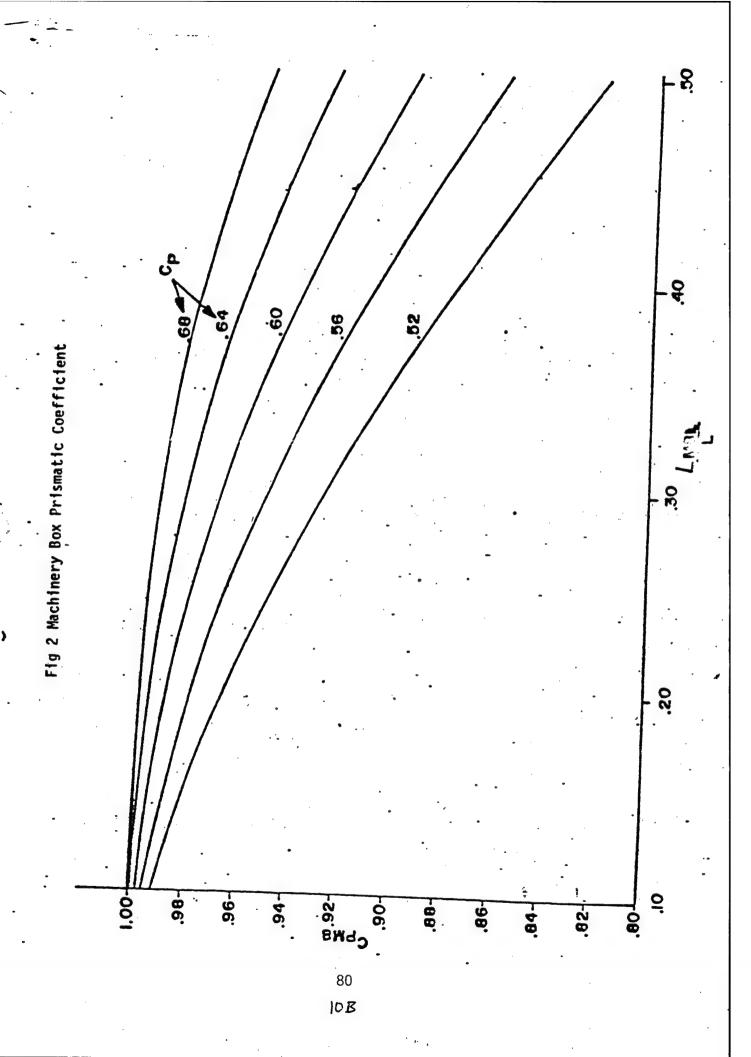


Figure 1 Relationship Among the Three Types of Space



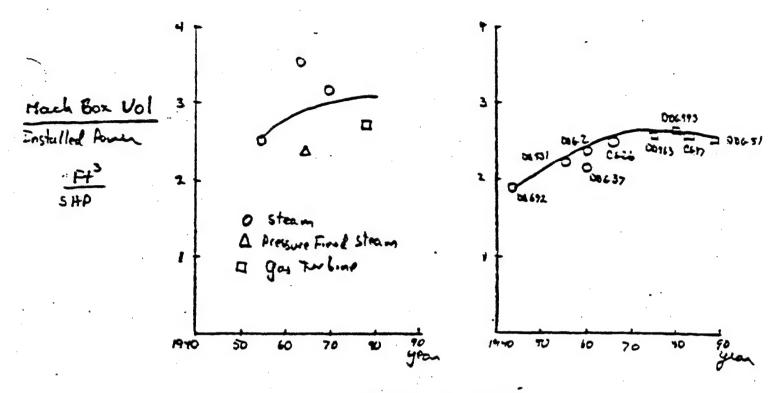
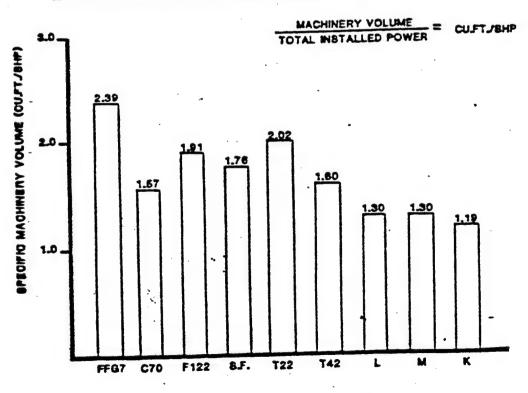
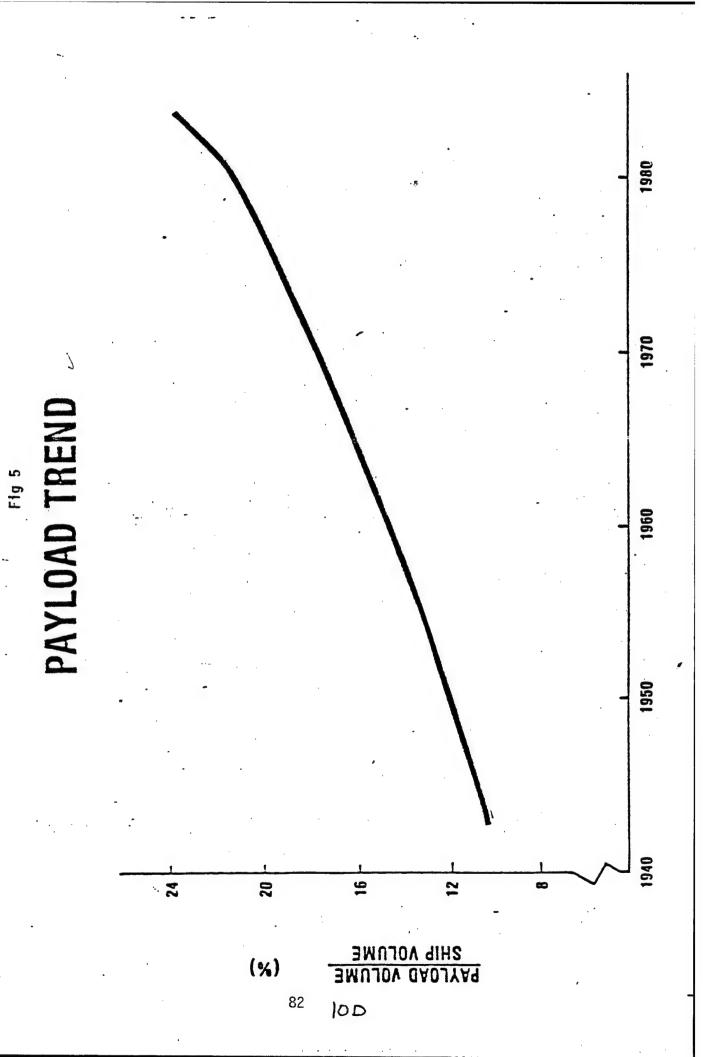


Fig 3 Machinery Box Volume

### Fig 4 FRIGATES - SPECIFIC MACHINERY VOLUME





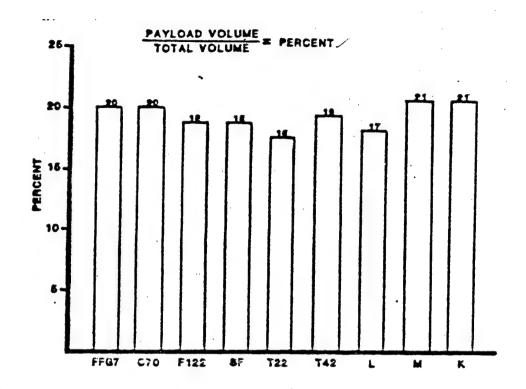
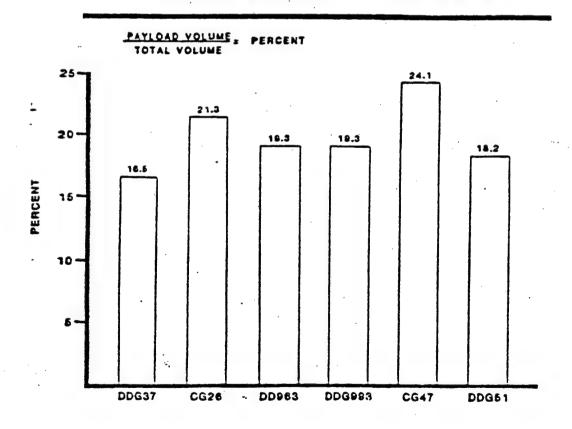
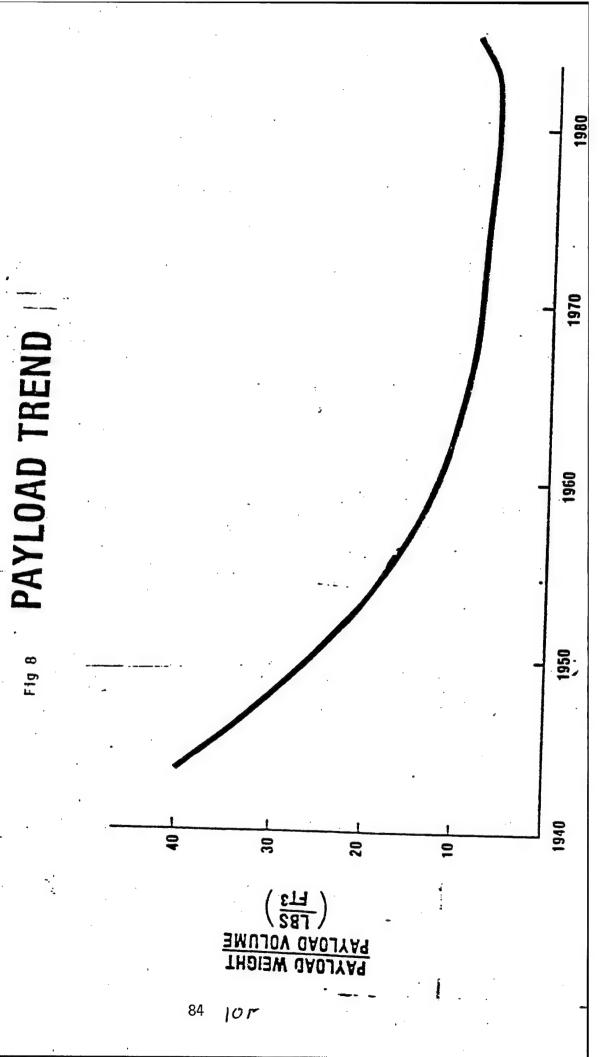


Fig 7PAYLOAD VOLUME - U.S. SHIPS





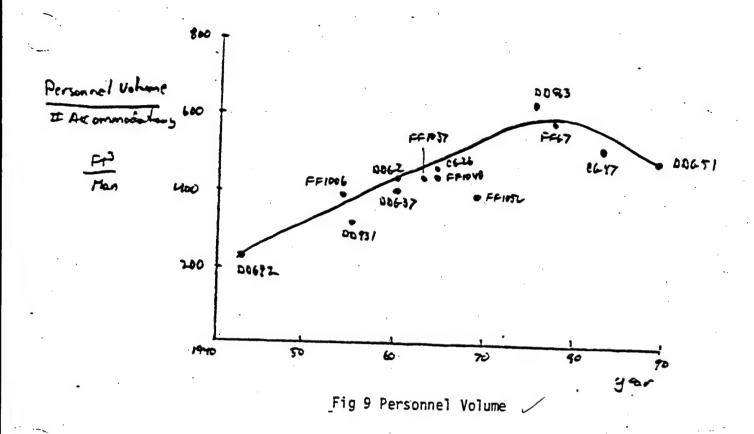
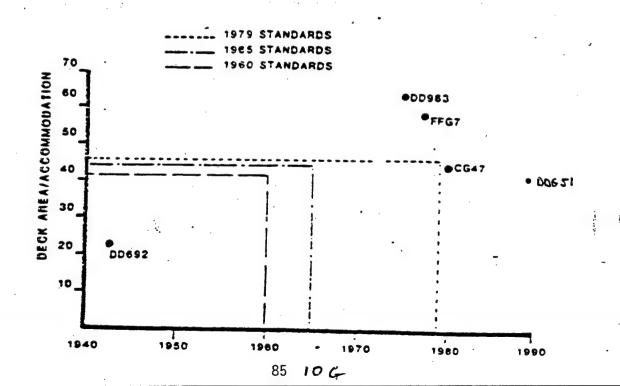


Fig 10 HABITABILITY DECK AREA - U.S. SHIPS



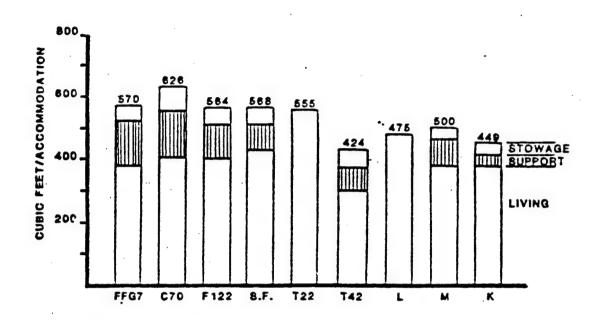
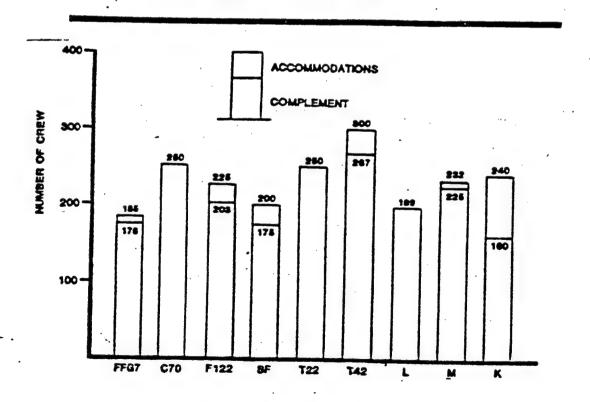
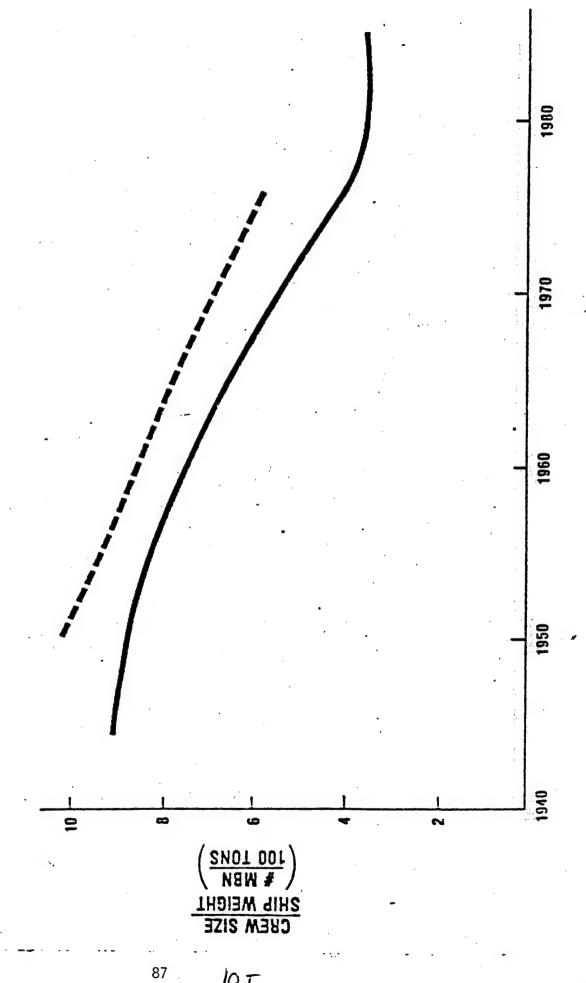
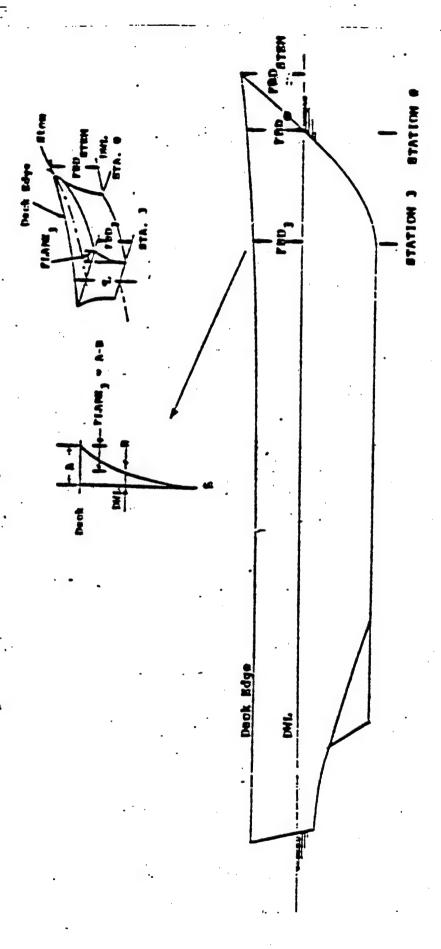


Fig 12 FRIGATES - CREW SIZE







ig 14 Presboard and Plare Definitions

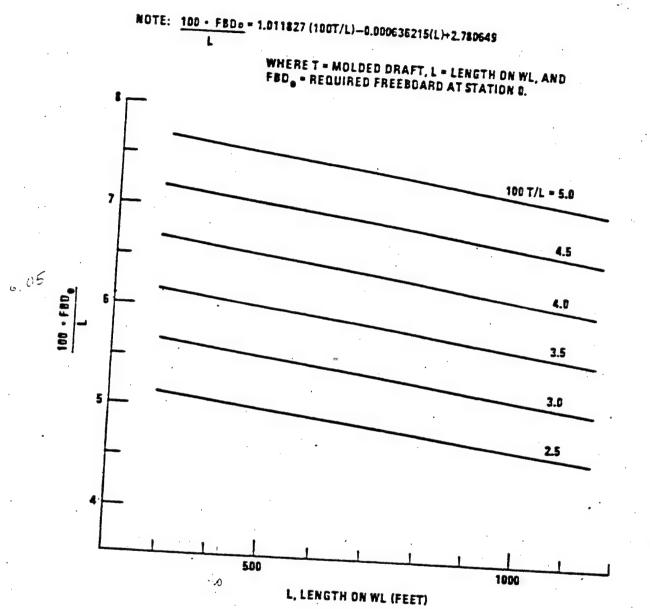
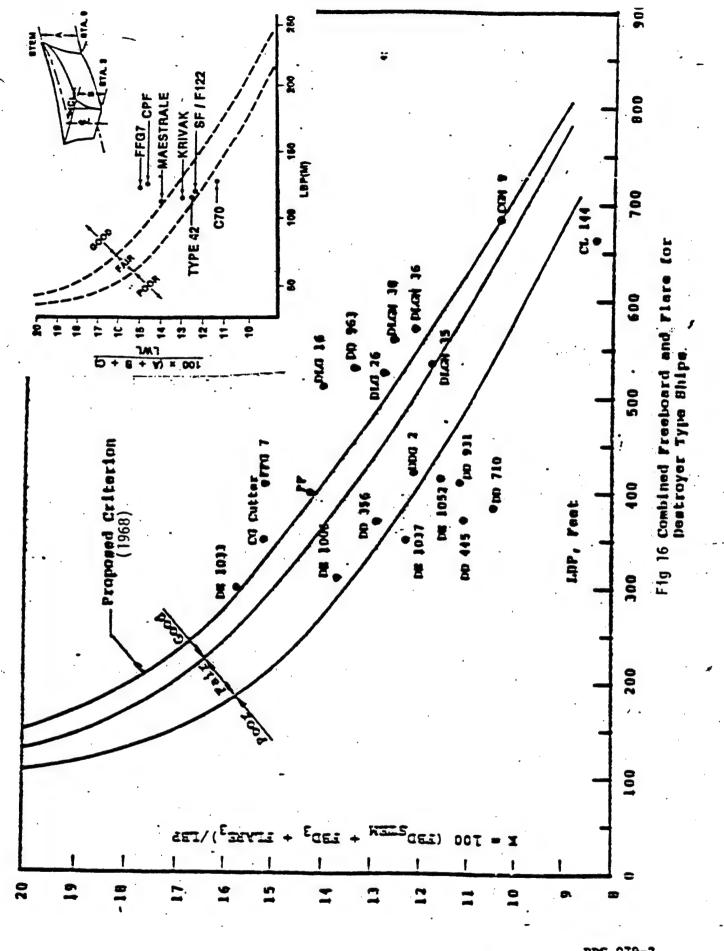
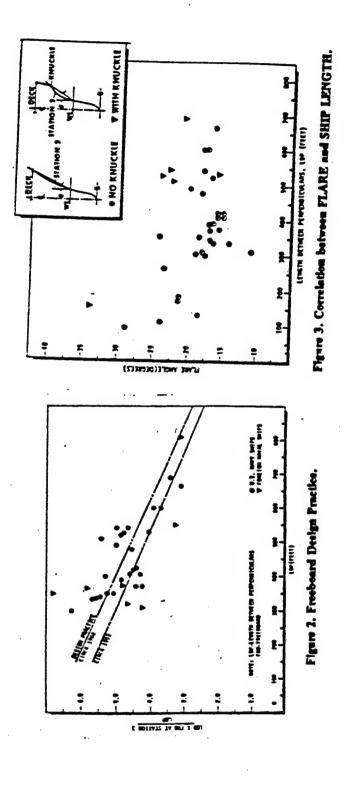


Fig 15 A Criterion for Bow Freeboard for Cruiser/Destroyer Ships



SOURCE, DOS 079-2

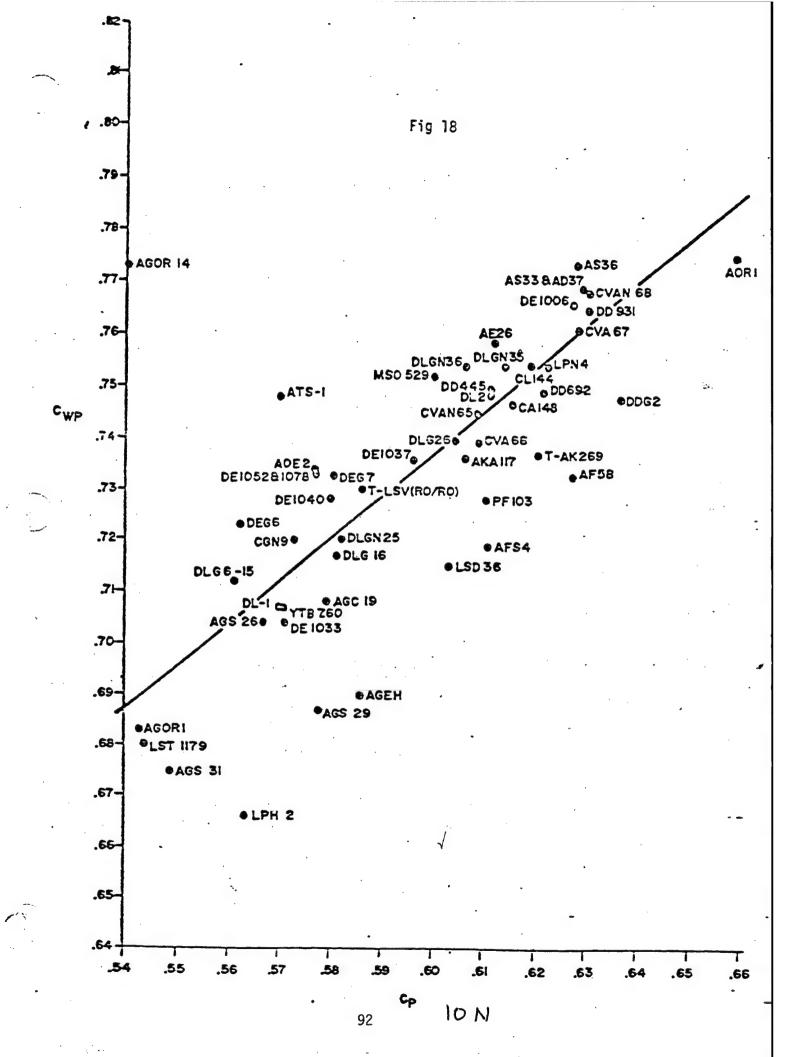


COMSTOCK/KEANE Ffg 17 SEAKEEPING BY DESIGN

SOURCE:

IOM

91



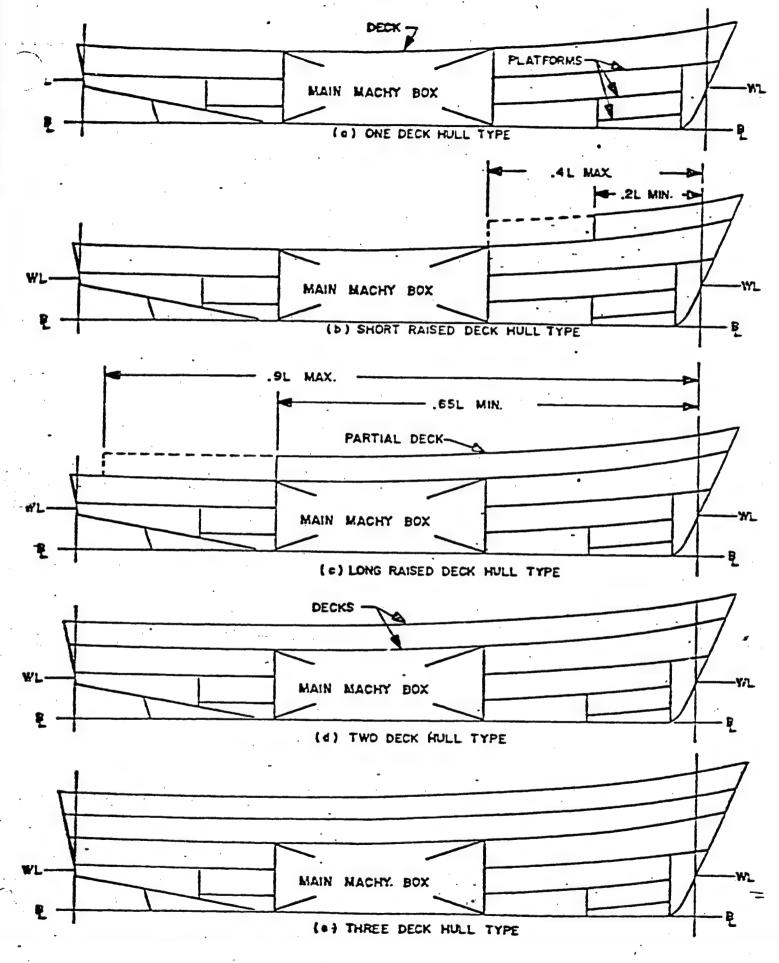


Fig 19 10 0

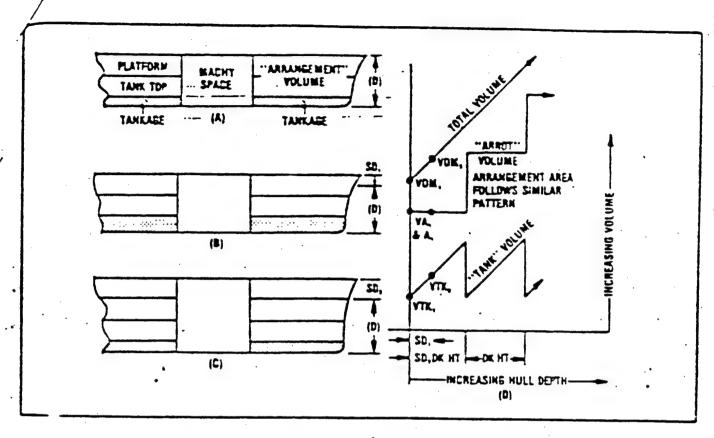


Figure 20 Idealized Area/Depth Relationship

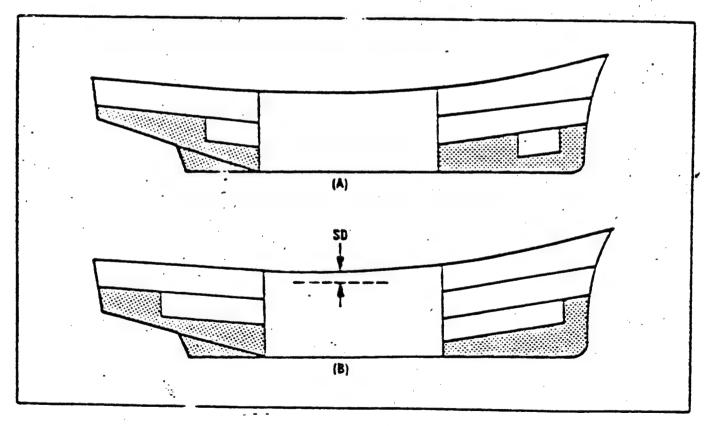


Figure 21 Typical Destroyer Profiles

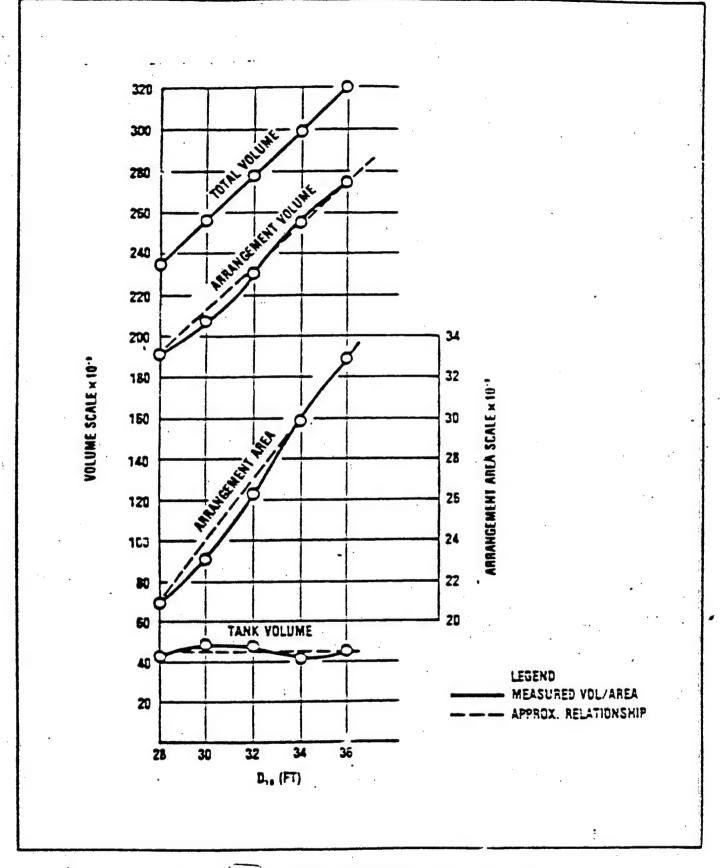


Figure 22 Area/Volume/Depth Relationships

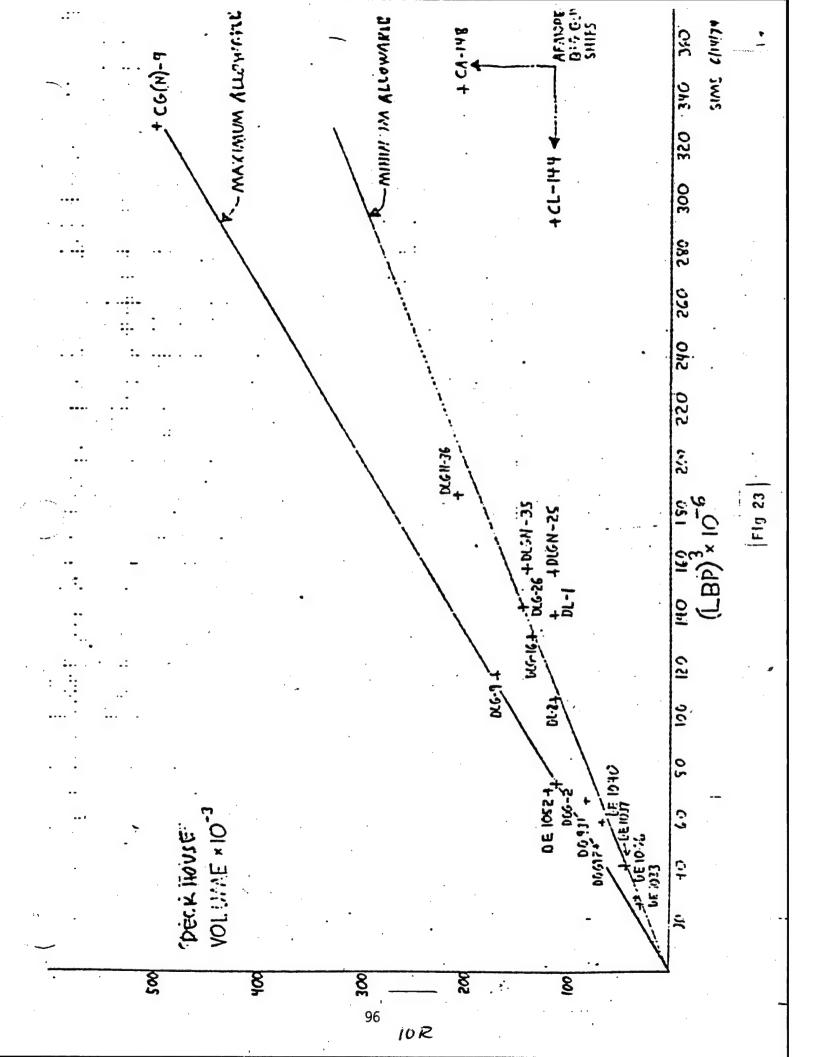
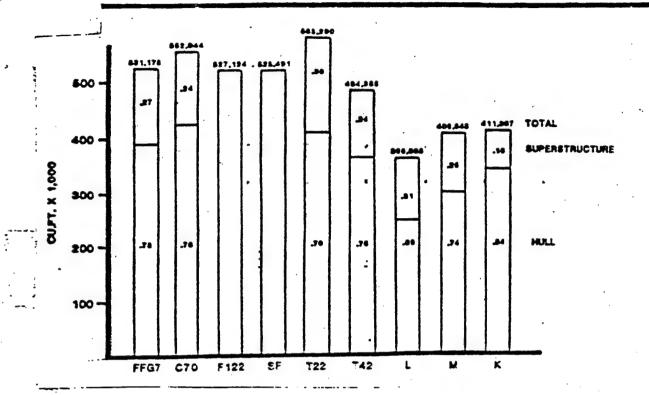
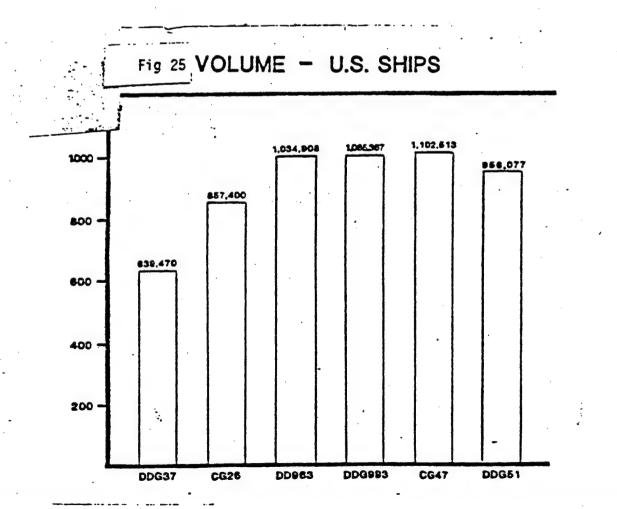


Fig 24 FRIGATES - VOLUME





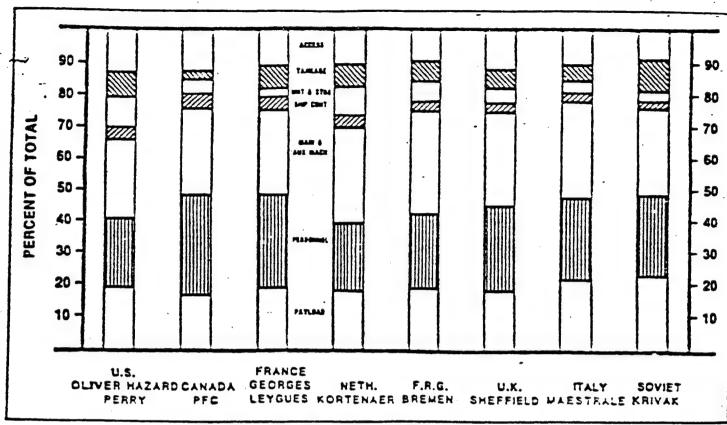
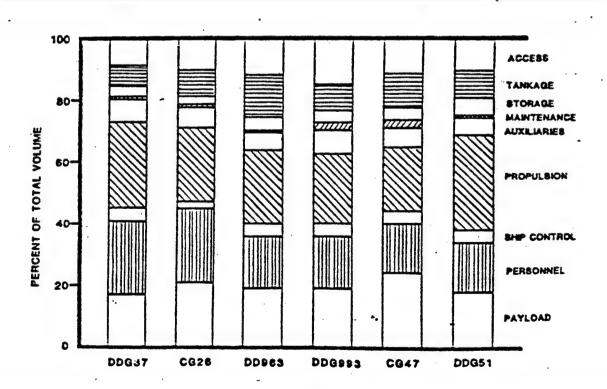


Fig 26

Volume Distributions.

Fig 27 VOLUME DISTRIBUTION - U.S. SHIPS



## Micro Flow Diagrams (Continued)

#### V. WEIGHT

```
\textbf{Input}: \ L,B,T,P_{I},N_{S},\nabla_{D},kW_{B},\nabla_{T},W_{P},N_{T},EP,CN,W_{MT},W_{SD}
                                                P_{I}, L ,D_{P} ,N_{S}
V1.
                                               W_{BM} = f(P_1)
W_{ST} = f(L, D_P, N_S)
                                          Propulsion Machinery Weight
V2.
                                                           kW_B
                                              Electrical Plant Weight
                                                           W_3
V3.
                                                        W<sub>PC</sub>, CN
                                        Communications/Control Weight
                                                           W_4
V4. and V5.
                                                     \nabla_{T}, N_{T}, B, D_{10}
                                            Auxiliary Systems Weight
                                          Outfit and Furnishing Weight
                                                          W_6
V6.
                                                           W_{\text{PA}}
                                                 Armament Weight
                                                          W_7
V7.
                                                   CN, \nabla_D, W_{MT}, W_{SD}
                                                  W_{\mathtt{BH}}, \, W_{\mathtt{DH}}, \, W_{\mathtt{FD}}
                                              Hull Structure Weight
                                                          W_{1}
                                                Light Ship Weight
                                                          W_L
V8.
                                                   Margin Policy
```

# Micro Flow Diagrams (Continued)

Margin Weight

W<sub>g</sub>

↓

V9.

N<sub>o</sub>, N<sub>e</sub>, EP

W<sub>C</sub>, W<sub>PRV</sub>, W<sub>GSM</sub>, W<sub>w</sub>

W<sub>F</sub>, W<sub>Lo</sub>, W<sub>A</sub>

W<sub>H</sub>, W<sub>HF</sub>

↓

Weight of Loads

W<sub>LD</sub>

Total Ship Weight

W<sub>T</sub>

Useful Output: All Weight Groups, ∇

#### V. WEIGHT ESTIMATING RELATIONSHIPS

V1. 
$$W_{BM} = P_1 \bullet (12.6 + 12.4 \bullet [P_1 \bullet 10^{-5} - 1]^2)/2240$$
  
 $W_S = W_S \bullet L \bullet f_1$   
where  $W_S = 0.356$  tons/ft  
 $f_1 = 0.33$  for single screw ship  
 $W_B = 0.15 \bullet (W_S + W_{PR})$   
 $D_P = (0.6625 \bullet T + 0.0125 \bullet L) \bullet 1.2$   
 $W_{PR} = (0.05575 [D_P]^{(5.497 - 0.0433 DP)}) \bullet N_S /2240$   
 $W_{ST} = W_S + W_B + W_{PR}$   
 $W_2 = W_{BM} + W_{ST}$ 

V2. 
$$kW_I = n \cdot kW_{GEN}$$
 where the following relationship must hold  $0.9 \cdot (n-1) \cdot kW_{GEN} \ge 1.2 \cdot 1.2 \cdot kW_{max load}$   $kW_I \ge n \cdot kW_B / (n-1)$   $W_3' = 50 + 0.03214 \cdot kW_I$ 

V3. 
$$W_{PC} = Input$$
  
 $W_{CG} = 4.65 CN$   
 $W_{CO} = 2.24 CN$   
 $W_{CC} = 0.04 (W_{PC} + W_{CG} + W_{CO})$   
 $W_4 = W_{PC} + W_{CG} + W_{CO} + W_{CC} + W_{SW}$ 

V4. 
$$W_5 = 7.72 \times 10^{-8} \bullet \nabla_T^{1.443} + 5.14 \times 10^{-4} \bullet \nabla_T + 6.19 \times 10^{-4} \bullet \nabla_T^{.7224} + 0.0377 N_T + 2.74 \times 10^{-4} \bullet P_1 + 113.8 + W_{SS}$$

V5. 
$$W_{OFH} = 31.4 + 31.87 \times 10^{-5} \circ \nabla_{T}$$
  
 $W_{OFP} = 0.504 \circ (N_{T} - 95)$   
 $W_{6} = W_{OFH} + W_{OFP}$ 

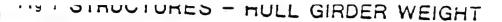
V6. 
$$W_7 = W_{PA}$$
; Input

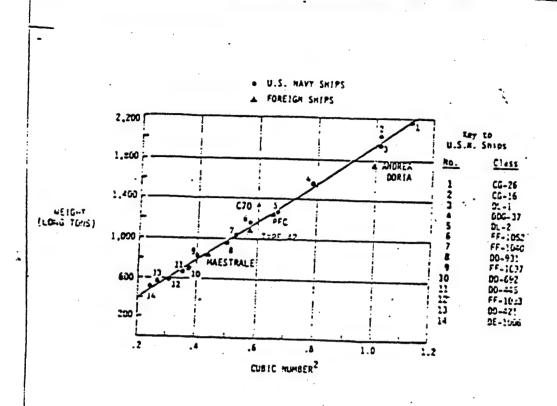
V7. 
$$W_{BH} = 1.68341 \cdot \text{CN}^2 + 167.1721 \cdot \text{CN} - 23.283$$
  
 $W_{DH} = f_m \cdot \nabla_D$   
where  $f_m = \text{deck house material factor which}$   
for steel is  $1.429 \times 10^{-3}$   
and for aluminum is  $8.57 \times 10^{-4}$   
 $W_{FD} = 0.0675 \cdot W_{BM} + 0.072 \cdot (W_3 + W_4 + W_5 + W_7)$ 

## Micro Flow Diagrams (Continued)

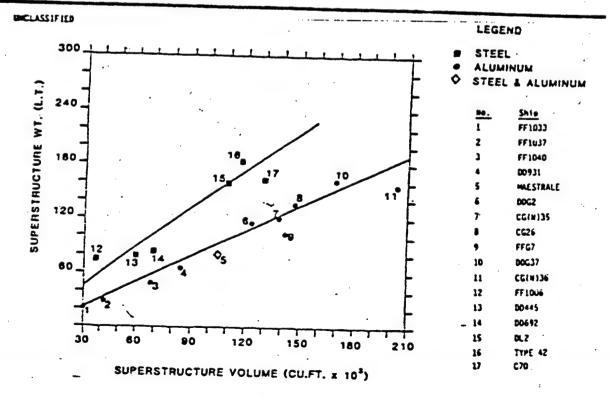
$$\begin{split} W_{MT} &= \text{Input} \\ W_{SD} &= \text{Input} \\ W_{1} &= W_{BH} + W_{DH} + W_{FD} + W_{MT} + W_{SD} \\ \end{split}$$

$$W_{L} &= \sum_{W_{G-1}}^{7} W_{WG} \\ V8. \quad W_{g} &= W_{\text{margin}} \bullet W_{L} \\ V9. \quad W_{C} &= (236 \bullet N_{E} + 400 \bullet [N_{O} + 1]) / 2240 \\ W_{PRV} &= N_{T} \bullet (2.8 \bullet \text{EP}_{DRY} + 2.2 \bullet \text{EP}_{CHL} + 1.3 \bullet \text{EP}_{FRZ} + 1.3 \bullet \text{EP}_{GSM} + 22.6) / 2240 \\ W_{GSM} &= 9.598 \times 10^{4} \bullet N_{T} \bullet \text{EP}_{GSM} \\ W_{W} &= 0.224 \bullet N_{T} \\ W_{A}, W_{H}, W_{HF}, W_{LO} \quad \text{all input values} \\ W_{LD} &= W_{C} + W_{PRV} + W_{GSM} + W_{W} + W_{A} + W_{H} + W_{HF} + W_{F} + W_{LO} \\ W_{T} &= W_{L} + W_{LD} + W_{g} \end{split}$$





### Fig 2 SUPERSTRUCTURE WEIGHT



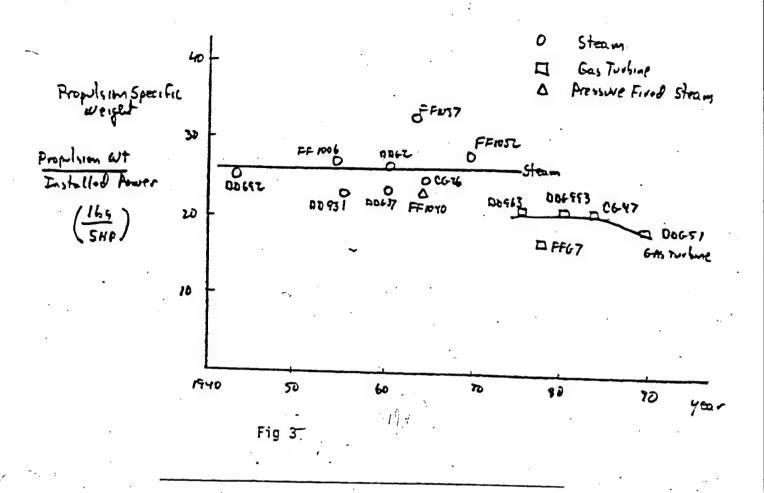
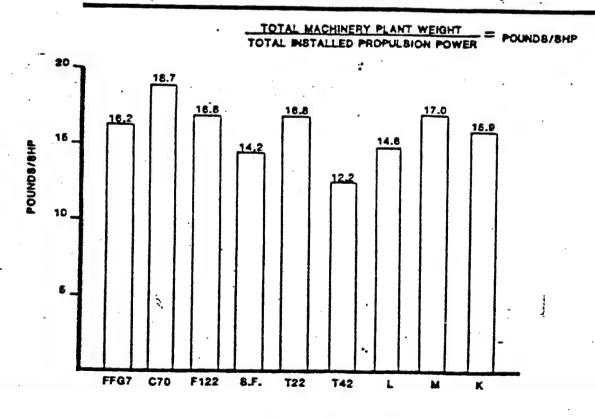


Fig 4 FRIGATES - PROPULSION WEIGHT



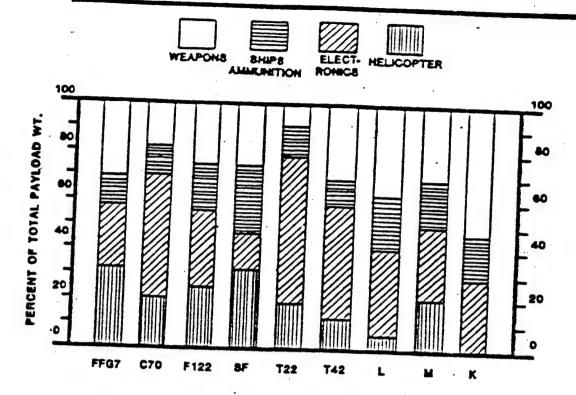
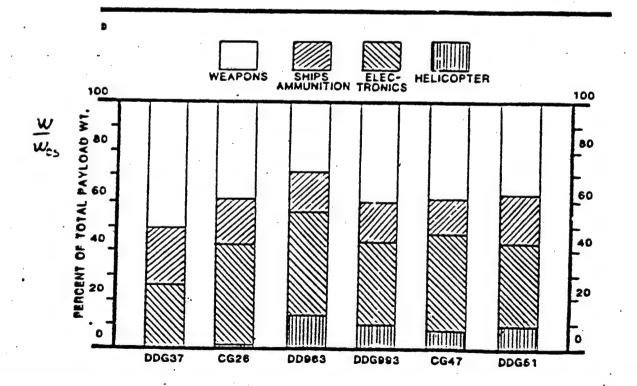


Fig 6 PAYLOAD WEIGHT DISTRIBUTION - U.S. SHIPS



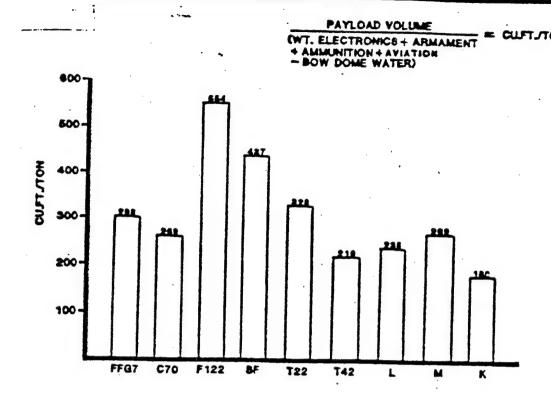


Fig 8 FRIGATES - DISPLACEMENT

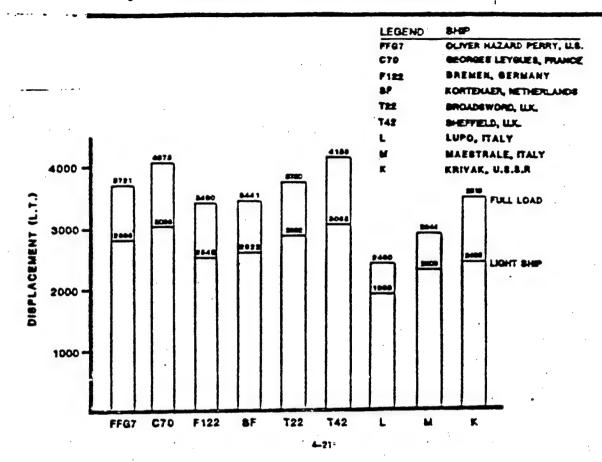
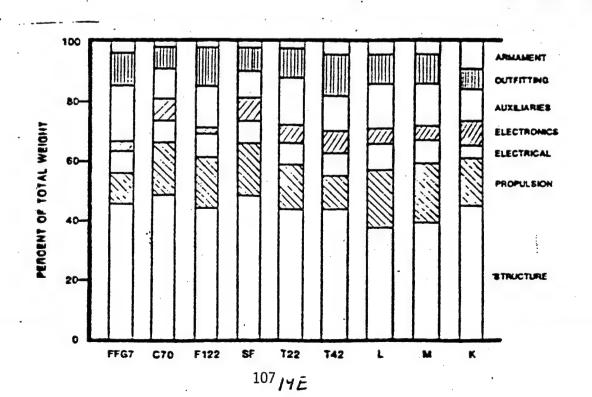


Fig 9 LIGHT SHIP WEIGHT DISTRIBUTION - FRIGATES



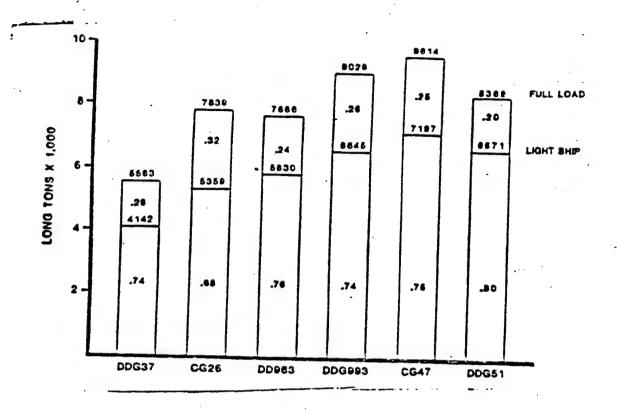
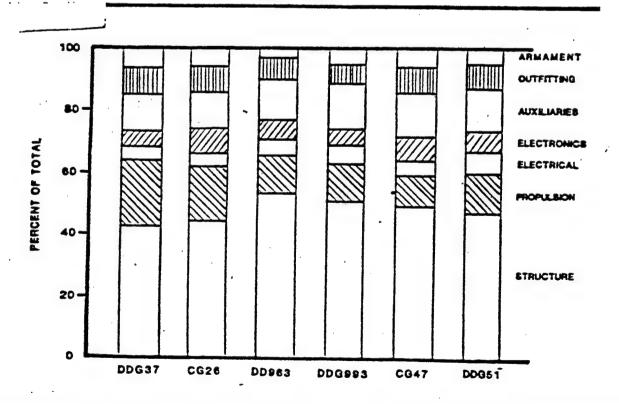


Fig 11 LIGHT SHIP WEIGHT DISTRIBUTION - U.S. SHIPS



## Micro Flow Diagrams (Continued)

KB BM GM

#### VI. STABILITY

Input :  $D_{AV}$ ,  $\nabla_T$ ,  $\nabla_D$ , L,  $D_{10}$ , T,  $H_{MB}$ , B, Weight Groups VI1. Inputs VCGs of Weight Groups VCGs of Loads VI2. Moment of Weight Groups Weight of Weight groups  $W_{\mathtt{margin}}$  $KG_{\text{margin}}$ 1  $W_{\mathbf{g}}$ KG<sub>Lnm</sub>  $KG_L$ VI3. Moment of Loads Weight of Loads  $C_P$ ,  $\nabla_T$ , B, L KG  $C_{\mathbf{w}}$ 

Useful Output: GM / B

### VI. STABILITY ESTIMATING RELATIONSHIPS

Input Calculations: (all VCGs in feet above baseline)

<u>SWBS</u>	WEIGHT VARIABLE	VCG FORMULA
1	$W_{\mathtt{BH}}$	$VCG_{BH} = 0.527 \cdot D_{AV}$
1	$W_{ extsf{DH}}$	$VCG_{DH} = D_{10} + 2.45 \bullet \nabla_{D} / (L \bullet B)$
1	$W_{ extsf{FD}}$	$VCG_{FD} = 0.68 \bullet D_{10}$
1	$W_{MT}$	$VCG_{MT} = 2.65 \bullet D_{10}$
1	$W_{SD}$	$VCG_{SD} = -2.5$
2	$\mathbf{W}_{\mathtt{BM}}$ .	$VCG_{BM} = 0.55 \bullet D_{10}$
2	$W_{st}$	$VCG_{ST} = 3.9 + 0.19 \bullet T$
3	$W_3$	$VCG_3 = 0.7 \bullet D_{10}$
4	$W_{sw}$	$VCG_{sw} = -2.5$
4	$\mathbf{W_{PC}}$	$VCG_{PC}$ = Input (Note: use $D_{AV}$ to bring to BL)
4	$W_{CG}$	$VCG_{CG} = D_{10}$
4	$W_{co}$	$VCG_{co} = 5.6 + 0.4625 \cdot D_{10}$
4	$W_{cc}$	$VCG_{CC} = 16$
5	W <sub>BA</sub>	$VCG_{BA} = 1.1 \cdot (D_{10} - 7.4)$
5	$W_{ss}$	$VCG_{SS} = 0.5 \bullet H_{MB}$
6	W <sub>OFH</sub>	$VCG_{OFH} = 0.805 \bullet D_{10}$
6 .	$W_{OFP}$	$VCG_{OFP} = 8 + 0.71 \cdot D_{10}$
7	W <sub>7</sub> .	$VCG_7$ = Input (Note: use $D_{AV}$ to bring to BL)
L	$W_c$	$VCG_{C} = 0.746 \bullet D_{10}$
L	$W_{PRV}$	$VCG_{PRV} = 10$

## Micro Flow Diagrams (Continued)

Final Check: GM/B must be within design range.

#### TAYLOR STANDARD SERIES MADE EASY

#### **PURPOSE**

GIVEN SHIP PARAMETERS, PREDICT EFFECTIVE HOUSEPOWER USING TAYLOR STANDARD SERIES

#### REFERENCE

DESIGN DATA SHEET 051-1 OF 15 MAY 1984

THIS DDS USES A REANALYSIS OF TAYLOR'S ORIGINAL DATA BY GERTLER, AND ADDS MANY FACETS OF ACTUALLY PERFORMING A POWERING CALCULATION.

#### **METHOD**

USE THE ATTACHED TABLE TO STEP THROUGH THE CALCULATIONS

			T
CODE	VARIABLE	FORMULA or EXPLANATION of VARIABLE VALUE	
1	L	Length on Waterline (LBP)	
2	$B_{\mathbf{X}}$	Beam at maximum section on design waterline	
3	$T_X$	Draft to design waterline at maximum section	
4	$\Delta_{ t FL}$	Total displacement at draft T <sub>x</sub>	
5	$\Delta_{ ext{APP}}$	Displacement of appendages	0
6	$\Delta_{\mathtt{BH}}$	Bare hull displacement (without appendages)	·
7	$C_{x}$	Maximum section coefficients	
8	$C_{P}$	Prismatic Coefficient	
9	$B_X/T_X$	Beam to Draft ratio	
10	$ abla_{ ext{BH}}$	Bare hull displacement volume {6}•{35}	
11	$C_{v}$	Bare hull volumetric coefficient $\{10\}/\{1\}^3$	
12 .	$D_{P}$	Propeller diameter, $(0.6625 \cdot \{3\} + 0.0125 \cdot \{I\}) \cdot 1.2$	
13	•	Number, type of Propellers	
14	$A_{v}$	Frontal area of the ship to predict wind resistance	
- 15	$T_{sw}$	Temperature of seawater 59 °F	
16	$ ho_{ m SW}$	Density of seawater at given temperature 1.9905 lbf•sec²/	
17	$ u_{\mathrm{SW}}$	Kinematic viscosity of seawater at given 1.2817x1 temperature ft²/sec	
18	C <sub>A</sub>	Correlation Allowance 0.0005	
19	CS(SHIP) C <sub>S(TSS)</sub>	Ratio of wetted surface coefficients 1.0	
20	C <sub>s (TSS)</sub>	Wetted surface coefficient of TSS, Use figure 1 with C <sub>P</sub> and B/T	
21	C <sub>s(ship)</sub>	Wetted Surface coefficent of ship (if known) unknown	

CODE	VARIABLE	FORMULA or EXPLANATION of VARIABLE	VALUE
22	CD <sub>(APP)</sub>	Drag coefficient of appendages. Use figure 2 or 3 with L	
23	C <sub>AA</sub>	Air drag coefficient	0.0
24	PMF	Power Margin factor - Depends on design stage, usually 10% in early stages	1.10
25	S <sub>(TSS)</sub>	Wetted Surface (SHIP), {20}•{10} <sup>0.5</sup> •{1} <sup>0.5</sup>	
26	S <sub>(SHIP)</sub>	Wetted Surface (SHIP) {25}•{19}	
a	V	Ship speed (knots), (endurance, threshold, and goal)	1. 2. 3.
b	V√L	Speed to length ratio, $\{a\} / \{I\}^{0.5}$	1. 2. 3.
c and 27	R <sub>N</sub>	Reynold's Number $1.689 \bullet \{I\} \bullet \{a\}/\{I7\}$	1. 2. 3.
d and 28	$C_{F}$	Frictional resistance Coefficient $0.075/\{[\log_{10}(\{27\}) - 2]^2\}$	1. 2. 3.
e and 29	$R_{ m F}$	Frictional Resistance, $1.4264 \cdot \{16\} \cdot \{26\} \cdot \{a\}^2 \cdot [\{18\} + \{28\}]$	1. 2. 3.
f	C <sub>R 2.25</sub>	Use Taylor Standard Series with $\{8\}$ , $\{11\}$ and $\{b\}$ @ B/T = 2.25	1. 2. 3.
g	C <sub>R 3.00</sub>	Use Taylor Standard Series with $\{8\}$ , $\{11\}$ and $\{b\}$ @ B/T = 3.00	1. 2. 3.

CODE	VARIABLE	FORMULA or EXPLANATION of VARIABLE	VALUE
h	C <sub>R 3.75</sub>	Use Taylor Standard Series with $\{8\}$ , $\{11\}$ and $\{b\}$ @ B/T = 3.75	1. 2. 3.
31		Form Factor $\frac{4}{3} \cdot \left[ \frac{Bx}{Tx} - 3 \right]$	
i		({h}-{f}) /2	1. 2. 3.
j		$[(\{f\} + \{h\})/2] - \{g\}$	1. 2. 3.
k		<i>{31}•{i}</i>	1. 2. 3.
1		{31}²•.{j}	1. 2. 3.
m and 30	$C_{R(TSS)}$	Residuary resistance Coefficient, $\{g\}+\{k\}+(\{31\}^2 \times \{j\})$	1. 2. 3.
n and 32	R <sub>R(TSS)</sub>	Residuary Resistance (TSS), $1.4264 \times (\{16\} \bullet \{25\} \bullet \{m\} \bullet \{a\}^2)$	1. 2. 3.
0	WCF	Worm Curve Factor, use figures 4 through 9 with $\{b\}$	1. 2. 3.
р	R <sub>R</sub>	Residuary resistance (ship), $\{n\} \cdot \{o\}$	1. 2. 3.

CODE			
CODE	VARIABLE	FORMULA or EXPLANATION of VARIABLE	VALUE
q	R <sub>T</sub>	Total Resistance, $\{e\} + \{p\}$	1. 2. 3.
r	P <sub>E</sub>	Effective Horsepower, $\{a\} \bullet \{q\}/325.6$	1. 2. 3.
s and 33	P <sub>E(APP)</sub>	Appendage Drag, horsepower, $\{1\} \bullet \{12\} \bullet \{a\}^3 \bullet \{22\}$	1. 2. 3.
t and 34	P <sub>E(AA)</sub>	Air Drag, horsepower, $\{14\} \bullet \{23\} \bullet \{a\}^2 /96,500$	1. 2. 3.
u and 35	P <sub>E(MISC)</sub>	Miscellaneous drag, horsepower,	1. 0.0 2. 0.0 3. 0.0
v	$\Sigma_{\mathrm{P}_{\mathtt{E}}}$	Sum of Effective Horsepowers, $\{r\} + \{s\} + \{t\} + \{u\}$	1. 2. 3.
w	ЕНР	Total Effective Horsepower, $\{v\} \bullet \{24\}$	1. 2. 3.
x and 36	PC	Propulsive Coefficient, EHP/SHP	0.65
у	P <sub>e</sub> P <sub>Sthreshold</sub> P <sub>SGoal</sub>	Shaft Horsepower, $\{w\} / \{x\}$	1. 2. 3.
	P <sub>Ir threshold</sub> P <sub>Ir goal</sub>	Needed Installed Shaft Horsepower {y} • 1.25	2. 3.
	P <sub>I</sub>	Total Installed Shaft Horsepower	

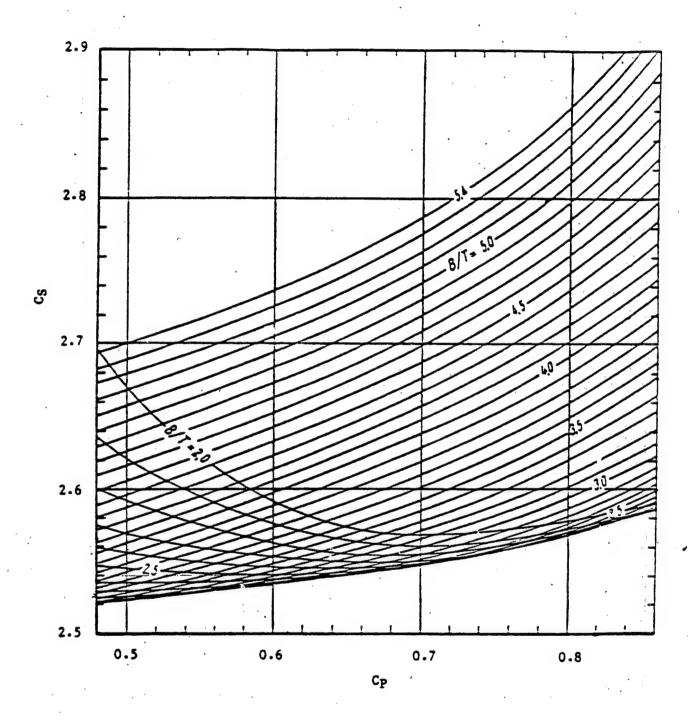


Figure 1: Surface Coefficients  $C_s = S / (Vol \cdot L_{WL})^{0.5}$  for the Taylor Standard Series

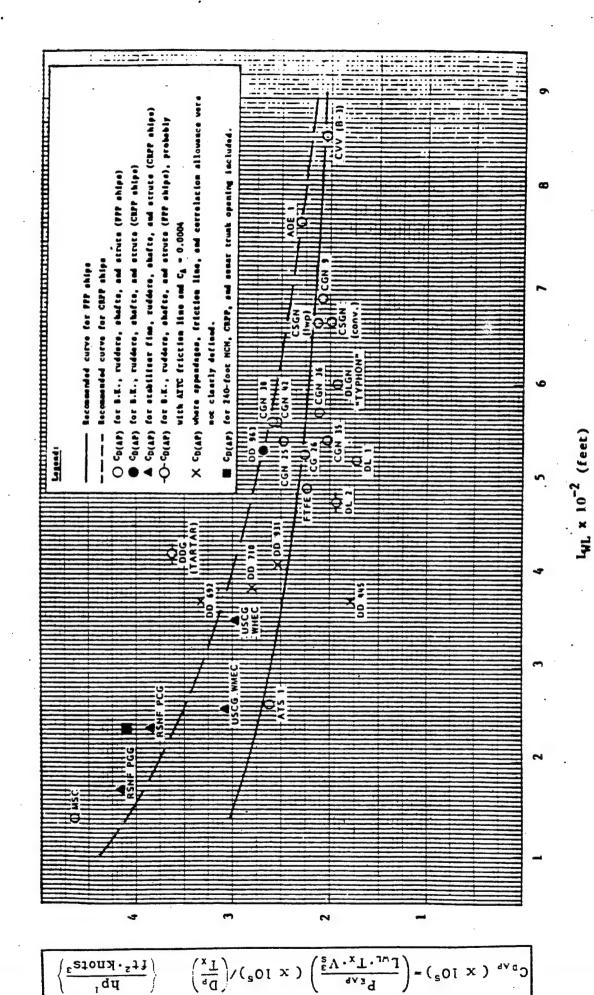


Figure 2: Appendage Drag Coefficients For Twin-Screw Naval Ships With Strut-Supported Shafts Sheet 1 of 2: Plot

118 7

- 1. CD(AP) values based on PE data calculated with ITTC friction line and CA 0.0005, except as noted.
- When selecting the recommended curves for PPP ships, the "X" points were ignored.
- When selecting the recommended curve for CRPP ships, the  ${
  m C}_{
  m D}({
  m AP})$  values for PCG and PGG were given more "weight" than CD(AP) values for WHEC and WHEC.
- The two CSGN points represent model test data for two difference hull forms.
- Compared to the typical  $Dp/T_X$  value of ships represented on this plot, the  $Dp/T_X$  value of the AOE is small.

Figure 2: Sheet 2 of 2: Notes

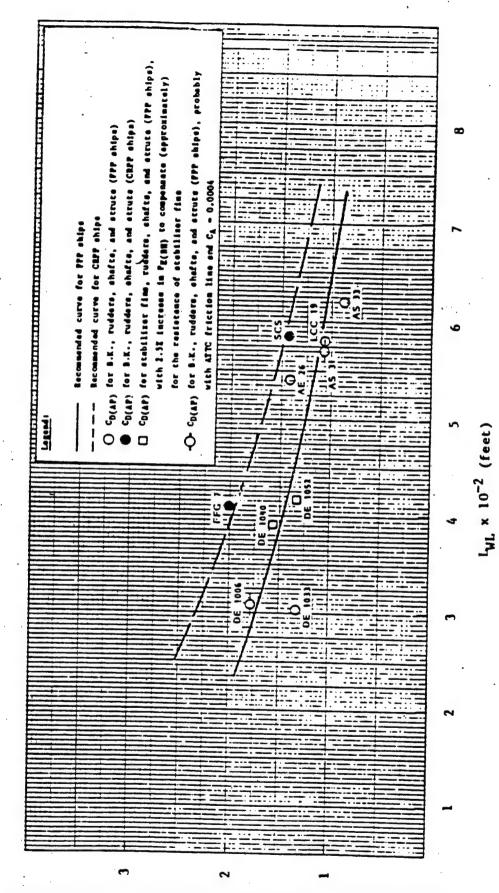


Figure 3: Appendage Drag Coefficients for Single-Screw Naval Ships With Strut-Supported Shafts Sheet 1 of 2: Plot

 $C_{DAP}$  (x 10°) -  $\left(\frac{P_{EAP}}{L_{WL} \cdot T_x \cdot V_s^2}\right)$  (x 10°)  $\left(\frac{T_x}{T}\right)$   $\left(\frac{D_P}{T}\right)$ 

9

120

- 1.  $C_{D(AP)}$  values based on  $P_{R}$  data calculated with ITTC friction line and  $C_{A}$  = 0.0005, except as noted.
- CD(AP) value for the SCS is based on only three Pg(AP) values at closely spaced speeds.
- CD(AP) value for the DE 1006 may include the effect on appendage resistance of two small sound domes.
- $c_{
  m D(AP)}$  value for the PFG 7 includes the effect on appendage resistance of a skeg and a small, keelmounted sound dome.
- Compared to the typical  $D_p/T_X$  value of ships represented on this plot, the  $D_p/T_X$  value of the AE 26

Figure 3: Sheet 2 of 2: Notes

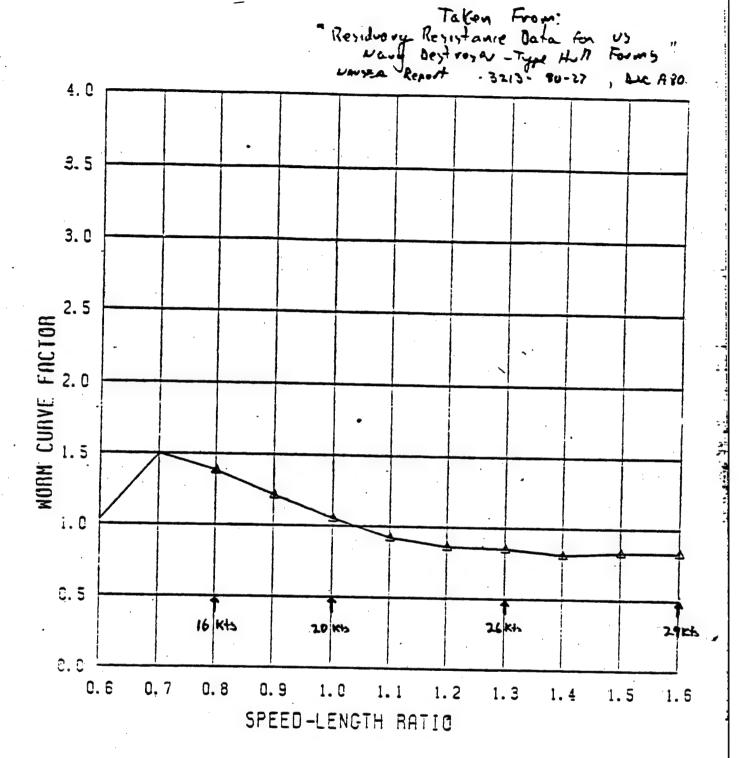


Figure 4: Worm Curve of FFG-7 Hull Form

MODEL 5279

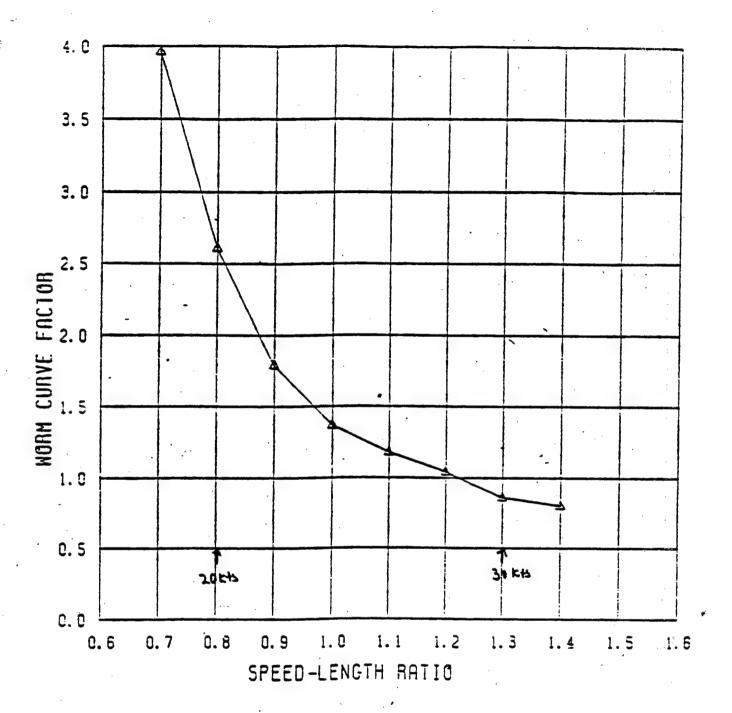


Figure 5: Worm Curve of DD-963 Hull Form with bow mounted AN/SQS-26 sonar dome

\_\_\_\_ MODEL 5265-1

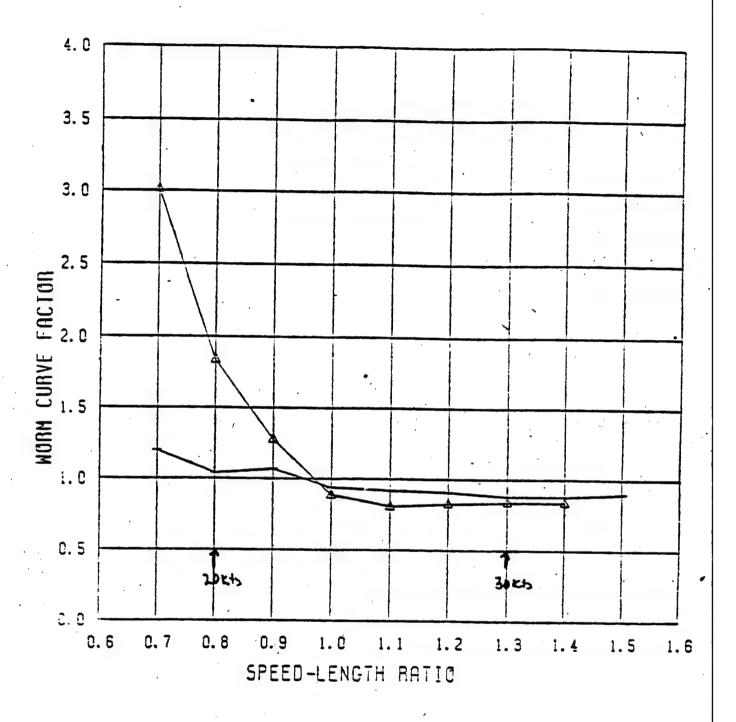


Figure 6: Worm Curve of CG-26 Hull Form with and without bow mounted AN/SQS-26 sonar dome

MCDEL 4858-1 (WITH DOME)

HOGEL 4858 (W/O DOME)

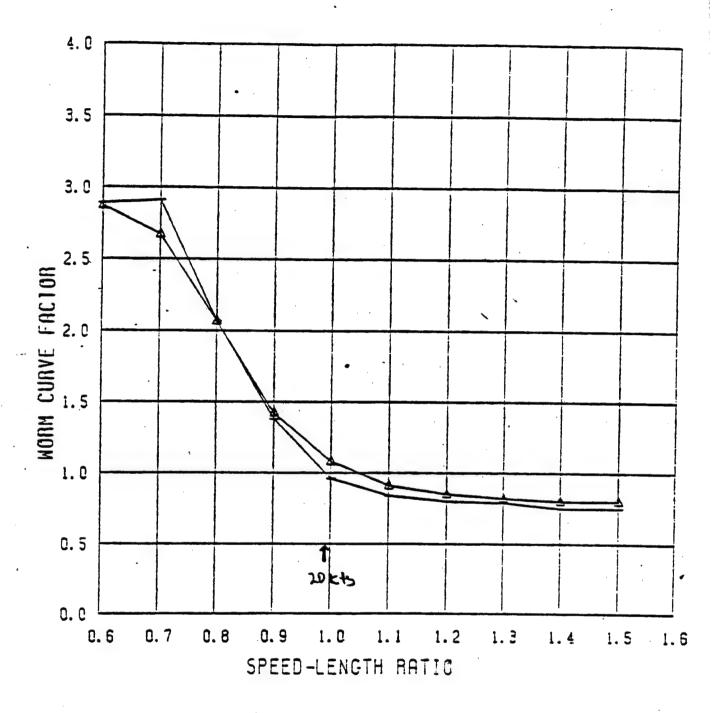


Figure 7: Worm Curve of DDGX Cruise Variant and Seakeeping Variant Hull Forms both with AN/SQS-26 sonar dome



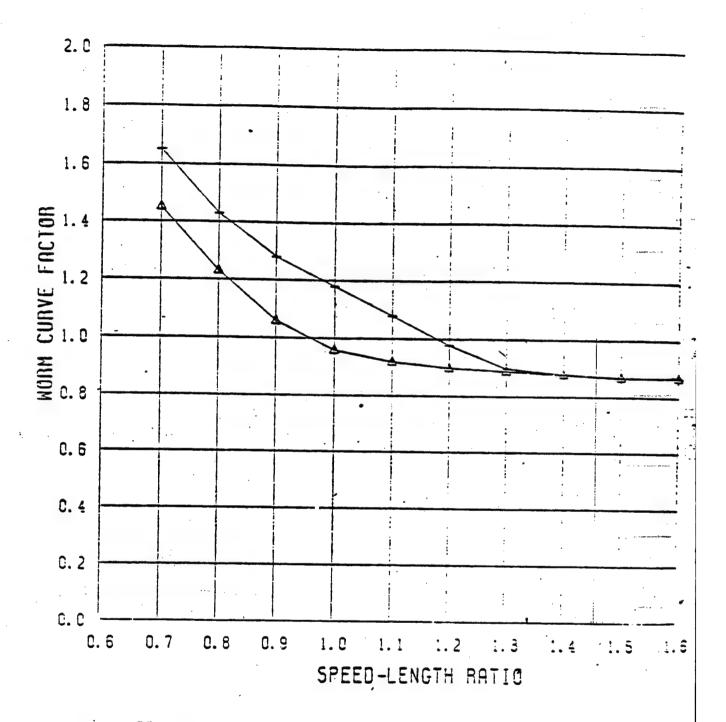


Figure 8: Recommended Worm Curves for USN Destroyer Type Hull Form without bow dome

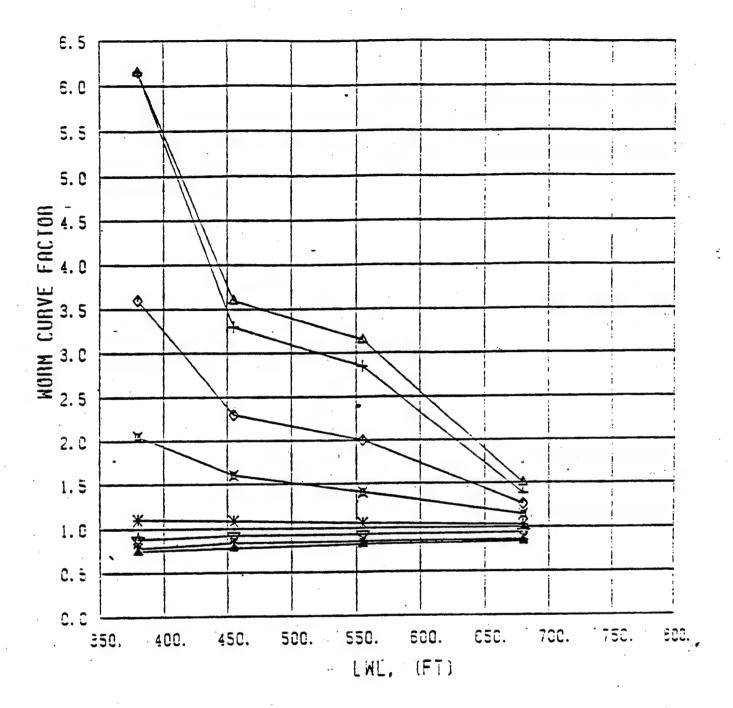


Figure 9: Contours of recommended Worm Curve factor versus Ship Waterline length.

For USN Destroyer Type Hull Forms with bow mounted AN/SQS-26 sonar dome

**	0.5 0.7 0.8 0.9 1.1 1.2 1.4	SPEED-LENGTH RATIO
127	16	

### **ENERGY BALANCE**

### VARIABLES USED.

r			
	SYMBOLS USED IN ENERGY BALANCE MODULE		
Pe	Endurance power, shaft horsepower		
Peavg	Average Endurance power, shaft horsepower		
FR	Specific fuel consumption for engine, lb/hp-hr		
$F_{I}$	Power ratio factor		
FR <sub>SP</sub>	Specified fuel rate		
$P_{I}$	Installed power, shaft horsepower		
FR <sub>avg</sub>	Average Endurance fuel rate		
E	Endurance distance, nautical miles		
V <sub>e</sub>	Endurance speed, knots		
$W_{\mathtt{BP}}$	Burnable propulsion endurance fuel weight		
TPA	Tail pipe allowance, propulsion fuel		
$W_{FP}$	Propulsion endurance fuel weight		
γ	Specific fuel weight, propulsion		
$ abla_{ ext{FP}} $	Propulsion fuel tankage volume		
kW <sub>CL</sub>	Connected Electrical load		
kW <sub>MCL</sub>	Maximum connected load		
kW <sub>FL</sub>	Functional load		
kW <sub>MFL</sub>	Maximum functional load		
kW <sub>MFLm</sub>	Maximum functional load with margin		
n	Number of generators		
kW <sub>c</sub>	Electrical power of single generator		
kW <sub>I</sub>	Installed electrical power		
kW <sub>24</sub>	Average 24 hour electrical load		
kW <sub>24avg</sub>	Average 24 hour electrical load with margin		
$FR_e$	Specific fuel consumption for generator, lb/kW-hr		
$f_{Ie}$	Power ratio factor, electrical		
FR <sub>avg e</sub>	Average electrical fuel rate		

W <sub>Be</sub>	Burnable electrical endurance fuel weight		
TPA <sub>e</sub>	Tail pipe allowance, electrical fuel		
$W_{Fe}$	Electrical endurance fuel weight		
γe	Specific fuel weight, electrical		
$ abla_{ extsf{Fe}}$	Electrical fuel tankage volume		
$W_{\scriptscriptstyle F}$	Total Fuel Weight		
$ abla_{ extsf{F}}$	Total propulsion and electrical fuel tankage volume		

#### **Calculations:**

#### **Propulsion Fuel**

#### Average Endurance Power

$$P_{eave} = 1.1 \cdot P_{e}$$

where the 10% factor is for sea state, hull fouling, machinery degredation, etc.

#### Specified Fuel Rate

$$FR_{SP} = f_1 \cdot FR$$

where f<sub>1</sub> factor is for instrumentation inaccuracies and machinery changes and is given by the following:

$$f_{1} = \begin{bmatrix} 1.04 & for & \frac{P_{e}}{P_{I}} < \frac{1}{3} \\ 1.03 & for & \frac{P_{e}}{P_{I}} < \frac{2}{3} \\ 1.02 & for & \frac{P_{e}}{P_{I}} < 1 \end{bmatrix}$$

and FR is the Specified Fuel Consumption for the engine.

#### Average Endurance Fuel Rate

$$FR_{avg} = 1.05 \cdot FR_{SP}$$

where 5% factor is for plant deterioration.

Burnable Propulsion Endurance Fuel Weight

2

$$W_{B_p} = \frac{E}{V_e} (P_{e_{avg}} \cdot FR_{avg}) \cdot \frac{1}{2240}$$

Tail Pipe Allowance

$$TPA = \begin{bmatrix} 0.95 \text{ for broad, shallow tanks} \\ 0.98 \text{ for narrow, deep tanks} \end{bmatrix}$$

#### Propulsion Endurance Fuel Weight

$$W_{F_{P}} = \frac{W_{B_{P}}}{TPA}$$

#### Tankage Volume for Propulsion Fuel

$$\nabla_{\text{FP}} = 1.02 \cdot 1.05 \cdot \gamma \cdot W_{\text{FP}}$$

where the 5% factor is for fuel expansion and 2% is for the tank structure.

#### Electrical Load and Fuel

#### Estimate Maximum Functional Load with Margin

a. Estimate load for four conditions at two temperatures:

FILL IN LOAD kW <sub>CL</sub>	10 F	
Battle		
Cruise		
Anchor		
In Port		

and the largest of these loads is the maximum connected load,  $kW_{\text{MCL}}$ .

b. The functional load can be obtained by one of the following methods:

Functional Load =  $kW_{FL} = kW_{CL} \cdot Load$  Factor (see DDS 9610-2)

or from empirical formulas based on crew size, volume, payload, combat systems, etc. The maximum functional load is designated by  $kW_{MFL}$ 

c. Maximum functional load with margin:

$$kW_{MFLm} = 1.2 \cdot 1.2 \cdot kW_{MFL}$$

where the 20% factors are for acquisition (design and build) and service life margins.

#### Determine Installed Electrical Power

a. Generator size is obtained from the following formula:

$$kW_G \geq \frac{kW_{MFLm}}{(n-1)(0.9)}$$

where the n-1 factor is for one generator out of commission and the 0.9 factor is for generator control

b. Complete generator power installed is gotten from the following:

$$kW_I = n \cdot kW_G$$

#### Estimate Average 24 hour Electrical Load

kW24 consists of the complete propulsion and steering loads required during cruise operations and 75% of all other cruise loads. Note that this does not contain any margins.

Average 24 hour Electrical Load with Margin

$$kW_{24avg} = 1.2 \cdot kW_{24}$$

where the 20% factor is an acquisition margin.

#### Average Electrical Fuel Rate

$$FR_{avge} = 1.05 f_{1e} FR_{e}$$

where the  $f_{1e}$  factor is for machinery changes and instrumentation inaccuracies and is given by the following:

$$f_{1_{\epsilon}} = \begin{bmatrix} 1.04 & for & \frac{P_{\epsilon}}{P_{I}} < \frac{1}{3} \\ 1.03 & for & \frac{P_{\epsilon}}{P_{I}} < \frac{2}{3} \\ 1.02 & for & \frac{P_{\epsilon}}{P_{I}} < 1 \end{bmatrix}$$

where P<sub>e</sub>/P<sub>I</sub> is defined in the following way for electric power:

$$\frac{P_e}{P_I} = \frac{kW_{24_{evg}}}{(n-1) \cdot kW_G}$$

FRe is the specified fuel consumption for a generator and the 5% factor is for plant deterioration.

Burnable Electrical Endurance Fuel Weight

$$W_{B_e} = \frac{E}{V_e} (kW_{24_{avg}} \cdot FR_{avg_e}) \cdot \frac{1}{2240}$$

Tail Pipe Allowance, Electrical

$$TPA_e = \begin{bmatrix} 0.95 \text{ for broad, shallow tanks} \\ 0.98 \text{ for narrow, deep tanks} \end{bmatrix}$$

Electrical Endurance Fuel Weight

$$W_{F_{\epsilon}} = \frac{W_{B_{\epsilon}}}{TPA_{\epsilon}}$$

Tankage Volume for Electrical Fuel

$$\nabla_{\mathbf{F}_e} = 1.02 \cdot 1.05 \cdot \gamma \cdot \mathbf{W}_{\mathbf{F}_e}$$

where the 5% factor is for fuel expansion and the 2% is for tank structure.

**Total Fuel Values** 

Total Fuel Weight

$$W_F = W_{FP} + W_{Fe}$$

Total Propulsion and Electrical Fuel Tankage

$$\nabla_{\mathbf{F}} = \nabla_{\mathbf{FP}} + \nabla_{\mathbf{Fe}}$$

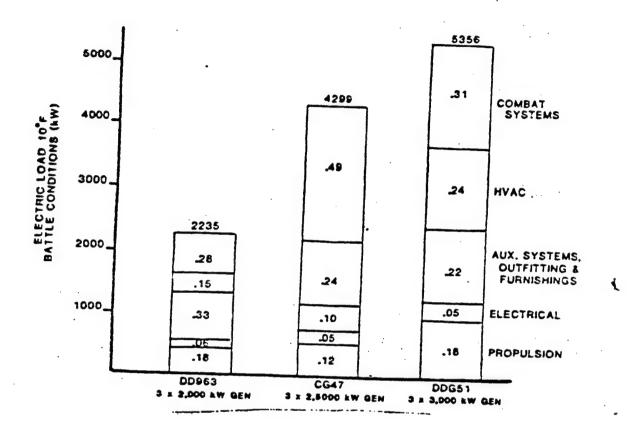


Fig 12 INSTALLED POWER

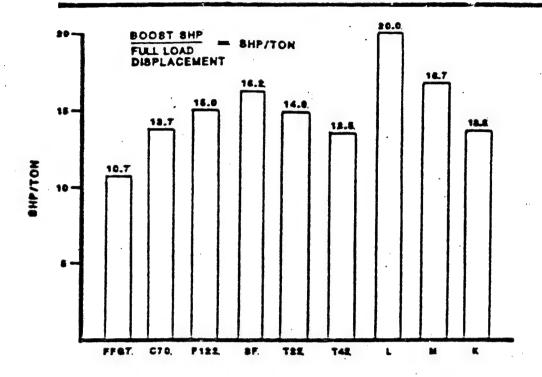
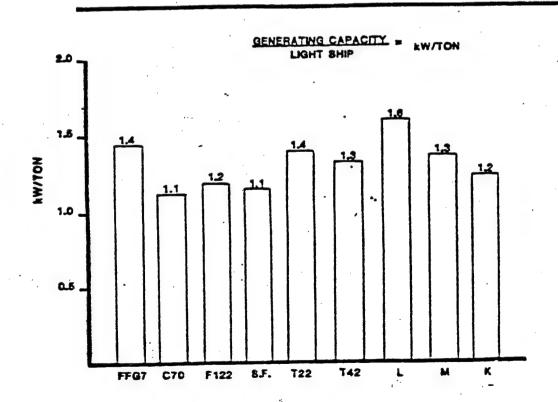


Fig 13 FRIGATES - ELECTRICAL CAPACITY



# APPENDIX D. MATLAB OPTIMIZATION COMPUTER PROGRAM

```
% This MATLAB program initiates the use of the optimization toolbox for%
 % a constrained, non-linear problem. Two input arrays from the Mathcad%
 % worksheet (w,z) are used in conjunction with the user defined design %
 % space boundaries (vlb, vub) and initial design variable guess (x0).
 % These are passed to the optimizer (constr), which determines the
 % minimum full load displacement and the values of the design variables%
 % at that point.
 %Input weight array from Mathcad%
 w=in0;
                         % Input values for # of personnel, speed and
 z=in2;
                         % endurance%
                        %Toggles on optimizer output summary%
 options(1)=1;
 diary outopt
                         % Saves optimizer input/output details to
                         % MATLAB editor%
                                   % Initial guess of B,T,LWL,Cp,Cx
 x0=[in1(1),in1(2),in1(3),.6,.75]
                                   % from Mathcad%
                                 %Use different intial guess to check
 %x0=[0,0,0,0,0]
                                 %if local minimum.
                        %Upper and Lower bounds of design variables%
 vlb=[20,5,200,.54,.7]
 vub=[90,30,800,.64,.85]
 [x,options]=constr('disp3opt',x0,options,vlb,vub,[],w,z)
 diary off
 optctr=options(10)
                          % Counter for number of optimization
                          % iterations%
B=x(1)
 T=x(2)
 LWL=x(3)
 cp=x(4)
 cx=x(5)
 [Wfl,g,Cgmb] = disp3opt(x,w,z);
 Cbt=x(1)/x(2);
 Clb=x(3)/x(1);
 Cdispl=Wfl/((x(3)/100)^3);
 out0=[Wfl,x,Cbt]';
 out1=[Cbt, Clb, Cqmb, Cdispl, optctr]';
```

```
function [Wf41,Dp]=resist_calc(x,z)
% This function calculates the hull resistance, the propulsion power %
 % and the electrical service load required to generate the necessary %
% fuel load as part of the full load displacement calculation. The %
% resistance calculation uses Gertler's reanalysis of the Taylor
% Standard Series. The designer must ensure that the following
% variables are properly assigned to remain consistent with the
% Mathcad model: FR
RESISTANCE AND PROPULSION POWER CALCULATIONS
Cpropd=z(9);
                          %Cpropd=1.2 for one prop, 1.0 for two props%
Dp=(.662*x(2)+.012*x(3))*Cpropd; %Prop diameter%
Aw=x(1)*(3*x(2));
                                 %Frontal Area of Ship%
roair=.0023817; Tsw=59; rosw=1.995; nusw=1.2817e-5; %Physical
                   lton=2240;
hp=33000/60;
                                  knt=1.69;
                                                   %Properties
                %Correlation allowance%
Ca=.0005;
Cstss=2.53;
               %Wetted surface coefficient, average value%
volfl=x(1)*x(2)*x(3)*x(4)*x(5);
                                %Underwater volume%
Ss=Cstss*sqrt(volfl)*sqrt(x(3)); %Wetted surface area%
Cdapp=2.85*hp*1e-5/knt^3;
                               * %Appendage drag coefficient%
Caa=.7;
                                 %Air drag coefficient%
PMF=1.1;
                                 %Power Margin Factor%
Ve=z(3)*knt
                                %Endurance speed%
Vs=z(2)*knt
                                %Sustained speed%
E=z(4)*knt
                                %Endurance range%
for i=1:7
   V(i)=i*5*knt;
   V(4) = Ve;
                                 %Endurance speed%
   V(6) = Vs;
                                 %Sustained speed%
   R(i) = (V(i)/sqrt(x(3)))/knt;
                                %Speed-to-length ratio%
   Rn(i)=x(3)*V(i)/nusw;
                                 %Reynolds Number%
   Cf(i) = .075/(log10(Rn(i))-2)^2;
   Rf(i)=.5*(rosw*Ss*(V(i))^2*(Ca+Cf(i))); %ITTC Friction%
   %Taylor Resistance Coefficient for interpolation of Cr%
   Cr225=[.00028 .00028 .00028 .0008 .00150 .00335 .00410];
   Cr300=[.00035 .00035 .00042 .001 .0018 .0035 .0043];
   Cr375=[.00048 .00048 .00048 .00095 .0018 .0036 .0046];
   FF=(4/3)*((x(1)/x(2))-3);
                                                %Form Factor%
   Crtss(i) = Cr300(i) + FF*((Cr375(i) - Cr225(i))/2) + FF^2*...
            ((Cr225(i)+Cr375(i))/2-Cr300(i));
   Rrtss(i) = .5*(rosw*Ss*V(i)^2*Crtss(i));
                                               %TSS Resistance%
   WCF=[3.242 2.124 1.460 1.083 .923 .880 .870]; %Worm Curve Factor%
   Rr(i) = Rrtss(i) *WCF(i);
```

```
Rt(i) = Rf(i) + Rr(i);
                               %Bare hull effective horsepower%
   Pebh(i)=Rt(i)*V(i)/hp;
                               %Sonar Dome, SQS-53C=215ft, SQS-56=27ft%
   Csd=.28; Asd=z(5);
   Peapp(i)=(x(3)*Dp*Cdapp+.5*Csd*rosw*Asd)*(V(i)^3)/hp; %Appendage HP%
   Peaa(i)=.5*Caa*Aw*roair*V(i)^3/hp; %Air resistance horsepower%
   Pet(i) = (Pebh(i) + Peapp(i) + Peaa(i));
   EHP(i) = PMF*Pet(i);
                                        %Total effective horsepower%
   PC=.67:
                       %Propulsive Coefficient%
   SHP(i)=EHP(i)/PC; %Shaft horsepower%
end
Pe=SHP(4);
                       %Endurance shaft horsepower%
                       %Sustained speed shaft horsepower%
Ps=SHP(6);
Pireg=1.25*Ps;
                       %Required installed horsepower%
Npeng=z(10);
                       %Number of engines installed%
Pbeng=z(11);
                       %Engine horsepower%
Pibrake=Npeng*Pbeng; %Installed BHP%
%PROPULSION FUEL WEIGHT CALCULATION%
Pebavg=(1.1*Pe)/.97; %Average endurance BHP required, w/fouling%
FR=1.97*Pebavg^(-.15); Specific fuel rate, GT. (Diesel=.327, ICR=.347) 
f1=1.04;
                       %Margin for instrumentation differences%
FRsp=f1*FR;
                       %Specified fuel rate%
FRavg=1.05*FRsp;
                       %Average fuel due to plant deterioration%
Wbp=(E/Ve)*Pebavg*FRavg/lton; &Burnable propulsion endurance fuel wt%
Wfp=Wbp/.95;
                       %Tailpipe allowance%
gammaf=43;
                       %Fuel specific volume%
Vfp=1.02*1.05*gammaf*Wfp; %Propulsion fuel volume%
%ELECTRICAL LOAD CALCULATION%
Nt=z(1);
                                  %# of personnel%
kWfins=z(7);
                                  %Stabilizing fin power%
kWp=.00466*Pibrake;
                                  %Propulsion electrical load%
kWs = .00583 * x(3) * x(2);
                                  %Steering electrical load%
kWl=.0002053*1.8*x(1)*x(2)*x(3); %Lighting electrical load%
                                  %Miscellaneous load%
kWm=46.1;
kWh=.0013*1.25*x(1)*x(2)*x(3);
                                  %Heating electrical load%
kWcps=.00026*1.8*x(1)*x(2)*x(3); %CPS electrical Load%
kWv=.19*(kWh+kWp)+kWcps;
                                  %Ventilation electrical load%
kWac=.67*(.1*Nt+.0015*.47*1.3*x(1)*x(2)*x(3)+.1*kWp); %A/C load%
kWb=.94*Nt;
                                  %Aux boiler and FW%
kWf=.0001*1.8*x(1)*x(2)*x(3);
                                  %Firemain load%
kWrh=.00002*1.25*x(1)*x(2)*x(3); %Unrep and handling load%
kWa=.22*Nt+kWfins;
                                  %Aux machinery load%
kWserv=.35*Nt;
                                  %Service and work space load%
%Non-payload functional load%
kWnp=kWp+kWs+kWl+kWm+kWh+kWcps+kWv+kWac+kWb+kWf+kWrh+kWa+kWserv;
kWpay=z(6);
                                %Payload power%
kWmfl=kWpay+kWnp;
                                  %Maximum functional load%
kWmflm=1.2*1.2*kWmfl;
                                  %With margins%
kW24=.5*(kWmfl-kWp-kWs)+.8*(kWp+kWs); %24 hr electrical load%
                                        %With margins%
kW24avg=1.2*kW24;
```

# **%ELECTRICAL FUEL RATE%**

FRg=.113; FRgsp=f1\*FRg;

FRgavg=1.05\*FRgsp;

%Specific fuel rate for generators%

%With margins%

%Plant deterioration%

Wbe=(E/Ve)\*(kW24avg\*FRgavg)/lton; %Burnable electric fuel weight%

Wfe=Wbe/.95;

%Tank allowance%

Vfe=1.02\*1.05\*gammaf\*Wfe;

%Electrical Fuel volume%

Wf41=Wfp+Wfe;
Vf=Vfp+Vfe;

%Total ship fuel weight, lton%

%Total ship fuel volume%

```
function [CN,D10,Vd,Vt]=cubicnum calc(x)
% This function calculates the cubic number and the depth of the
% midships section. The total volume is calculated from the
\$ sum of the underwater and deckhouse volumes. The deckhouse volume \$
% can be calculated using a range of values to fit the requirement. %
% The designer must ensure that the calculation of Vd is consistent %
% between this M-file and the Final Synthesis Design Mathcad
% Worksheet.
%CALCULATE CUBIC NUMBER%
%Sheer Line%
M=[.21*x(1)+x(2), x(3)/15, 22];
D10min=max(M);
D10=D10min+1;
D0=1.0111827*x(2)-(6.36215e-6*x(3)^2)+(2.780649e-2*x(3))+x(2);
D20=.014*x(3)*(2.125+(1.25e-3*x(3)))+x(2);
%Above Water Hull Volume%
F0=D0-x(2);
F10=D10-x(2);
F20=D20-x(2);
Apro=x(3)*(F0+4*F10+F20)/6;
Fav=Apro/x(3);
Dav=Fav+x(2);
CN=x(3)*x(1)*Dav/le5;
                         %Cubic Number%
Cw=.236+.836*x(4);
Mf=[ff 1]; ff=max(Mf);
Vhaw=x(3)*x(1)*Fav*Cw*ff;
Vfl=x(1)*x(2)*x(3)*x(4)*x(5);
                            %Underwater volume%
Vht=Vfl+Vhaw;
Vd=.0025*x(3)^3;
                            %Deckhouse volume, max calc%
Vd=.0005*x(3)^3;
                            %Deckhouse volume, min calc%
                            %Total ship volume%
Vt=Vht+Vd;
```

```
function [Wdvd, W24, Wls, w] = dvd weights (x, Dp, CN, Vd, Vt, w, z)
\$ This function calculates the design variable dependent weights and \$
% the light ship weight.
% DESIGN VARIABLE DEPENDENT WEIGHTS %
lton=2240;
                                      %Long ton conversion factor%
Nt=z(1);
                                      %Number of Personnel%
Npeng=z(10);
                                      %Number of propulsion engines%
Pbeng=z(11);
                                      %Engine horsepower%
Np=z(12);
                                     %Numper of propellers%
Pinst=Npeng*Pbeng*.97;
                                     %Installed power%
fs=z(13);
                                      %.5 twin screws,.33 single%
W237=w(7);
                                      %APU weight%
Wbm=Pinst*(9+12.4*((Pinst*le-5)-1)^2)/lton;%Propulsion weight%
Ws=.356*x(3)*fs;
                                     %Shaft weight%
Wpr=(Np*.05575*Dp^(5.497-.0433*Dp))/lton;%Propeller weight%
Wb=.15*(Ws+Wpr);
                                     %Bearing weight%
Wst=Ws+Wpr+Wb;
                                      %Total Shafting weight%
W2=Wbm+W237+Wst;
                                     %Total propulsion weight%
Waux=(.00072*Vt^1.443+5.14*Vt+6.19*Vt^.7224+377*Nt+2.74*Pinst)*...
  1e-4+113.8;
                          %Auxiliary machinery weight
w(13) = Waux;
W598=.000075*Vt;
                          %Auxiliary machinery fluid weight%
W5=Waux+W598;
W6=(31.4+.0003187*Vt);
                         %Wofh, hull fitting weights%
w(15) = W6:
Wic=4.65*CN;
                          %Gyro/Nav/IC%
w(9) = Wic;
Wco=2.24*CN;
                          %Other Group 400%
w(10) = Wco;
Wcc=.04*(w(25)+Wic+Wco);
                          %Cabling Weight%
w(11)=Wcc;
W4=w(25)+Wic+Wco+Wcc+w(12); %Intermediate Weight Group Sum%
w(1) = Wbh;
rodh=.001429;
                          %Deckhouse density, steel%
Wdh=rodh*Vd;
                          %Deckhouse weight
w(2) = Wdh;
W171 = .0688 * x(3) - 13.75;
                          %Mast Weight%
w(4) = W171;
W180=.0675*Wbm+.072*(w(8)+W4+W5+w(32)); %Foundation Weights%
w(3) = W180;
W1=Wbh+Wdh+W171+W180;
Wvpw=w(24)-w(17)-w(18)-w(19)-w(33); %Subtract out variable payloads%
```

Wm24=0.1\*(Wvpw+W1+W2+W4+W5+W6);

Wdvd=W1+W2+W4+W5+W6+Wm24; W24=Wdvd-Wm24+Wvpw; Wls=Wdvd+Wvpw %10% Weight Margin for Future Growth%
%Design Variable Dependent Weights%
%Lightship weight%

```
function GM=stability calc(x,w,f,D10,Wls,W24)
% This function uses the previously calculated full load displacement %
% to generate stability data and return the value of GM for the
% constraint requirements.
% STABILITY CALCULATION %
Vfl=x(1)*x(2)*x(3)*x(4)*x(5); %Underwater volume%
%CALCULATE MOMENTS%
P(1)=w(1)*.527*D10;
                            %Bare hull weight%
P(2)=w(2)*(D10+1.5*9);
                            %Deckhouse weight%
P(3)=w(3)*.68*D10;
                            %Foundation weight%
P(4)=w(4)*2.65*D10;
                            %Mast weight%
P(5)=w(5)*.5*D10;
                            %Propusion machinery weight%
P(6) = w(6) * (3.9 + .19 * x(2));
                            %Shafting weight%
P(7) = w(7) * w(30);
                            %APU weight%
P(8)=w(8)*.65*D10;
                            %Electric generator weight%
P(9)=w(9)*D10;
                            %Gyro/IC/Nav weight%
P(10)=w(10)*(5.6+.4625*D10); %Misc group 400 weight%
P(11)=w(11)*.5*D10;
                            %Cabling weight%
P(12)=w(12)*w(31);
                            %Sonar dome weight%
P(13)=w(13)*.9*(D10-7.4);
                            %Auxiliary weight%
P(14)=w(14)*.5*D10;
                            %Aux steam weight%
P(15) = \dot{w}(15) * .805 * D10;
                            %Hull fitting weight%
P(16) = w(16) * (8+.71*D10);
                            %Personnel misc%
P(17)=w(17)*.746*D10;
                           %Crew weight%
P(18)=w(18)*.55*D10;
                            %Provision weight%
P(19)=w(19)*.65*D10;
                            %General stores%
P(20)=w(20)*7.5;
                            %Fuel weight%
P(21)=w(21)*10;
                            %Helo fuel weight%
P(22)=w(22)*.35*D10;
                            %Lube oil weight%
P(23)=w(23)*7.5;
                            %Potable water weight%
ww=w(26) *w(28) -w(27) *w(29);
px=sum(P(1:16));
Pwg=px+ww;
KGls=Pwg/W24;
Pwgl=sum(P(17:23))+w(27)*w(29);
Wl=sum(w(17:23))+w(33);
VCGl=Pwql/W1;
KG=(((Wls*KGls)+(Wl*VCGl))/f)+.5;
Cw=.236+.836*x(4);
Cit=-.497+1.44*Cw;
KB = (x(2)/3) * (2.5 - (x(4) * x(5)/Cw));
BM = (x(3)*x(1)^3*Cit)/(12*Vf1);
GM=KB+BM-KG;
```

# APPENDIX E. MATHCONNEX INTEGRATED SHIP DESIGN SYSTEM VALIDITY AND ROBUSTNESS CHECKS

Design		Initial Run		Expand	<b>Expand Side Constraints</b>	raints	High Va	High Value Initial Guess	ness
Attribute	Results	qnv-qlv	0×	Results	qnv-qiv	0x	Results	qnv-qlv	오
Displacement, Wfl (Iton)	6123.424			6123.424			6123.424		
Beam, B (ft)	45.50163	40 to 70	55.745	45.50163	20 to 90	55.745	45.50163	20 to 90	100
Draft, T (ft)	12.29774	10 to 30	16.892	12.29774	5 to 40	16.892	12.29774	5 to 40	100
Waterline Length, LWL (ft)	455.0163	455.0163 400 to 700	495.3	455.0163	455.0163 200 to 800	495.3	455.0163	455.0163 200 to 800	1000
Prismatic Coefficient, Cp	0.54	.54 to .64	9.0	0.54	.54 to .64	9.0	0.54	.54 to .64	10
Max Transverse Section, Cx	0.787983	.70 to .85	0.75	0.787983	.70 to .85	0.75	0.787983	.70 to .85	10
Beam-to-Draft, Cbt	3.7			3.7			3.7		
Length-to-Beam, Clb	10			10			10		
GM-to-Beam, Cgmb	0.122			0.122			0.122		
Displacement-to-Length, Cdl	65			65			65		
Number of Iterations	31			31			109		

		****			_			****				****
Optimum	0×		55.745	16.892	495.3	9.0	0.75		ing:	sible	found.	
Constrained Below Optimum	qnv-qiv		20 to 90	5 to 10	406.4662 200 to 800	.54 to .64	.70 to .85		Warning:	No feasible	solution found	
Constrain	Results	4729.255	40.22113	10.41899	406.4662	0.121007 .54 to .64	0.281007	3.860366	10.10579	-0.33549	70.42378	37
Optimum	0x		55.745	16.892	495.3	9.0	0.75					
Constrainted Above Optimum	qnv-qlv		50 to 90	15 to 40	500 to 800	.54 to .64	.70 to .85					
Constrair	Results	7182.628	20	15	200	0.54	0.770449	3.33333	10	0.122	57.46102	32
ness	0×		0	0	0	0	0					
Low Value Initial Guess	qn^-ql^		40 to 70	.29774 10 to 30	5.0163 400 to 700	.54 to .64	787983 .70 to .85					
Low Va	Results	6123.424	45.50163	12.29774	455.0163	0.54	0.787983	3.7	10	0.122	9	49
Design	Attribute	Displacement, Wfl (Iton)	Beam, B (ft)	Draft, T (ft)	Waterline Length, LWL (ft)	Prismatic Coefficient, Cp	Max Transverse Section, Cx	Beam-to-Draft, Cbt	Length-to-Beam, Clb	GM-to-Beam, Cgmb	Displacement-to-Length, Cdl	Number of Iterations

Results of Optimizer Validity and Robustness Checks.

## MATLAB OPTIMIZER DETAILED OUTPUT FOR VALIDIDITY AND ROBUSTNESS CHECKS:

```
Initial Run Results:
                          495.3014
                                      0.6000
                                                 0.7500
x0 = 55.7451
                 16.8924
vlb = 40.0000
                 10.0000
                          400.0000
                                      0.5400
                                                 0.7000
vub = 70.0000
                 30.0000 700.0000
                                       0.6400
                                                 0.8500
f-COUNT
          FUNCTION
                          MAX\{g\}
                                          STEP
                                                Procedures
           7627.82
    6
                        0.534195
                                             1
                                             1
   12
             6312.8
                    0.0459915
                      0.00388632
                                             1
   18
           6099.97
   24
            6123.31 1.92403e-005
                                             1
   30
            6123.42 6.04933e-010
                                             1
                                                 Hessian modified
                                             1
   31
           6123.42 8.88178e-016
                                                 Hessian modified
Optimization Converged Successfully
Active Constraints:
     2
     4
     6
     8
                                     0.5400
                12.2977 455.0163
                                                0.7880
x = 45.5016
Expand Side Constraints:
                 16.8924
                          495.3014
                                    0.6000
                                                 0.7500
x0 = 55.7451
vlb = 20.0000
                  5.0000
                          200.0000
                                       0.5400
                                                 0.7000
                 40.0000
                          800.0000
                                       0.6400
vub = 90.0000
                                                 0.8500
f-COUNT
          FUNCTION
                                          STEP
                                                Procedures
                          MAX{g}
           7627.82
                        0:534195
    6
                                             1
   12
             6312.8
                       0.0459915
                                             1
            6099.97
   18
                      0.00388632
                                             1 .
   24
            6123.31 1.92403e-005
                                             1
   30
            6123.42 6.04933e-010
                                             1
                                                 Hessian modified
            6123.42 8.88178e-016
                                             1
                                                 Hessian modified
   31
Optimization Converged Successfully
Active Constraints:
     4
     6
     8
                       455.0163
                                     0.5400
                                               0.7880
x = 45.5016
              12.2977
```

```
High Value Initial Guess:
                                              10
                                                           10
                               1000
                   100
x0 = 100
                           200.0000
                                       0.5400
                                                  0.7000
vlb = 20.0000
                  5.0000
vub = 90.0000
                 40.0000
                           800.0000
                                       0.6400
                                                  0.8500
f-COUNT
           FUNCTION
                          MAX\{g\}
                                           STEP
                                                 Procedures
                                                  infeasible
    6
            26700.1
                        0.244444
                                              1
                     -0.00381213
                                              1
   12
            23210.4
                                            0.5
   19
                     -0.00179031
              19983
                                            0.5
   26
            11608.4
                        -0.03448
                                            0.5
                      -0.0343611
            7598.42
   33
                      -0.0150468
                                            0.5
            6651.19
   40
                                            0.5
                      -0.0075712
   47
            6359.78
                                            0.5
   54
            6236.04
                     -0.00384339
                                            0.5
   61
            6178.47
                     -0.00194103
                                            0.5
            6150.64 -0.000975889
   68
            6136.96 -0.000489382
                                            0.5
   75
                                            0.5
            6130.17 -0.000245074
   82
                                            0.5
            6126.79
                     -0.00012263
   89
            6125.11 -6.13377e-005
                                             0.5
   96
            6123.42 6.05291e-008
                                              1
  102
            6123.42 1.36113e-013
                                              1
                                                  Hessian modified twice
  108
  109
            6123.42
                                0
                                              1
                                                  Hessian modified twice
Optimization Converged Successfully
Active Constraints:
     2
     4
     6
     8
x = 45.5016
               12.2977
                        455.0163
                                     0.5400
                                                0.7880
Low Value Initial Guess:
                                0
             0
                   0
                         0
x0 =
      0
                  5.0000 200.0000
                                       0.5400
                                                  0.7000
vlb = 20.0000
                                       0.6400
vub = 90.0000
                 40.0000 800.0000
                                                  0.8500
                                           STEP
                                                 Procedures
f-COUNT
          FUNCTION
                          MAX\{q\}
    6
            3317.57
                          5.37994
                                              1
   12
            3686.38
                          5.72939
                                              1
                                              1
   18
            4293.17
                        0.774454
            5199.71
                          0.23014
                                              1
   24
                                              1
   30
            5911.86
                       0.0398647
                      0.00179708
                                              1
   36
            6113.23
  . 42
             6123.4 4.04898e-006
                                              1
                                              1
                                                  Hessian modified
            6123.42 1.33333e-011
            6123.42 3.77476e-015
                                                  Hessian modified
                                              1
Optimization Converged Successfully
Active Constraints:
     2
     4
     6
     45.5016
                12.2977 455.0163
                                      0.5400
                                                 0.7880
```

```
Constrained Above Optimum:
x0 = 55.7451
                16.8924
                         495.3014
                                      0.6000
                                                0.7500
vlb = 50.0000
                15.0000
                         500.0000
                                      0.5400
                                                0.7000
vub = 90.0000
                40.0000
                         800.0000
                                      0.6400
                                                0.8500
f-COUNT
          FUNCTION
                         MAX{g}
                                         STEP
                                               Procedures
           7712.59
    6
                        0.508232
                                            1
   12
           7188.86
                               0
                                            1
           7185.72
                                          0.5
   19
   25
           7182.61
                     0.00010248
   31
           7182.63 2.87194e-009
                                            1
                                                Hessian modified
   32
           7182.63 1.55431e-015
                                                Hessian modified
Optimization Converged Successfully
Active Constraints:
     4
     6
x = 50.0000
              15.0000 500.0000
                                    0.5400
                                              0.7704
Constrained Below Optimum:
x0 = 55.7451
                16.8924
                         495.3014
                                      0.6000
                                                0.7500
vlb = 20.0000
                 5.0000
                         200.0000
                                      0.5400
                                               .0.7000
vub = 90.0000
                10.0000 ' 800.0000
                                      0.6400
                                               0.8500
```

f-COUNT	FUNCTION	$MAX\{g\}$	STEP	Procedures
6	6906.3	1.70751	1	infeasible
12	4987.11	0.801315	1	infeasible
18	4738.86	0.0763757	1	infeasible
24	4729.4	0.083331	1	infeasible
30	4729.26	0.0834429	1	Hessian modified twice;
infeasibl	e			
36	4729.26	0.0834426	1	Hessian modified;
infeasibl	e			
37	4729.26	0.0834427	1	Hessian modified;
infeasibl	e			
		4		t .

Warning: No feasible solution found.

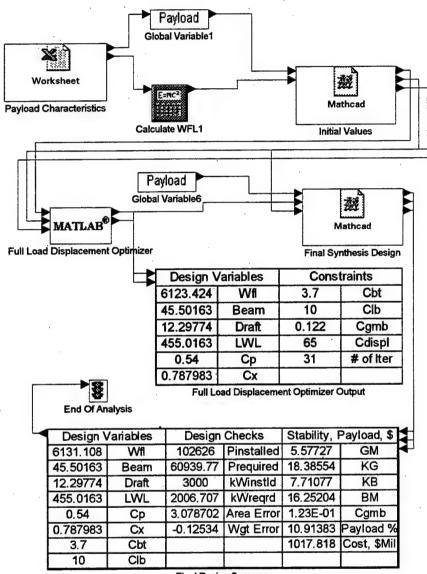
x = 40.2211 10.4190 406.4662 0.1210 0.2810

# APPENDIX F. OPTIMIZED AND NON-OPTIMIZED DESIGN EXAMPLE RESULTS

# This section contains:

- The ISDS MathConnex worksheet
- The Excel spreadsheet of the characteristics for the DD-13A Payload #2
- The Initial Value Mathcad Math Model
- The Matlab Optimizer detailed output
- The Final Design Synthesis Mathcad Math Model
- The Non-Optimized MathConnex worksheet
- The Non-Optimized MIT Math Model

## INTEGRATED SHIP DESIGN SYSTEM



# DD13A PAYLOAD #2

PAYLOAD NAME	WT KEY	WT	VCG	VCG	AREA	HULL	DICHS	CRUISE	BATTLE
•			DATUM	FT AD	KEY	FT2	FT2	KW	KW
STEEL LANDING PAD (ON HULL) - SH-60 CAPABLE  128 CELL VLS ARMOR - LEVEL III HY-80	W111	10.7	36.717	0.20	NONE	0	0	0	0
VGAS HY-80 ARMOR LEVEL III	1	-	<del>                                     </del>	<del> </del>	<del> </del>				
SQS-53C 5M BOW SONAR DOME	W165	85.7		-1.5	NONE	0		0	0
GROUP 100	WP100	96.4				0	0	0	0
CIC W/UYO-44 & 2X LSD	W410	19.34	0	35.58	A1131	1953	448	45.03	45.03
NAVIGATION SYSTEM	W420	7.29		14.00		0	848.3	55.99	53.5
ADVANCED DIGITAL C4I (JTIDS/LINK 16/LINK22/TADIXS/TACINTEL)	W440	37.91		-46.84		1230.6		35.76	39.67
SPS-87 SURFACE SEARCH RADAR ADVANCED IFF	W451 W455	2.32		-10.00 -5.00		0	70	8	0
SPY-1D MFAR - SINGLE TRANSMITTER	W400	2.52	- 01	*5.00	NONE	-		3.2	4
X-BAND RADAR AND FOUNDATION, 110 FT ABOVE BL	W456	4,11		113.00		0	0	220.16	220.16
SQS-53C 5M BOW SONAR DOME ELEX LIGHTWEIGHT BROADBAND VARIABLE DEPTH SONAR (LBVDS)	W463	57.7	0	9.3	A1122	1942	0	39	39
SSQ-61 BATHYTHERMOGRAPH	+	-				-			
SQQ-28 SONOBUOY PROCESSING SYSTEM	W466	5.26	51	-44.86	NONE	0	0	1,15	1.15
ADVANCED INTEGRATED ELECTRONIC WARFARE SYSTEM (AIEWS)									
AN/SLQ-25A NIXIE MK36 DLS W/6 LAUNCHERS	W473 W474	0.24		-6.20		200	0	3	4.2
MINEHUNTING AUV / REMOTE MINEHUNTING SYSTEM	W4/4	0.96	33.4	5.39	NONE	0	0	2.4	2.4
AEGIS-BASED VGAS GFCS (UYO-21 + UYK-44)									
AN/SWG-1 HARPOON CONTROL IN CIC .	W482	1.14	38.31575	10.80	NONE	0	0	Ö	4.9
MK99 GMFCS W/CEC W/3 SPG-62 ILLUM VLS WEAPON CONTROL SYSTEM	W482	0.7	38.31575	-7.80	A1220	56	310	13.62	19.69
ADVANCED TACTICAL WEAPON CONTROL SYSTEM (ATWCS)	17402	0.7	30.313/5	-7.80	AIZZU	- 56	310	13.82	19.69
ASW CONTROL SYSTEM W/SSTD [ASWCS]									
COMBAT DF	W495	8.26		21.00		0	448	15.47	19.34
ELECTRONIC TEST & CHECKOUT GROUP 400	W499 WP400	148.14	38.31575	10.80	NONE	5381.6	3394.7	442.78	453.04
	177.400	140.14			<del> </del>	5301.6	3384.7	442.78	453.04
FWD 64-CELL VLS MAGAZINE DEWATERING SYSTEM	W529	7	35.0585	-0.46	NONE	0	0	0	0
AFT 64-CELL VLS MAGAZINE DEWATERING SYSTEM									
COOLING EQUIPMENT FOR SPY-1D COOLING ADJUSTMENT FOR X-BAND RADAR	W532	4.43	0	9.81	A1121	47.00			
LAMPS MKIII AVIATION FUEL SYS	W532	4.86		-11.00		47.85 30	0	13.64	13.64
LAMPS MKIII RAST/RAST CONTROL/HELO CONTROL	W588	31.1		-1.60		219	33	4.4	4.4
GROUP 500	WP500	47.39				296.85	33	20.04	20.94
SQS-53C 5M BOW SONAR DOME HULL DAMPING	W636				Neve				
LAMPS MKIII AVIATION SHOP AND OFFICE	W636 W665	1.04	35.0585	-2.5 -4.50		194	75	0	0
GROUP 600	WP600	7.74		50	2.500	194	75	0	0
10.10 AFF 184									
VGAS 155 MM  2X HARPOON SSM QUAD CANNISTER LAUNCHERS	W721	4,1	33.4	1.17	A1220				
FWD MK41 VLS 64-CELL	W721	107.72	35.0585	1.14		128	0	69.65	1.6 69.65
AFT MK41 VLS 64-CELL									
2X MK32 SVTT ON DECK GROUP 700	W750	5.55	33.4	2.20	A1244	0	368	2	5
31001 100	W/	117.37				128	368	71.65	76.25
VGAS AMMO - 680 RDS									
HARPOON MISSILES 8 RDS IN CANNISTERS	WF21	3.78	33.4	5.00	NONE	0	0	0	0
AFT MK 41 LAUNCHER MISSILE LOADOUT (ESSM, SM. VLA, TLAM, ATACMS) FWD MK 41 LAUNCHER MISSILE LOADOUT (ESSM, SM, VLA, TLAM, ATACMS)	WF21	144	35,0585	0.01	41000				
MK46 LWT ASW TORPEDOES - 6 RDS IN SVTT TUBES	WF21	1.36	35.0585	0.34 2.50		1420 368	720	0	0
MK36 DLS SRBOC CANNISTERS - 100 RDS	WF21	2.2	33.4	11.60		0	0	0	0
SMALL ARMS AMMO - 7.62MM + 50 CAL + PYRO	WF21	4.1	33.4	-6		0	0	0	0
LAMPS MKIII 18 X MK46 TORP & SONOBUOYS & PYRO  LAMPS MKIII 2 X SH-60B HELOS, UAV'S, AND HANGAR (BASED)	WF22 WF23	9.87		4.80		0	588	0	0
LAMPS MKIII AVIATION SUPPORT AND SPARES	WF26	9.42		5.00		357	3406	5.6	5.6 0
BATHYTHERMOGRAPH PROBES									
GROUP WF20	WF20	187.46				2145	4714	5.6	5.6
LAMPS MKIII: AVIATION FUEL (JP-6)	WF42	62.0		40.7	41000				
Some V middle ATTRITON FOLL (MT-O)	WF42	63.8	0	10.4	A1380	0	0	0	Ó
VARIABLE MILITARY PAYLOAD (WF20 + WF42)	WVP	251.26							
ARMAMENT (WP500,WP600,W7,WF20)						2763.9	5190		
								KWP	
TOTAL PAYLOAD	WP	668.3				8145.5	8584.7	540.07	555.83
	<del> </del>								
DATUM DEFINITIONS:	1								
	DEPTHO	47.445		VCG P:	24.78				
	DEPTH3	43.232		VCG VP:	29.61				
	DEPTH6.5 DEPTH10	38.316			-				
	DEPTH15	35.059				-			
	DEPTH20	36.717							
	BL	0							
	MAST BAS	· 51							

# MIT MATH MODEL: INITIAL VALUES

$$hp = \frac{33000 \cdot ft \cdot lbf}{min} \qquad knt = 1.69 \cdot \frac{ft}{sec}$$

lton≡2240·lb

# L INPUT:

Primary Input Variables Are Highlighted in Yellow and Must Be Checked for Consistency Between MATHCAD Elements.

#### I1. Requirements:

Payload: (From Excel Payload Spreadsheet ) Wp:=in0, lton

variable:

 $W_{VP} := in0_2 \cdot lton$ 

Payload VCG:

 $VCG_P := in0_3 \cdot ft$ 

Variable Payload VCG:  $VCG_{VP} := in0_A \cdot ft$ 

Command and Surveillance Payload: (W<sub>400</sub> less 420 and 430)

 $W_{P400} := in0_5 \cdot lton$ 

Armament (all W 700):

 $W_7 := in0_6$  lton

Armor: W<sub>164</sub> := in0<sub>7</sub>·lton

Mission handling/support:  $W_{P500} := in0_8 \cdot lton$ 

Ordnance:  $W_{F20} := in0_{10}$ ·lton (incl helo wt, WF23)

Helo Fuel:

 $W_{F42} := in0_{11} \cdot lton$ 

Helo's:

N HELO := 2

W F23 := 12.73 lton

Payload Cruise Electric Power Requirement:

 $kW_{PAY} := in0_{12} \cdot kW$ 

Payload Deck Areas:

Deckhouse:

**C&D:**  $A_{DPC} := in0_{13} \cdot ft^2$ 

(W400)

Armament:  $A_{DPA} := in0_{14} \cdot ft^2$ 

(W500, W600, W700, WF20)

Hull:

**C&D:**  $A_{HPC} := in0_{15} \cdot ft^2$ 

(W400)

Armament:  $A_{HPA} := in0_{16} \cdot ft^2$ 

(W500, W600, W700, WF20)

Manning:

Officers: NO =15

Enlisted: N<sub>F</sub>:=135

Total:  $N_T := N_E + N_O N_T = 150$ 

Average deck height:

H<sub>DK</sub> :=9 ft

Sustained Speed:

 $V_{S} = 27.4 \text{knt}$ 

(Use Figure 3 as a guide in selecting V s)

**Endurance Speed:** 

 $V_e = 20 \, \text{sknt}$ 

Range: E = 7500 eknt.hr

Stores period:

 $T_S := 45 \cdot day$ 

Sonar Dome/Appendages: SQS-53C; 215ft<sup>2</sup>, 87.9lton,-1.2ft,85.7lton SQS-56; 27ft <sup>2</sup>,13.94lton,-3.1ft,7.43lton

 $A_{SD}:=in2_{c}\cdot ft^{2}$ 

 $W_{A98} := 87.9 \text{ Iton}$  VCG  $_{A98} := -1.2 \text{ ft structure}$ :  $W_{A65} := 85.7 \text{ Iton}$ 

Fin Stabilizers:

(for one pair, electric power requirement = 50 kW)

kW fins :=0 kW

Hull Material: (OS: C HMAT=1.0; HTS: C HMAT=0.93)

C +IMAT := .93

CPS: (W CPS=30lton):

 $W_{CPS} := 30$  lton (ie. no CPS)

Machinery:

Number of propellers =

 $N_p := 2$   $C_{PROPD} := if(N_p > 1, 1.0, 1.2)$   $C_{PROPD} = 1$ 

Aux Propulsion (APU):

W 237 :=0 Iton

VCG 237 := 0 ft (Weight=14.2lton, VCG=3.5ft)

Propulsion Engines (PE) - standard LM2500's; Generator engines; DDA 501-K34

Number and brake horsepower of propulsion engines:

 $N_{PENG} := 4$   $P_{RPENG} := 26450 \cdot hp$ 

Inlet/exhaust Xsect area for PE:

 $A_{IE} := 135.2 \text{ ft}^2$   $A_{PIE} := N_{PENG} \cdot A_{IE}$   $A_{PIE} = 540.8 \text{ eft}^2$ 

Deckhouse decks impacted by propulsion and generator inlet/exhaust:

N DIE := I

Hull decks impacted by propulsion inlet/exhaust:

N HPIE :=0

Machinery Box:

H<sub>MBMIN</sub> := 22 ft L<sub>MB</sub> := 40 ft

 $C_{P} = 0.59$   $C_{MB} := \frac{L_{MB}}{t_{WT}}$   $C_{MB} = 0.081$   $C_{PMB}$  from Fig. 10:  $C_{PMB} := .998$ 

Ship Service Generators:

 $N_G := 3$ 

 $kW_G := 3000 \ kW$ 

Hull decks impacted by generator inlet/exhaust:

Specific fuel rate for generator engines:

FR G :=  $\frac{288}{2.54} \frac{lb}{kW.hr}$  FR G = 0.085  $\frac{lb}{hr.hr}$ 

Inlet/exhaust X-sect area for gen:

 $A_{GIE} := 38.4 \cdot ft^2$   $A_{eIE} := N_{G} \cdot A_{GIE}$   $A_{eIE} = 115.2 \cdot ft^2$ 

#### IL GROSS CHARACTERISTICS

**Hull Principle Characteristics:** 

(see Figures 5 and 6)

Adjust in Summary Section at

LWL = 495.301 oft B = 55.745 oft

 $C_P = 0.59$   $C_X = 0.85$ 

end of file

deckhouse volume:

 $V_D = 97715 \, eft^3$ 

C DHMAT := 2

(Deckhouse Material: Aluminum - C DHMAT=1; Steel - C DHMAT=2)

#### II1. Complete Principle Characteristics:

Choose Payload Weight Fraction from Figure 4 and Calculate Full Load Weight (1st Iteration only, set  $W_{FL}=W_{FL1}$  in Summary section at end of file).

$$F_P := .1$$
  $W_{FL1} := \frac{W_P}{F_P}$   $W_{FL1} = 6683$  elton

Specify Full Load Weight (subsequent iterations set W FL=WT from prior iteration in Summary at end of file):

$$W_{FI} = 6683$$
 elton

Calculate Full Load Displacement and Volume at LWL:

$$\Delta_{FL} := W_{FL}$$
  $V_{FL} := \Delta_{FL} \cdot 35 \cdot \frac{\text{ft}^3}{\text{Iton}}$   $V_{FL} = 233905 \cdot \text{ft}^3$ 

Calculate Draft (LWL):

$$T := \frac{V_{FL}}{C_{P} \cdot C_{X} \cdot LWL \cdot B}$$
 
$$T = 16.892 \cdot \text{ft}$$

II2. Calculate Displacement to Length Ratio and Compare to Figure 5:

$$C_{\Delta L} := \frac{\Delta_{FL}}{\left(\frac{LWL}{100}\right)^3} \qquad C_{\Delta L} = 55 \frac{lton}{ft^3}$$
 (45-65)

II3. Calculate Speed to Length Ratio and C v:

$$R_{VL} := \frac{V_S}{\sqrt{LWL}}$$
  $R_{VL} = 1.213 \frac{knt}{ft^5}$   $C_V := \frac{V_{FL}}{LWL^3}$   $C_V = 0.001925$ 

II4. Calculate Beam to Draft Ratio and Compare to Tables 1-4:

$$C_{BT} := \frac{B}{T}$$
  $C_{BT} = 3.3$  (2.8-3.7)

II5. Calculate Length to Beam Ratio:

$$C_{LB} := \frac{LWL}{R}$$
  $C_{LB} = 8.885$  (7.5-10)

#### III. ENERGY (Uses Taylor Standard Series (TSS)

References: DDS 051-1 and Taylor Reanalysis by Gertler

III1. Calculate TSS Resistance:

III1.1 Estimate propeller diameter and frontal area of ship:

III1.2 Seawater propereties:

$$T_{SW} := 59$$
  $\rho_{SW} := 1.9905 \cdot \frac{\text{slug}}{\text{ft}^3}$   $\nu_{SW} := 1.2817 \cdot 10^{-5} \cdot \frac{\text{ft}^2}{\text{sec}}$ 

III1.3 Resistance calculation parameters:

$$C_{D} = 0.59$$

Use Figure 7 with C 
$$_{\rm P}$$
 and C  $_{\rm BT}$  for TSS wetted surface coeficient:

$$C_{BT} = 3.3$$

$$S_{TSS} := C_{STSS} \cdot V_{FL}^{.5} \cdot LWL^{.5}$$
  $S_{TSS} = 27296.301 \text{ eft}^2$ 

$$S_{TSS} = 27296.301 \, \text{eft}^2$$

$$S_S := S_{TSS}$$

Use Figure 8 or 9 with LWL for Appendage Drag Coeficient:

$$C_{\text{DAPP}} := 2.85 \cdot \frac{\text{hp} \cdot 10^{-3}}{\text{ft}^2 \cdot \text{knt}^3}$$

 $C_{STSS} := 2.536$ 

Air Drag Coeficient:

$$C_{AA} := .7$$

Power Margin Factor (margin for concept design = 10%):

$$PMF := 1.05$$

III1.4 Use range of ship speeds for speed to length ratios (R i). Reynold's numbers (RN i) and ITTC friction (RF i):

$$i := 1...7$$
 V. :=  $i \cdot 5 \cdot knt$ 

$$V_6 := V_S \qquad V_6 = 27 \text{ eknt}$$

$$V_4 := V_e$$
  $V_4 = 20 \text{ sknt}$ 

 $R_{F_i} := .5 \cdot \left[ \rho_{SW} \cdot S_{S'} \left( V_i \right)^2 \cdot \left( C_A + C_{F_i} \right) \right]$ 

$$R_i := \frac{V_i}{\sqrt{LWL}}$$

$$R_{N_i} := LWL \cdot \frac{V_i}{v_{SW}}$$

$$R_{i} := \frac{V_{i}}{\sqrt{LWL}} \qquad R_{N_{i}} := LWL \cdot \frac{V_{i}}{v_{SW}} \qquad C_{F_{i}} := \frac{.075}{\left(\log(R_{N_{i}}) - 2\right)^{2}}$$

# III1.5 Use Gertler with C $_{P}$ , $C_{V}$ , $R_{i}$ and $C_{BT}$ to interpolate for $C_{R}$ and calcualte TSS resistance:

Form Factor:

$$FF := \frac{4}{3} \cdot (C_{BT} - 3)$$
  $FF = 0.4$ 

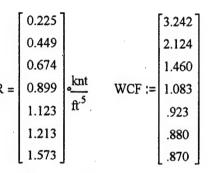
$$C_{RTSS_{i}} := C_{R3.00_{i}} + FF \cdot \left(\frac{C_{R3.75_{i}} - C_{R2.25_{i}}}{2}\right) + FF^{2} \cdot \left(\frac{C_{R2.25_{i}} + C_{R3.75_{i}}}{2} - C_{R3.00_{i}}\right)$$

$$C_{RTSS} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0.001 \\ 0.002 \\ 0.004 \\ 0.004 \end{bmatrix}$$

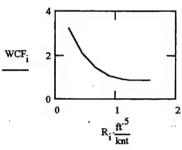
$$R_{RTSS_{i}} := .5 \cdot \left[ \rho_{SW} \cdot S_{S} \cdot (V_{i})^{2} \cdot C_{RTSS_{i}} \right]$$

$$R_{RTSS} = \begin{bmatrix} 765.82 \\ 3063.279 \\ 7918.902 \\ 31346.623 \\ 89035.271 \\ 200574.47 \\ 418973.994 \end{bmatrix}$$
elbi

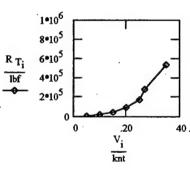
## III2 Calculate Bare Hull Ship Resistance - Worm Curve data from ASSET:



 $R_{T_i} := R_{F_i} + R_{R_i}$ 



$$R_{R} = \begin{bmatrix} 2482.788 \\ 6506.404 \\ 11561.597 \\ 33948.392 \\ 82179.556 \\ 176505.533 \\ 364507.375 \end{bmatrix} \text{ olbf } R_{T} = \begin{bmatrix} 6881.321 \\ 22915.697 \\ 47080.19 \\ 95434.858 \\ 176335.081 \\ 285578.054 \\ 543664.612 \end{bmatrix}$$



# III3. Total Ship Effective Horsepower:

704.137 2169.969  $P_{EBH_i} := R_{T_i} V_i$ hull: 5864.906 13545.74 23692.594  $C_{SD} := .28$ 58468.658

105.722

appendage: 
$$P_{EAPP_{i}} := (LWL \cdot D_{P} \cdot C_{DAPP} + .5 \cdot C_{SD} \cdot p_{SW} \cdot A_{SD}) \cdot (V_{i})^{3}$$

$$\frac{P_{EAPP_{i}}}{hp} = \begin{bmatrix} 95.946 \\ 767.565 \\ 2590.531 \\ 6140.518 \\ 11993.199 \\ 15107.977 \\ 32909.338 \end{bmatrix}$$
air: 
$$P_{EAA_{i}} := .5 \cdot C_{AA} \cdot A_{W} \cdot p_{A} \cdot (V_{i})^{3}$$

$$\frac{P_{EAA}}{hp} = \begin{bmatrix} 2.583 \\ 20.667 \\ 69.75 \\ 165.334 \\ 322.918 \\ 406.784 \\ 886.088 \end{bmatrix}$$

$$P_{ET_{i}} := P_{EBH_{i}} + P_{EAPP_{i}} + P_{EAA_{i}}$$

$$\frac{P_{ET}}{hp} = \begin{bmatrix} 204.251 \\ 1492.368 \\ 4830.25 \\ 12170.758 \\ 25861.858 \\ 39207.355 \\ 92264.084 \end{bmatrix}$$

$$\frac{V_{i}}{knt}$$

$$\frac{V_{i}}{knt}$$

$$EHP_{i} := PMF \cdot P_{ET_{i}}$$

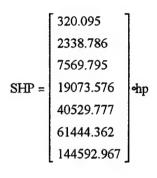
$$\frac{EHP_{i}}{1566.987} = PMF \cdot P_{ET_{i}}$$

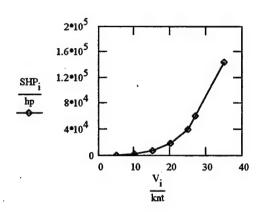
$$\frac{P_{ET}}{hp} = \begin{bmatrix} 204.251 \\ 1492.368 \\ 4830.25 \\ 12170.758 \\ 25861.858 \\ 39207.355 \\ 92264.084 \end{bmatrix}$$

### III4. Shaft Horsepower:

Approximate Propulsive Coeficient (PC):

$$SHP_i := \frac{EHP_i}{PC}$$





Endurance Shaft Horsepower:

$$P_e := SHP_A$$

$$P_e = 19073.576 \circ hp$$

Sustained Speed Installed Shaft Horsepower Required (Allows for fouling and sea state):

$$P_S := SHP_A$$

$$P_S := SHP_6$$
  $P_S = 61444.362 \text{ shp}$ 

$$P_{IREQ} := 1.25 P_{S}$$
  $P_{IREQ} = 76805.452 \text{ ohp}$ 

Actual installed SHP must be greater than P IREO

 $P_{IBRAKE} := N_{PENG} \cdot P_{BPENG}$   $P_{IBRAKE} = 105800 \text{ ohp } \eta := .97$ 

$$P_{IBRAKE} = 105800 \text{ shp } \eta := .97$$

$$P_I := \eta \cdot P_{IBRAKE}$$
  $P_I = 102626 \text{ shp}$ 

(
$$P_{I}$$
 must be  $> P_{IREQ}$ )  $P_{IREQ} = 76805.452 \text{ shp}$ 

(P<sub>I</sub> must be > P<sub>IREQ</sub>) 
$$P_{IREQ} = 76805.452 \text{ ehp}$$
  $ERR_{POWER} := \frac{P_{I} - P_{IREQ}}{P_{IREQ}}$   $ERR_{POWER} = 0.336$ 

III5. Estimate Propulsion Fuel Required:

Reference: DDS 200-1 "Calculate of Surface Ship Endurance Fuel"

Average Endurance Brake SHP Required (Allows for fouling and sea state):

$$P_{eBAVG} := 1.1 \frac{P_e}{\eta}$$
  $P_{eBAVG} = 21629.828 \circ hp$ 

Specific fuel rate for propulsion engines: (GT; FR for diesel = .327)

FR := 1.97 
$$\cdot \frac{1b}{hp^{.85} \cdot hr} \cdot P_{eBAVG}^{-.15}$$
 FR = 0.441 ×

Margin for instrumentation and machinery differences, f(P \_ /P\_I):

Specified fuel rate:

$$FR_{SP} := f_1 \cdot FR$$

Average fuel rate allowing for plant deterioration:

FR AVG := 
$$1.05 \cdot \text{FR}$$
 SP FR AVG =  $0.481 \cdot \frac{\text{lb}}{\text{hp} \cdot \text{hr}}$ 

Burnable propulsion endurance fuel weight:

$$W_{BP} := \frac{E}{V_e} \cdot (P_{eBAVG} \cdot FR_{AVG})$$
  $W_{BP} = 1742.879 \cdot \text{lton}$ 

Tailpipe allowance and propulsion endurance fuel:

$$W_{FP} := \frac{W_{BP}}{TPA}$$

$$W_{FP} = 1834.609$$
 •lton

Allow for expansion and tank structure in required propulsion tank volume:

$$\gamma_F := 43 \cdot \frac{ft^3}{1ton}$$

$$\gamma_F := 43 \cdot \frac{\text{ft}^3}{\text{Iton}}$$
  $V_{FP} := 1.02 \cdot 1.05 \cdot \gamma_F \cdot W_{FP}$   $V_{FP} = 84489.268 \text{ eft}^3$ 

$$V_{FP} = 84489.268 \, \text{eft}^3$$

#### III6. Estimate electric load.

Reference: DDS 310-1

Estimate Maximum Functional Load based on parametrics for WINTER cruise condition:

Propulsion:

$$kW_P := .00466 \frac{kW}{hp} \cdot P_{IBRAKE}$$

Steering:

$$kW_S := .00583 \cdot \frac{kW}{A^2} \cdot LWL \cdot T$$

Lighting:

$$kW_L := .0002053 \cdot \frac{kW}{R^3} \cdot 1.8 \cdot LWL \cdot T \cdot B$$

$$kW_L = 172.357 \text{ ekW}$$

Miscellaneous:

Heating:

$$kW_H := .0013 \cdot \frac{kW}{e^3} \cdot 1.25 \cdot LWL \cdot T \cdot B$$

Ventilation:

$$kW_V := .19 \cdot (kW_H + kW_P) + kW_{CPS}$$
  $kW_V = 455.96 \cdot kW$ 

$$kW_V = 455.96 \text{ } \text{kW}$$

Air Conditioning:

$$kW_{AC} := .67 \cdot \left( .1 \cdot kW \cdot N_{T} + .0015 \cdot \frac{kW}{R^3} \cdot .47 \cdot 1.3 \cdot LWL \cdot T \cdot B + .1 \cdot kW_{P} \right)$$

 $kW_{AC} = 329.485 \text{ ekW}$ 

Aux Boiler and FW: (electric boiler)

$$kW_B := .94 \cdot N_T \cdot kW$$

$$kW_B = 141 \text{ ekW}$$

Firemain:

$$kW_{F} := .0001 \frac{kW}{\Delta^{3}} \cdot 1.8 \cdot LWL \cdot T \cdot B$$
  $kW_{F} = 83.954 \cdot kW$ 

Unrep and handling:

$$kW_{RH} := .00002 \cdot \frac{kW}{n^3} \cdot 1.25 \cdot LWL \cdot T \cdot B$$
  $kW_{RH} = 11.66 \cdot kW$ 

Aux Machinery:

$$kW_A := .22 \cdot N_T \cdot kW + kW_{fins}$$

 $kW_A = 33 kW$ 

Services and Work Spaces:

$$kW_{SERV} := .35 \cdot N_{T} \cdot kW$$

# Non-Payload Functional Load:

 $kW_{NP} := kW_{P} + kW_{S} + kW_{L} + kW_{M} + kW_{H} + kW_{V} + kW_{AC} + kW_{B} + kW_{F} + kW_{RH} + kW_{A} + kW_{SER}$ Maximum Functional Load:

$$kW_{MFL} := kW_{PAY} + kW_{NP}$$

MFL with margins: (design,growth):

# **Installed Electrical Power Required:**

Power available per generator:

$$kW_G = 3000 *kW$$

$$kW_{GREQ} := \frac{kW_{MFLM}}{(N_{G}-1).9}$$
  $kW_{GREQ} = 2532.648 \text{ kW}$ 

24 hour electrical load:

$$ERR_{KW} := \frac{kW_{G} - kW_{GREQ}}{kW_{GREQ}}$$

$$kW_{24} := .5 \cdot (kW_{MFL} - kW_{P} - kW_{S}) + .8 \cdot (kW_{P} + kW_{S})$$
  $kW_{24} = 1745.447 \cdot kW$ 

with margin (design):

$$kW_{24AVG} := 1.2 kW_{24}$$

$$kW_{24AVG} := 1.2 kW_{24}$$
  $kW_{24AVG} = 2094.537 kW$ 

FR 
$$_{G} = 0.113 \frac{\text{lb}}{\text{kW} \cdot \text{hr}}$$

Margin for instrumentation and machinery differences,  $f(P_I)$ :

Specified fuel rate:

$$FR_{GSP} := f_{le} \cdot FR_{G}$$

Average fuel rate allowing for plant deterioration:

FR 
$$GAVG = 0.124 \circ \frac{lb}{kW \cdot hr}$$

FR 
$$_{GAVG} = 0.124 \circ \frac{lb}{kW \cdot hr}$$
 FR  $_{GAVG} = 0.092 \circ \frac{lb}{hp \cdot hr}$ 

# III8. Estimate Electrical and Total fuel Required

Burnable electrical endurance fuel weight:

$$W_{Be} := \frac{E}{V_e} (kW_{24AVG} \cdot FR_{GAVG})$$
  $W_{Be} = 43.416 \cdot elton$ 

$$W_{Be} = 43.416$$
 olton

Tailpipe allowance and electrical endurance fuel:

$$W_{Fe} := \frac{W_{Be}}{TPA}$$
  $W_{Fe} = 45.701$  elton

TPA := .95 (shallow tanks)

Allow for expansion and tank structure in required electrical fuel tank volume:

$$V_{Fe} := 1.02 \cdot 1.05 \cdot \gamma_{F} \cdot W_{Fe}$$
  $V_{Fe} = 2104.684 \text{ eft}^3$ 

Total ship fuel: (DFM)

$$W_{F41} := W_{FP} + W_{Fe}$$
  $W_{F41} = 1880.311 \text{ olton}$   
 $V_F := V_{FP} + V_{Fe}$   $V_F = 86593.952 \text{ eft}^3$ 

# IV. Space Estimate

IVA. Available Space

IVA1. Underwater Hull Volume Available

$$V_{HUW} := V_{FL}$$
  $V_{HUW} = 233905 \text{ e} \text{ ft}^3$ 

IVA2. Sheer Line. (3 criteria)

- 1) Keep deck edge above water at 25 degree heel
- 2) Longitudinal strength

$$H_{MRMIN} = 22 \, \text{eft}$$

$$\mathbf{M} = \begin{bmatrix} 28.599 \\ 33.02 \\ 22 \end{bmatrix}$$

$$D_{10MIN} := max(M)$$

$$D_{10MIN} = 33.02 \text{ eft}$$

$$D_{10} := D_{10MIN} + 1 \cdot \text{ft}$$
  $D_{10} = 34.0$ 

$$D_{0MIN} := 1.011827 \cdot T - 6.36215 \cdot \frac{10^{-6}}{ft} \cdot LWL^2 + 2.780649 \cdot 10^{-2} \cdot LWL + T \quad D_{0MIN} = 46.196 \cdot ft \quad D_{0} := D_{0MIN}$$

$$D_0 := D_{0MIN}$$

D<sub>20MIN</sub> := .014·LWL·
$$\left(2.125 + 1.25 \cdot \frac{10^{-3}}{\text{ft}} \cdot \text{LWL}\right) + T$$
 D<sub>20MIN</sub> = 35.921 oft D<sub>20</sub> := D<sub>20MIN</sub>

$$D_{20MIN} = 35.921$$
 off  $D_{20} := D_{20MIN}$ 

IVA3. Above-Water Hull Volume

$$F_0 := D_0 - T$$

$$F_{10} := D_{10} - T$$
  $F_{20} := D_{20} - T$ 

$$A_{PRO} := LWL \cdot \frac{F_0 + 4 \cdot F_{10} + F_{20}}{6}$$
  $F_{AV} := \frac{A_{PRO}}{LWL}$   $F_{AV} = 19.474 \text{ eft}$ 

$$F_{AV} := \frac{A_{PRO}}{LWL}$$

$$F_{AV} = 19.474$$
 oft

$$D_{AV} := F_{AV} + T$$
  $D_{AV} = 36.366 \text{ of }$ 

$$D_{AV} := F_{AV} + T$$
  $D_{AV} = 36.366 \text{ eft}$   $cubic #: CN := \frac{LWL \cdot B \cdot D_{AV}}{10^5 \cdot ft^3}$   $CN = 10.041$ 

$$C_W := .236 + .836 \cdot C_P$$
  $C_W = 0.729$ 

$$C_{W} = 0.72$$

flare factor: 
$$f_{\mathbf{f}} := .714599 + .18098 \cdot \frac{D_{\mathbf{A}\mathbf{V}}}{T} - .018828 \cdot \left(\frac{D_{\mathbf{A}\mathbf{V}}}{T}\right)^2 \mathbf{M}_{\mathbf{f}} := \begin{bmatrix} f_{\mathbf{f}} \\ 1 \end{bmatrix} \qquad f_{\mathbf{f}} := \max(\mathbf{M}_{\mathbf{f}}) \\ f_{\mathbf{f}} = 1.017$$

$$V_{HAW} := LWL \cdot B \cdot F_{AV} \cdot C_{W} \cdot f_{f}$$

$$V_{HAW} = 398749.111 \, \text{el}^3$$

IVA4. Total Hull Volume.

$$V_{HT} := V_{HUW} + V_{HAW}$$
  $V_{HT} = 632654.111 \text{ eft}^3$ 

IVA5. Size Deck House:

$$V_{DMAX} := .0025 \cdot LWL^3$$
  $V_{DMAX} = 303772.727 \text{ eft}^3$ 

$$V_{DMIN} := .0005 \cdot LWL^3$$
  $V_{DMIN} = 60754.545 \text{ eft}^3$   $V_D = 97715 \text{ eft}^3$ 

IVA6. Calculate Total Ship Volume

$$V_T := V_{HT} + V_D$$
  $V_T = 730369.111 \text{ et}^3$ 

IVB. Space Requirement

IVB1. Machinery Box (assumed near midships) 
$$B_{MB} := B B_{MB} = 55.745 \text{ eft}$$

$$H_{MB} := D_{10}$$
  $L_{MB} = 40 \text{ eft}$   $A_{MB} := B \cdot T \cdot C_{X} + B \cdot (H_{MB} - T)$   $A_{MB} = 1755.202 \text{ eft}^{2}$ 

Calculate Machinery Box Volume:

$$V_{MB} := L_{MB} \cdot A_{MB} \cdot C_{PMB}$$
  $V_{MB} = 70067.665 \cdot eft^3$   $V_{AUX} := 1.2 \cdot V_{MB}$   $V_{AUX} = 84081.198 \cdot eft^3$ 

IVB2. Tankage

Helo:

Helo fuel weight from Payload Spreadsheet: 
$$W_{F42} = 63.8$$
 elton

Allow for tank structure and expansion: 
$$\gamma_{HF} := 43. \cdot \frac{ft^3}{lton}$$

$$V_{HF} := 1.02 \cdot 1.05 \cdot W_{F42} \cdot \gamma_{HF}$$
  $V_{HF} = 2938.181 \cdot \text{eft}^3$ 

Lube Oil:

**LO weight:** 
$$W_{F46} := 7.2 \cdot lton$$

Allow for tank structure and expansion: 
$$\gamma_{LO} := 39 \cdot \frac{\hat{R}^3}{ltor}$$

$$V_{LO} := 1.02 \cdot 1.05 \cdot W_{F46} \cdot \gamma_{LO} \quad V_{LO} = 300.737 \text{ eft}^3$$

Potable Water:

Water weight: 
$$W_{F52} := N_{T} \cdot .15 \cdot lton$$
  $W_{F52} = 22.5 \cdot lton$ 

Allow for tank structure:  

$$V_W := 1.02 \cdot W_{F52} \cdot \gamma_W$$
  $V_W = 826.2 \cdot \text{ft}^3$ 

$$V_{SEW} := N_{T} \cdot 2 \cdot \Omega^{3}$$

$$V_{SEW} := N_{T} \cdot 2 \cdot \hat{\pi}^{3}$$
  $V_{SEW} = 300 \text{ eft}^{3}$ 

$$V_{WASTE} := .005 \cdot V_{EI}$$

$$V_{WASTE} := .005 \cdot V_{FL}$$
  $V_{WASTE} = 1169.525 \text{ eft}^3$ 

$$V_{BAL} := .032 \cdot V_{FL} \qquad V_{BAL} := 0 \cdot \hat{\mathfrak{n}}^3$$

$$V_{BAI} := 0 ft^3$$

$$V_{BAL} = 0 \, eft^3$$

Total:

(for compensated system)

$$V_{TK} := V_F + V_{HF} + V_{LO} + V_{W} + V_{SEW} + V_{WASTE} + V_{BAL}$$
  $V_{TK} = 92128.595 \text{ eft}^3$ 

$$V_{TK} = 92128.595 \, \text{eft}^3$$

## IVB3. Payload Deck Areas

$$A_{DPR} := 1.15 \cdot A_{DPA} + 1.23 \cdot A_{DPC}$$
  $A_{DPR} = 10143.981 \cdot \text{eft}^2$ 

$$A_{DPR} = 10143.981 \, \text{eft}^2$$

$$A_{HPR} := 1.15 \cdot A_{HPA} + 1.23 \cdot A_{HPC}$$
  $A_{HPR} = 9797.796 \text{ eR}^2$ 

$$A_{HPR} = 9797.796 \, \text{eft}^2$$

#### IVB4. Living Deck Area

$$A_{COXO} := 225 \cdot ft^2$$
  $A_{DO} := 75 \cdot N_{O} \cdot ft^2$   $A_{DO} = 1125 \cdot ft^2$ 

$$A_{DO} = 1125 \, \text{eft}^2$$

$$A_{DL} := A_{COXO} + A_{DO}$$
  $A_{DL} = 1350 \text{ eft}^2$ 

$$A_{DL} = 1350 \, \text{eft}^2$$

$$A_{HAB} := 50 \cdot ft^2$$
  $A_{HL} := \left(A_{HAB} + \frac{LWL}{100} \cdot ft\right) \cdot N_T - A_{DL}$ 

$$A_{HL} = 6892.952 \, \text{eft}^2$$

#### IVB5. Hull Stores

$$A_{HS} := 300 \cdot ft^2 + .0158 \cdot \frac{ft^2}{lb} \cdot N_T \cdot 9 \cdot \frac{lb}{dav} \cdot T_S$$
  $A_{HS} = 1259.85 \circ ft^2$ 

$$A_{HS} = 1259.85 \text{ eft}^2$$

#### IVB6. Other Ship Functions

#### Deckhouse:

#### Maintenance:

$$A_{DM} := .05 \cdot (A_{DPR} + A_{DL})$$
  $A_{DM} = 574.699 \text{ eft}^2$ 

# **Bridge and Chartroom:**

$$A_{DB} := 16 \cdot \text{ft} \cdot (B - 18 \cdot \text{ft})$$

$$A_{DB} = 603.921 \text{ eft}^2$$

# Engine Inlet/Exhaust:

$$A_{DIE} := 1.4 \cdot N_{DIE} \cdot (A_{PIE} + A_{eIE})$$
  $A_{DIE} = 918.4 \text{ eft}^2$ 

# Hull:

# **Ship Functions:**

$$A_{HSF} := 2500 \cdot ft^2 \cdot CN$$

$$A_{HSF} = 25102.384 \, \text{eft}^2$$

# Engine Inlet/Exhaust:

$$A_{HIE} := 1.4 \cdot (N_{HPIE} \cdot A_{PIE} + N_{HeIE} \cdot A_{eIE})$$
  $A_{HIE} = 161.28 \text{ eft}^2$ 

# IVB7. Total Required Area and Volume

$$A_{HR} := A_{HPR} + A_{HL} + A_{HS} + A_{HSF} + A_{HIE}$$
  $A_{HR} = 43214.262 \text{ eft}^2$   
 $V_{HR} := H_{DK} \cdot A_{HR}$   $V_{HR} = 388928.354 \text{ eft}^3$ 

# Deckhouse:

$$A_{DR} := A_{DPR} + A_{DL} + A_{DM} + A_{DB} + A_{DIE}$$

$$A_{DR} = 13591.001 \, \text{eft}^2$$

$$V_{DR} := H_{DK} \cdot A_{DR} \quad V_{DR} = 122319.01 \text{ eff}^3$$

# Total:

$$A_{TR} := A_{HR} + A_{DR}$$
  $A_{TR} = 56805.263 \text{ eft}^2$   
 $V_{TR} := H_{DK} \cdot A_{TR}$   $V_{TR} = 511247.364 \text{ eft}^3$ 

# IVC. Space Balance

$$V_{D} = 97715 \text{ eft}^{3} \qquad V_{DR} = 122319.01 \text{ eft}^{3}$$

$$V_{HA} := V_{HT} - V_{MB} - V_{AUX} - V_{TK} \quad V_{HA} = 386376.654 \text{ eft}^{3} \qquad V_{HR} = 388928.354 \text{ eft}^{3}$$

$$V_{TA} := V_{HA} + V_{D} \qquad V_{TA} = 484091.654 \text{ eft}^{3} \quad > \quad V_{TR} = 511247.364 \text{ eft}^{3}$$

$$A_{HA} := \frac{V_{HA}}{H_{DK}} \qquad A_{HA} = 42930.739 \text{ eft}^{2} \qquad A_{HR} = 43214.262 \text{ eft}^{2}$$

$$A_{DA} := \frac{V_{D}}{H_{DK}} \qquad A_{DA} = 10857.222 \text{ eft}^{2} \qquad A_{DR} = 13591.001 \text{ eft}^{2}$$

$$A_{TA} := A_{DA} + A_{HA} \qquad A_{TA} = 53787.962 \text{ eft}^{2} \quad > \quad A_{TR} = 56805.263 \text{ eft}^{2}$$

$$ERR_{VOL} := \frac{V_{TA} - V_{TR}}{V_{TR}} ERR_{VOL} = -0.053117 \qquad ERR_{AREA} := \frac{A_{TA} - A_{TR}}{A_{TR}} ERR_{AREA} = -0.053117$$

## V. Weight

#### V1. Propulsion (200)

Basic Machinery: 
$$W_{BM} := P_{I} \cdot \frac{lb}{hp} \left[ 9.0 + 12.4 \cdot \left( P_{I} \cdot \frac{10^{-5}}{hp} - 1 \right)^{2} \right]$$
  $W_{BM} = 412.728 \text{ olton}$ 



$$W_S := .356 \cdot \frac{\text{lton}}{\text{ft}} \cdot LWL \cdot f_S$$
  $W_S = 88.164 \cdot \text{lton}$ 

(f<sub>S</sub>=0.5 for twin screws, 0.33 for single screw)

Props: (245)

5: 
$$W_{PR} := .05575 \cdot lb \cdot \left(\frac{D_P}{ft}\right)$$
  $N_P$   $W_{PR} = 36.613 \cdot lton$ 

Bearings:

(244)

$$W_B := .15 \cdot (W_S + W_{PR})$$
  $W_B = 18.717$  elton

**Total Shafting:** 

$$W_{ST} := W_{S} + W_{B} + W_{PR}$$

W <sub>ST</sub> = 143.493 •lton

**Total Propulsion:** 

$$W_2 := W_{BM} + W_{ST} + W_{237}$$

 $W_2 = 556.222$  elton

# V2. Electrical Plant (300)

$$W_3 := 50 \cdot lton + .03214 \cdot \frac{lton}{kW} \cdot N_G \cdot kW_G$$
  $W_3 = 339.26 \cdot lton$ 

#### V3. Command/Control/Surveillance (400)

Gyro/IC/Navigation (420, 430):

$$W_{IC} := 4.65 \cdot CN \cdot lton$$

Other/Misc Group 400:

$$W_{CO} := 2.24 \cdot CN \cdot lton$$

Cabling:

$$W_{CC} := .04 \cdot (W_{P400} + W_{IC} + W_{CO})$$
  $W_{CC} = 8.693$  elton

$$W_4 := W_{P400} + W_{IC} + W_{CO} + W_{CC} + W_{498}$$

$$W_4 = 313.915$$
 elton

#### V4. Auxiliary Systems (500)

aux steam (electric aux boiler):

hotel steam:

 $Q_{HS} := 15 \cdot N_T$  distiller:  $Q_{DS} := 6.5 \cdot N_T + 250$ 

 $W_{517} := .0013 \cdot \left(Q_{HS} + Q_{DS}\right) \cdot \text{lton}$   $W_{517} = 4.518 \cdot \text{lton}$  aux sys operating fluids:

 $W_{598} := .000075 \cdot V_T \cdot \frac{\text{iton}}{a^3}$ 

$$W_{AUX} := \left[ .000772 \cdot \left( \frac{V_T}{ft^3} \right)^{1.443} + 5.14 \cdot \frac{V_T}{ft^3} + 6.19 \cdot \left( \frac{V_T}{ft^3} \right)^{.7224} + 377 \cdot N_T + 2.74 \cdot \frac{P_I}{hp} \right] \cdot 10^{-4} \cdot lton + 113.8 \cdot lton$$

environmental support:

$$W_{593} := 10 \cdot \text{lton}$$
  $W_5 := W_{P500} + W_{517} + W_{593} + W_{CPS}$   $W_5 = 91.907 \cdot \text{lton}$ 

$$W_s = 91.907$$
 •Iton

#### V5. Outfit & Furnishings (600)

$$W_{OFH} := \left(31.4 + \frac{.0003187}{R^3} \cdot V_T\right) \cdot lton$$
  $W_{OFH} = 264.169 \cdot lton$ 

Personnel-related:

$$W_{OFP} := .8 \cdot (N_T - 9.5) \cdot lton$$

$$W_{OFP} = 112.4$$
 olton

$$W_6 := W_{OFP} + W_{P600}$$

$$W_6 = 120.14$$
 olton

#### V6. Structure (100)

$$W_{BH} := C_{HMAT} \cdot (1.68341 \cdot CN^2 + 167.1721 \cdot CN - 103.283) \cdot 100 \cdot M_{BH} = 1622.856 \cdot$$

$$\rho_{DH} := if(C_{DHMAT} = 1,.0007,.001429)$$

$$\rho_{DH} = 0.001$$

$$W_{DH} := \rho_{DH} \cdot \frac{lton}{R^3} \cdot V_{D}$$

$$W_{171} := .0688 \cdot \frac{1 \text{ton}}{9} \cdot LWL - 13.75 \cdot 1 \text{ton}$$

$$W_{171} = 20.327$$
 olton

$$W_{180} := .0675 \cdot W_{BM} + .072 \cdot (W_3 + W_4 + W_5 + W_7)$$
  $W_{180} = 89.956 \text{ elton}$ 

$$W_{180} = 89.956$$
 olton

$$W_1 := W_{BH} + W_{DH} + W_{171} + W_{180} + W_{165} + W_{164}$$

$$W_1 = 1958.474$$
 olton

# V7. Single Digit Weight Summary & Weight Balance:

$$i1 := 1, 2...7$$

$$W_{M24} := .1 \cdot \left( \sum_{i1} W_{i1} \right)$$
  $W_{M24} = 349.729 \cdot \text{lton}$ 

$$W_{M24} = 349.729$$
 olton

#### Lightship:

$$W_{LS} := \sum_{i=1}^{n} W_{i1} + W_{M24}$$
  $W_{LS} = 3847.017 \text{ elton}$ 

$$W_{LS} = 3847.017$$
 •lton

#### **Additional Loads:**

$$W_{F31} := N_T \cdot 9 \cdot \frac{1b}{day} \cdot T_S$$

$$W_{F31} = 27.121$$
 olton

$$W_{F32} := .0009598 \cdot \frac{lton}{day} \cdot T_S \cdot N_T$$

$$W_{F32} = 6.479$$
 elton

$$W_{F10} := 236 \cdot lb \cdot N_E + 400 \cdot lb \cdot (N_O + 1)$$
  $W_{F10} = 17.08 \cdot lton$ 

$$w_T \coloneqq w_{LS} + w_{F41} + w_{F42} + w_{F20} + w_{F46} + w_{F52} + w_{F31} + w_{F32} + w_{F10}$$

$$W_T = 6058.967$$
 olton

ERR WEIGHT := 
$$\frac{\Delta_{FL} - W_T}{W_T}$$
 ERR WEIGHT = 0.102993

# Weights Independent of the Design Variables:

$$W_{1ND} := W_{237} + W_3 + W_5 + W_6 + W_7 + W_{165} + W_{164} + W_{F31} + W_{F32} + W_{F10} + W_{F20}$$
 
$$W_{1ND} = 992.517 \text{ olton}$$

# VL Stability

### VI1. Calculate Light Ship Weight Group Moments:

Weight	<u>VCG</u>		<u>Product</u>
W <sub>BH</sub> = 1622.856 •lton	$VCG_1 := .527 \cdot D_{10}$	VCG <sub>1</sub> = 17.929 oft	$P_1 := W_{BH} \cdot VCG_1$
W <sub>DH</sub> = 139.635 •lton	$VCG_2 := D_{10} + 1.5 \cdot H_{DK}$	VCG <sub>2</sub> = 47.52 oft	$P_2 := W_{DH} \cdot VCG_2$
$W_{180} = 89.956$ •lton	$VCG_3 := .68 \cdot D_{10}$	VCG <sub>3</sub> = 23.134 oft	$P_3 := W_{180} \cdot VCG_3$
W <sub>171</sub> = 20.327 •lton	VCG <sub>4</sub> := 2.65·D <sub>10</sub>	VCG <sub>4</sub> = 90.153 oft	$P_4 := W_{171} \cdot VCG_4$
$P_{100} := P_1 + P_2 + P_3$	3+P <sub>4</sub>	VCG <sub>100</sub> :	$= \frac{P_{100}}{W_1}  \text{VCG}_{100} = 20.243 \text{ eft}$
$W_{BM} = 412.728$ olton	$VCG_5 := .5 \cdot D_{10}$	VCG <sub>5</sub> = 17.01 oft	$P_5 := W_{BM} \cdot VCG_5$
$W_{ST} = 143.493$ elton	$VCG_6 := 3.9 \cdot ft + .19 \cdot T$	VCG <sub>6</sub> = 7.11 at	$P_6 := W_{ST} \cdot VCG_6$
W <sub>237</sub> = 0 •lton	VCG <sub>7</sub> := VCG <sub>237</sub>	VCG <sub>7</sub> = 0 oft	$P_7 := W_{237} \cdot VCG_7$
$P_{200} := P_5 + P_6 + P_7$	$VCG_{200} := \frac{P_{200}}{W_2}$ $VC$	G <sub>200</sub> = 14.456 oft	
W <sub>3</sub> = 339.26 •lton	VCG <sub>8</sub> := .65 D <sub>10</sub>	VCG <sub>8</sub> = 22.113 aft	$P_8 := W_3 \cdot VCG_8$
$W_{IC}$ = 46.69 elton	VCG <sub>9</sub> :=D <sub>10</sub>	VCG <sub>9</sub> = 34.02 oft	$P_9 := W_{IC} \cdot VCG_9$
W <sub>CO</sub> = 22.492 •lton	VCG <sub>10</sub> := 5.6·ft + .4625·D <sub>10</sub>	VCG <sub>10</sub> = 21.334 oft	$P_{10} := W_{CO} \cdot VCG_{10}$
W <sub>CC</sub> = 8.693 olton	VCG <sub>11</sub> := .5·D <sub>10</sub>	VCG <sub>11</sub> = 17.01 oft	$P_{11} := W_{CC} \cdot VCG_{11}$
$W_{498} = 87.9 \text{ elton}$	VCG <sub>12</sub> := VCG <sub>498</sub>	VCG <sub>12</sub> = -1.2 oft	$P_{12} := W_{498} \cdot VCG_{12}$
W <sub>AUX</sub> = 555.959 •lton	$VCG_{13} := .9 \cdot (D_{10} - 7.4 \cdot ft)$	VCG <sub>13</sub> = 23.958 oft	$P_{13} := W_{AUX} \cdot VCG_{13}$
W <sub>517</sub> = 4.518 •lton	$VCG_{14} := .5 \cdot H_{MB}$	VCG <sub>14</sub> = 17.01 oft	$P_{14} := W_{517} \cdot VCG_{14}$
W <sub>OFH</sub> = 264.169 •lton	VCG <sub>15</sub> := .805 D <sub>10</sub>	VCG <sub>15</sub> = 27.386 oft	$P_{15} := W_{OFH} \cdot VCG_{15}$
W <sub>OFP</sub> = 112.4 •lton	$VCG_{16} := 8 \cdot ft + .71 \cdot D_{10}$	VCG <sub>16</sub> = 32.154 oft	$P_{16} := W_{OFP} \cdot VCG_{16}$

ip := 1.. 16  

$$P_{WG} := \sum_{ip} P_{ip} + W_P \cdot VCG_P - W_{VP} \cdot VCG_{VP}$$
  $P_{WG} = 90665.675 \cdot \text{lton ft}$ 

#### V!2. Light Ship KG

$$VCG_{LS} := \frac{P_{WG}}{\sum_{i1}} VCG_{LS} = 25.925 \text{ eft}$$
  $KG_{LS} := VCG_{LS}$   $KG_{LS} = 25.925 \text{ eft}$ 

#### VI3. Calculate Variable Load Weight Group Moments:

Weight	<u>VCG</u>		Product		
W <sub>F10</sub> = 17.08 •lton	VCG <sub>17</sub> := .746 D <sub>10</sub>	VCG <sub>17</sub> = 25.379 oft	$P_{17} := W_{F10} \cdot VCG_{17}$		
$W_{F31} = 27.121$ •lton	VCG <sub>18</sub> := .55·D <sub>10</sub>	VCG <sub>18</sub> = 18.711 oft	$P_{18} := W_{F31} \cdot VCG_{18}$		
$W_{F32} = 6.479$ olton	VCG <sub>19</sub> := .65·D <sub>10</sub>	VCG <sub>19</sub> = 22.113 oft	$P_{19} := W_{F32} \cdot VCG_{19}$		
W <sub>F41</sub> = 1880.311 •lton	VCG <sub>20</sub> := 7.5 ft	VCG <sub>20</sub> = 7.5 oft	$P_{20} := W_{F41} \cdot VCG_{20}$		
$W_{F42} = 63.8 \text{ olton}$	VCG <sub>21</sub> := 10. ft	$VCG_{21} = 10 \text{ eft}$	$P_{21} := W_{F42} \cdot VCG_{21}$		
$W_{F46} = 7.2$ •lton	VCG <sub>22</sub> := .35·D <sub>10</sub>	VCG <sub>22</sub> = 11.907 oft	$P_{22} := W_{F46} \cdot VCG_{22}$		
W <sub>F52</sub> = 22.5 olton	VCG <sub>23</sub> := 7.5⋅ft	VCG <sub>23</sub> = 7.5 oft	$P_{23} := W_{F52} \cdot VCG_{23}$		
iL := 17 23 $P_{WGL} := \sum_{iL} P_{iL} + W_{VP} \cdot VCG_{VP}$ $P_{WGL} = 23519.564 \text{ elton ft}$					
$W_L := W_{F41} + W_{F42} + W_{F20} + W_{F46} + W_{F52} + W_{F31} + W_{F32} + W_{F10}$ $W_L = 2211.95 \text{ olton}$					
·		$VCG_{L} := \frac{P_{WGL}}{W_{L}}$	VCG <sub>L</sub> = 10.633 •ft		

#### VI4. Calculate Ship Stability Characteristics:

$$\begin{split} \text{KG}_{\text{MARG}} := .5 \cdot \text{ft} & \text{KG} := \frac{\text{W}_{\text{LS}} \cdot \text{KG}_{\text{LS}} + \text{W}_{\text{L}} \cdot \text{VCG}_{\text{L}}}{\text{W}_{\text{T}}} + \text{KG}_{\text{MARG}} & \text{C}_{\text{IT}} := -.497 + 1.44 \cdot \text{C}_{\text{W}} & \text{C}_{\text{IT}} = 0.553 \\ \text{KB} := \frac{\text{T}}{3} \cdot \left( 2.5 - \frac{\text{C}_{\text{P}} \cdot \text{C}_{\text{X}}}{\text{C}_{\text{W}}} \right) & \text{BM} := \frac{\text{LWL} \cdot \text{B}^3 \cdot \text{C}_{\text{IT}}}{12 \cdot \text{V}_{\text{FL}}} & \text{GM} := \text{KB} + \text{BM} - \text{KG} & \text{C}_{\text{GMB}} := \frac{\text{GM}}{\text{B}} \\ \text{KG} = 20.842 \cdot \text{eft} & \text{KB} = 10.205 \cdot \text{eft} & \text{BM} = 16.907 \cdot \text{eft} & \text{GM} = 6.27 \cdot \text{eft} & \text{C}_{\text{GMB}} = 0.112 \end{split}$$

Bdol := 1000·Mdol

# VIL VERY SIMPLIFIED COST MODEL (Lead-Ship End Cost only)

V!!1. Additional charcteristics:

$$L_{S} := 30$$

**Initial Operational Capability:** 

$$Y_{IOC} := 1998$$

**Total Ship Acquisition:** 

$$N_S := 25$$

Production Rate (per year):

$$R_P := 3$$

#### Inflation:

$$Y_B := 1998$$

$$iy := 1.. Y_B - 1981$$

Average Inflation Rate (%):

(from 1981)

$$R_I := 5$$
.

$$F_{I} := \prod_{i \in I} \left( 1 + \frac{R_{I}}{100} \right)$$
  $F_{I} = 2.292$ 

#### a. Lead Ship Cost - Shipbuilder Portion:

SWBS costs: (See Table 5 for K N factors)

$$K_{N1} := \frac{.55 \cdot Mdol}{lton^{.772}}$$

$$K_{N1} := \frac{.55 \cdot \text{Mdol}}{\text{lton}^{.772}}$$
  $C_{L_1} := .03395 \cdot F_1 \cdot K_{N1} \cdot (W_1)^{.772}$ 

$$K_{N2} := \frac{1.2 \cdot Mdol}{hp^{.808}}$$

$$K_{N2} := \frac{1.2 \text{ Mdol}}{\text{hp}^{.808}}$$
  $C_{L_2} := .00186 \cdot F_1 \cdot K_{N2} \cdot P_{IBRAKE}^{.808}$ 

$$K_{N3} := \frac{1.0 \cdot Mdol}{lton^{.91}}$$

$$C_{L_3} := .07505 \cdot F_I \cdot K_{N3} \cdot (W_3)^{.91}$$

#### + Command, Control, Surveillance

$$K_{N4} := \frac{2.0 \cdot Mdol}{lton^{.617}}$$

$$C_{L_4} := .10857 \cdot F_{I} \cdot K_{N4} \cdot (W_4)^{.617}$$

(less payload GFM cost)

$$K_{N5} := \frac{1.5 \cdot Mdol}{lton^{.782}}$$

$$C_{L_5} := .09487 \cdot F_I \cdot K_{N5} \cdot (W_5)^{.782}$$

$$K_{N6} := \frac{1.0 \cdot Mdol}{lton^{.784}}$$

$$C_{L_6} := .09859 \cdot F_{I} \cdot K_{N6} \cdot (W_6)^{.784}$$

$$K_{N7} := \frac{1.0 \cdot Mdol}{lton^{.987}}$$

$$C_{L_7} := .00838 \cdot F_{I} \cdot K_{\cdot N7} \cdot (W_7)^{.987}$$

(Less payload GFM cost)

+ Margin Cost:

$$C_{LM} := \frac{W_{M24}}{\left(W_{LS} - W_{M24}\right)} \cdot \left(\sum_{i1} C_{L_{i1}}\right)$$

C<sub>LM</sub> = 14.837 •Mdol

+ Integration/Engineering: (Lead ship includes detail design engineering for class)

$$K_{N8} := \frac{10.0 \cdot Mdol}{Mdol^{1.099}}$$

$$K_{N8} := \frac{10.0 \cdot Mdol}{Mdol^{1.099}}$$
  $C_{L_8} := .034 \cdot K_{N8} \cdot \left( \sum_{i1} C_{L_{i1}} + C_{LM} \right)^{1.099}$ 

 $C_{L_{8}} = 91.894 \text{ •Mdol}$ 

+ Ship Assembly and Support: (Lead ship includes all tooling, jigs, special facilities for class)

$$K_{N9} := \frac{2.0 \cdot Mdol}{(Mdol)^{\cdot 839}}$$

$$K_{N9} := \frac{2.0 \cdot \text{Mdol}}{(\text{Mdol})^{.839}}$$
  $C_{L_9} := .135 \cdot K_{N9} \cdot \left( \sum_{i,1} C_{L_{i,1}} + C_{LM} \right)^{.839}$ 

C<sub>L<sub>9</sub></sub> = 19.402 •Mdol

= Total Lead Ship Construction Cost: (BCC) :

$$C_{LCC} := \sum_{i1} C_{L_{i1}} + C_{L_{8}} + C_{L_{9}} + C_{LM}$$

C<sub>LCC</sub> = 274.505 •Mdol

+ Profit:

$$F_{PROFIT} := .10$$
  $C_{LP} := F_{PROFIT} \cdot C_{LCC}$   $C_{LP} = 27.451 \cdot Mdol$ 

= Lead Ship Price:

$$P_L := C_{LCC} + C_{LP}$$

$$P_{T} = 301.956 \text{ } \cdot \text{Mdol}$$

+ Change Orders:

$$C_{LCORD} := .12 \cdot P_L$$

= Total Shipbuilder Portion:

$$C_{SB} := P_L + C_{LCORD}$$

b. Lead Ship Cost - Government Portion

Other support:

+ Program Manager's Growth:

$$C_{LPMG} := .1 \cdot P_L$$
  $C_{LPMG} = 30.196 \cdot Mdol$ 

**Costed Military Payload:** 

$$W_{MP} := W_4 + W_7 + W_{F20} - W_{IC} - W_{F23}$$
  $W_{MP} = 559.325$  elton

$$W_{\lambda,m} = 559.325$$
 elton

+ Ordnance and Electrical GFE: (Military Payload GFE)

$$C_{LMPG} := \left(.319 \cdot \frac{\text{Mdol}}{\text{lton}} \cdot W_{MP} + N_{HELO} \cdot 18.71 \cdot \text{Mdol}\right) \cdot F_{I}$$

+ HM&E GFE (boats, IC):

 $C_{LHMEG} := .02 \cdot P_L$ 

C <sub>LHMEG</sub> = 6.039 •Mdol

+ Outfitting Cost:

 $C_{LOUT} := .04 \cdot P_L$   $C_{LOUT} = 12.078 \cdot Mdol$ 

= Total Government Cost:

 $C_{LGOV} \coloneqq C_{LOTH} + C_{LPMG} + C_{LMPG} + C_{LHMEG} + C_{LOUT} \qquad C_{LGOV} = 550.581 \text{ } \bullet \text{Mdol}$ 

c. Total End Cost: (Must always be less than SCN appropriation)

\* Total End Cost:

$$C_{LEND} := C_{SB} + C_{LGOV}$$

C<sub>LEND</sub> = 888.772 •Mdol

#### **SUMMARY: INITIAL VALUES**

W<sub>FL1</sub> = 6683 •lton

$$W_{FL} \equiv in1 \cdot lton$$

ERR 
$$_{\text{WEIGHT}} = 0.102993$$

$$V_{FL} = W_{FL} \cdot 35 \cdot \frac{R^3}{lton}$$

# **GROSS CHARACTERISTICS:**

$$C_{P} = .59$$
 (.54 - .64)

 $W_T = 6058.967$  •lton

C 
$$\Delta L$$
 ≡ 55  $\frac{1 \text{ton}}{\text{ft}^3}$  (45 - 65) LWL ≡ 100  $\left(\frac{\text{W}_{\text{FL}}}{\text{C}_{\Delta \text{L}}}\right)^{\frac{1}{3}}$ 

$$C_V := \frac{V_{FL}}{LWL^3}$$
  $C_V = 1.925 \cdot 10^{-3}$ 

$$C_{V} = 1.925 \cdot 10^{-3}$$

$$C_{BT} = 3.3$$
 (2.8 - 3.7)  $B = \sqrt{\frac{C_{BT} \cdot V_{FL}}{C_{P} \cdot C_{X} \cdot LWL}}$   $B = 55.745 \cdot \text{ft}$   $T = 16.892 \cdot \text{ft}$   $C_{LB} = 8.885$  (7.5 - 10)

$$B = 55.745 \cdot ft$$
  $T = 16.892 \cdot ft$ 

$$C_{LB} = 8.885$$
 (7.5 - 10)

#### **ENERGY BALANCE:**

$$P_{I} = 102626 \circ hp$$

$$P_{IREQ} = 76805.452 \circ hp$$

$$ERR_{POWER} = 0.336$$

$$kW_G = 3000 \text{ s} \text{kW}$$

$$kW_{GREQ} = 2532.648 \text{ kW} \quad ERR_{KW} = 0.185$$

$$ERR_{KW} = 0.185$$

E≢7500-knt-hr

# AREA/VOLUME BALANCE:

$$V_T = 730369.111 \cdot ft^3$$
  $V_{MB} = 70067.665 \cdot ft^3$ 

$$V_{TR} = 511247.364 \cdot ft^3$$

$$V_{DMIN} = 60754.545 \, \text{eft}^3$$

$$V_{HT} = 632654.111 \cdot ft^3$$

$$V_{HT} = 632654.111 \cdot \hat{t}^3 \quad V_{AUX} = 84081.198 \cdot \hat{t}^3 \qquad V_{TA} = 484091.654 \cdot \hat{t}^3$$

$$V_{DMAX} = 303772.727 \text{ eft}^3$$

$$V_{TK} = 92128.595 \cdot ft^3$$

ERR 
$$_{AREA} = -0.053117$$

$$D_{10} = 34.02 \cdot \text{ft (Must be > D_{10MIN})}$$

$$D_{10MIN} = 33.02 \, \text{eft}$$

$$A_{TR} = 56805.263 \cdot \text{ft}^2$$
  $A_{HR} = 43214.262 \cdot \text{ft}^2$   $A_{DR} = 13591.001 \cdot \text{ft}^2$ 

$$A_{DR} = 13591.001 \cdot ft^2$$

$$A_{TA} = 53787.962 \cdot \text{ft}^2$$
  $A_{HA} = 42930.739 \cdot \text{ft}^2$   $A_{DA} = 10857.222 \cdot \text{ft}^2$ 

$$A_{DA} = 10857.222 \cdot \text{ft}^2$$

#### WEIGHT BALANCE:

$$W_T = 6058.967$$
 •lton

ERR 
$$_{\text{WEIGHT}} = 0.102993$$

$$W_i = 1958.474$$
 olton

$$W_{LS} = 3847.017$$
 olton

$$W_2 = 556.222$$
 •lton

$$W_6 = 120.14$$
 olton

$$W_{P} = 668.3$$
 olton

$$W_7 = 117.37$$
 elton

$$W_{F41} = 1880.311$$
 elton

$$W_4 = 313.915$$
 olton

**STABILITY/PAYLOAD:** 
$$C_{GMB} = 0.112$$
 (.09 - .122)

$$F_P := \frac{W_P}{W_{FT}}$$

$$F_P = 0.1$$

#### x0 =0.6000 0.7500 55.7451 16.8924 495.3014 vlb = 0.7000 20.0000 5.0000 200.0000 0.5400 vub = 90.0000 30.0000 800.0000 0.6400 0.8500 STEP Procedures f-COUNT FUNCTION $MAX\{q\}$ 7627.82 0.534195 1 6 6312.8 0.0459915 1 12 18 6099.97 0.00388632 1 6123.31 1.92403e-005 1 24 6123.42 6.04933e-010 1 30 Hessian modified 6123.42 8.88178e-016 1 Hessian modified 31 Optimization Converged Successfully Active Constraints: 2 4 6 8 x = 12.2977 455.0163 0.5400 0.7880 45.5016 options = 1.0e+003 \* Columns 1 through 7 0.0000 . 0.0000 0.0000 0.0010 Columns 8 through 14 0 0.0310 0.0060 0.0060 0.5000 6.1234 Columns 15 through 18

MATLAB OPTIMIZER OUTPUT FOR OPTIMIZED DESIGN EXAMPLE:

0.0010

0.0000

0.0001

#### MIT MATH MODEL: FINAL SYNTHESIS DESIGN

$$hp = \frac{33000 \cdot ft \cdot lbf}{min} \qquad knt = 1.69 \cdot \frac{ft}{sec}$$

 $lton \equiv 2240 \cdot lb$ 

L INPUT:

Primary Input Variables Are Highlighted in Yellow and Must Be Checked for Consistency Between MATHCAD Elements.

#### I1. Requirements:

Payload: (From CS2MP.XLS, Fig 1&2)

 $W_P := in0_1 \cdot lton$ 

variable:

 $W_{VP} := in0_2 \cdot lton$ 

Payload VCG:  $VCG_P := in0_3 \cdot ft$ 

Variable Payload VCG:

 $VCG_{VP} := in0_4 \cdot ft$ 

Command and Surveillance Payload:

 $W_{P400} := in0_5 \cdot lton$   $\frac{W_{P400}}{lton} = 148.14$ 

(W<sub>400</sub> less 420 and 430)

 $W_7 := in0_6 \cdot lton$ 

Armor:  $W_{164} := in0_7 \cdot lton$ 

Armament (all W 700): Mission handling/support:  $W_{P500} := in0_8$ ·lton

Mission outfit:  $W_{P600} := in0_{9} \cdot lton$ 

Ordnance:  $W_{F20} := in0_{10} \cdot lton$  (incl helo wt, WF23)

Helo Fuel:  $W_{F42} := in0_{11} \cdot lton$ 

Helo's:

N<sub>HELO</sub>:=2

 $W_{F23} := 12.73$  lton

Payload Cruise Electric Power Requirement:

 $kW_{PAY} := in0_{12} \cdot kW$ 

Payload Deck Areas:

Deckhouse:

**C&D:**  $A_{DPC} := in0_{13} \cdot ft^2$ 

(W400)

Armament:  $A_{DPA} := in0_{14} \cdot ft^2$ 

(W500, W600, W700, WF20)

Hull:

**C&D:**  $A_{HPC} := in0_{15} ft^2$ 

(W400)

Armament:

 $A_{HPA} := in0_{16} \cdot ft^2$ 

(W500, W600, W700, WF20)

Manning:

Officers:  $N_O = 15$ 

Enlisted: N<sub>E</sub>:=135

Total:  $N_T := N_E + N_O N_T = 150$ 

Average deck height:

 $H_{DK} := 9 \text{ ft}$ 

Sustained Speed:

 $V_S = 27$  eknt

(Use Figure 3 as a guide in selecting V s)

**Endurance Speed:** 

 $V_e = 20 \text{ eknt}$ 

Range: E = 7500 eknt.hr

Stores period:

 $T_S := 45 \cdot day$ 

Sonar Dome/Appendages: SOS-53C; 215ft<sup>2</sup>, 87.9lton.-1.2ft,85.7lton SOS-56; 27ft <sup>2</sup>,13.94lton,-3.1ft,7.43lton

 $A_{SD} := in2 \cdot ft^2$  $W_{A98} := 87.9 \cdot \text{lton}$  VCG<sub>A98</sub> := -1.2 \text{·ft structure}:  $W_{165} := 85.7 \cdot \text{lton}$ water:

Fin Stabilizers: (for one pair, electric power requirement = 50 kW)  $kW_{fins} := in2_7 \cdot kW$ 

Hull Material: (OS: C <sub>HMAT</sub>=1.0; HTS: C <sub>HMAT</sub>=0.93) C HMAT := .93

W CPS := 30 lton (ie. No CPS=0) CPS: (W CPS=30lton):

Machinery:

 $N_P := in2_{12}C_{PROPD} := if(N_P > 1, 1.0, 1.2)$   $C_{PROPD} = 1$ Number of propellers =

VCG 237 := 0 ft (Weight=14.2lton, VCG=3.5ft) W 237 :=0-lton Aux Propulsion (APU):

Propulsion Engines (PE) - standard LM2500's; Generator engines DDA149TI

Number and brake horsepower of propulsion engines:  $N_{PENG} := in2_{10}P_{BPENG} := in2_{11} \cdot hp$ 

 $A_{IE} := 135.2 \text{ ft}^2$   $A_{PIE} := N_{PENG} A_{IE}$   $A_{PIE} = 540.8 \text{ eft}^2$ Inlet/exhaust Xsect area for PE:

Deckhouse decks impacted by propulsion and generator inlet/exhaust:

· Hull decks impacted by propulsion inlet/exhaust:  $N_{HPIF} := 0$ 

 $N_{PENG} = 4$ 

Machinery Box: H<sub>MRMIN</sub>:=22 ft L<sub>MR</sub>:=40 ft

 $C_{P} = 0.54$   $C_{MB} := \frac{L_{MB}}{L_{MB}}$   $C_{MB} = 0.088$   $C_{PMB}$  from Fig. 10: C PMB := .998

kW G := 3000-kW N c:=3 Ship Service Generators:

Hull decks impacted by generator inlet/exhaust:

 $FR_G := \frac{.288 \text{ lb}}{2.54 \text{ k/W/br}}$   $FR_G = 0.085 \circ \frac{\text{lb}}{\text{hp/hr}}$ Specific fuel rate for generator engines:

 $A_{GIE} := 38.4 \text{ ft}^2$   $A_{eIE} := N_{G} \cdot A_{GIE}$   $A_{eIE} = 115.2 \text{ eft}^2$ Inlet/exhaust X-sect area for gen:

IL GROSS CHARACTERISTICS

deckhouse volume:

LWL = 455.016 eft B = 45.502 eft

**Hull Principle Characteristics:** 

Adjust in (see Figures 5 and 6) Summary  $C_P = 0.54$   $C_X = 0.788$ Section at end of file

 $V_D = 235516.369 \, \text{eft}^3$ 

C DHMAT := 2 (Deckhouse Material: Aluminum - C DHMAT=1; Steel - C DHMAT=2) III1.2 Seawater propereties:

$$T_{SW} := 59$$
  $\rho_{SW} := 1.9905 \cdot \frac{\text{slug}}{\text{fr}^3}$   $\nu_{SW} := 1.2817 \cdot 10^{-5} \cdot \frac{\text{ft}^2}{\text{sec}}$ 

III1.3 Resistance calculation parameters:

Air Drag Coeficient:

Correlation Allowance: 
$$C_A := .0005$$
  $C_P = 0.54$  Use Figure 7 with  $C_P$  and  $C_{BT}$  for TSS wetted surface coeficient:  $C_{BT} = 3.7$   $C_{BT} = 3.7$   $C_{BT} = 3.7$  Specify or estimate actual ship surface area:  $C_{STSS} := C_{STSS} = 108340.212 \cdot nt^3$ 

Use Figure 8 or 9 with LWL for Appendage Drag Coeficient:

 $C_{\text{DAPP}} := 2.85 \cdot \frac{\text{hp} \cdot 10^{-5}}{\text{ft}^2 \cdot \text{knt}^3}$ 

Power Margin Factor (margin for concept design = 10%):

PMF := 1.1

III1.4 Use range of ship speeds for speed to length ratios (R i). Reynold's numbers (RN i) and ITTC friction (RF i):

### III1.5 Use Gertler with C $_{P}$ , $C_{V}$ , $R_{i}$ and $C_{BT}$ to interpolate for $C_{R}$ and calcualte TSS resistance:

Form Factor:

$$FF := \frac{4}{3} (C_{BT} - 3)$$
  $FF = 0.933$ 

$$C_{RTSS_{i}} := C_{R3.00_{i}} + FF \cdot \left(\frac{C_{R3.75_{i}} - C_{R2.25_{i}}}{2}\right) + FF^{2} \cdot \left(\frac{C_{R2.25_{i}} + C_{R3.75_{i}}}{2} - C_{R3.00_{i}}\right)$$

$$C_{RTSS} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0.001 \\ 0.002 \\ 0.004 \\ 0.005 \end{bmatrix}$$

$$R_{RTSS_{i}} := .5 \cdot \left[ \rho_{SW} \cdot S_{S} \cdot (V_{i})^{2} \cdot C_{RTSS_{i}} \right]$$

$$R_{RTSS} = \begin{bmatrix} 594.029 \\ 2376.118 \\ 5449.009 \\ 19457.936 \\ 57235.012 \\ 132640.508 \\ 283772.062 \end{bmatrix}$$

#### III2 Calculate Bare Hull Ship Resistance - Worm Curve data from ASSET:

$$WCFA := \begin{bmatrix} 2 & 3.5 \\ 3 & 2.95 \\ 4 & 2.5 \\ .5 & 2.1 \\ .6 & 1.8 \\ .7 & 1.55 \\ .8 & 1.33 \\ .9 & 1.17 \\ 1.0 & 1.07 \\ 1.1 & 1 \\ 1.2 & .94 \\ 1.3 & .89 \\ 1.4 & .88 \\ 1.5 & .87 \\ 1.6 & .87 \end{bmatrix} \qquad R = \begin{bmatrix} 0.234 \\ 0.469 \\ 0.703 \\ 0.938 \\ 1.172 \\ 1.266 \\ 1.641 \end{bmatrix} \qquad WCF := \begin{bmatrix} 3.242 \\ 2.124 \\ 1.460 \\ 1.083 \\ .923 \\ .880 \\ .870 \end{bmatrix} \qquad WCF_{i} = \begin{bmatrix} 1925.843 \\ 81.5 & 87 \\ 1.6 & .87 \end{bmatrix} \qquad R_{R_{i}} := R_{RTSS_{i}} \cdot WCF_{i} \qquad WCF_{i} = R_{R_{i}} := R_{R_{i}}$$

hull:  $P_{EBH_{i}} := R_{T_{i}} \cdot V_{i}$   $\frac{P_{EBH}}{hp} = \begin{bmatrix} 74.061 \\ 486.717 \\ 1443.121 \\ 3779.091 \\ 8812.269 \\ 15631.404 \\ 39212.572 \end{bmatrix}$ 

appendage: 
$$P_{EAPP_i} := (LWL \cdot D_P \cdot C_{DAPP} + .5 \cdot C_{SD \cdot P} \cdot SW \cdot A_{SD}) \cdot (V_i)^3$$

air:  $P_{EAA_i} := .5 \cdot C_{AA} \cdot A_{W \cdot P} \cdot A \cdot (V_i)^3$ 

$$\frac{P_{EAA}}{hp} = \begin{bmatrix} 1.535 \\ 12.281 \\ 41.448 \\ 98.246 \\ 191.887 \\ 241.723 \\ 526.539 \end{bmatrix}$$

$$P_{ET_i} := P_{EBH_i} + P_{EAPP_i} + P_{EAA_i}$$

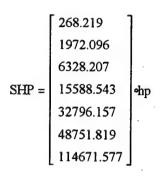
$$\frac{P_{ET}}{hp} = \begin{bmatrix} 163.37 \\ 1201.186 \\ 3854.453 \\ 9494.84 \\ 19975.841 \\ 29694.29 \\ 69845.415 \end{bmatrix}$$

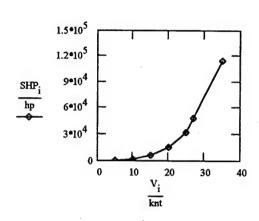
$$\frac{P_{ET}}{hp} = \begin{bmatrix} 163.37 \\ 1201.186 \\ 3854.453 \\ 9494.84 \\ 19975.841 \\ 29694.29 \\ 69845.415 \end{bmatrix}$$

#### III4. Shaft Horsepower:

Approximate Propulsive Coeficient (PC):

$$SHP_i := \frac{EHP_i}{PC}$$





Endurance Shaft Horsepower:

$$P_e := SHP_4$$

$$P_e := SHP_4$$
  $P_e = 15588.543 \text{ ohp}$ 

Sustained Speed Installed Shaft Horsepower Required (Allows for fouling and sea state):

$$P_S := SHP_c$$

$$P_S := SHP_6$$
  $P_S = 48751.819 \circ hp$ 

$$P_{IREQ} := 1.25 \cdot P_S$$

$$P_{IREQ} := 1.25 \cdot P_{S}$$
  $P_{IREQ} = 60939.774 \cdot hp$ 

Actual installed SHP must be greater than P IREO

$$P_{IBRAKE} := N_{PENG} \cdot P_{BPENG}$$
  $P_{IBRAKE} = 105800 \cdot hp \eta := .97$ 

$$P_I := \eta \cdot P_{IBRAKE}$$
  $P_I = 102626 \cdot hp$ 

$$(P_1 \text{ must be} > P_{IREQ})$$
  $P_{IREQ} = 60939.7$ 

(P<sub>I</sub> must be > P<sub>IREQ</sub>) 
$$P_{IREQ} = 60939.774$$
 ohp  $ERR_{POWER} := \frac{P_{I} - P_{IREQ}}{P_{IREQ}}$   $ERR_{POWER} = 0.684$ 

III5. Estimate Propulsion Fuel Required:

Reference: DDS 200-1 "Calculate of Surface Ship Endurance Fuel"

Average Endurance Brake SHP Required (Allows for fouling and sea state):

$$P_{eBAVG} := 1.1 \frac{P_e}{\eta}$$
  $P_{eBAVG} = 17677.73 \text{ shp}$ 

Specific fuel rate for propulsion engines: (GT; FR for diesel = .327)

$$FR := 1.97 \cdot \frac{lb}{hp^{.85} \cdot hr} \cdot P eBAVG^{-.15}$$
  $FR = 0.454$ 

$$FR = 0.454 \frac{b}{hp \cdot hr}$$

Margin for instrumentation and machinery differences,  $f(P_{ij})$ :

$$f_1 := 1.04$$

Specified fuel rate:

$$FR_{SP} := f_1 \cdot FR$$

Average fuel rate allowing for plant deterioration:

FR AVG := 1.05 FR SP FR AVG = 0.496 
$$\frac{\text{lb}}{\text{hp hr}}$$

Burnable propulsion endurance fuel weight:

$$W_{BP} := \frac{E}{V_e} \cdot (P_{eBAVG} \cdot FR_{AVG})$$
  $W_{BP} = 1468.198 \text{ elton}$ 

Tailpipe allowance and propulsion endurance fuel:

$$W_{FP} := \frac{W_{BP}}{TPA}$$

$$W_{FP} = 1545.472$$
 olton

Allow for expansion and tank structure in required propulsion tank volume:

$$\gamma_F := 43 \cdot \frac{\text{ft}^3}{\text{Iton}}$$

$$\gamma_F := 43 \cdot \frac{\text{ft}^3}{\text{Iton}}$$
  $V_{FP} := 1.02 \cdot 1.05 \cdot \gamma_F \cdot W_{FP}$   $V_{FP} = 71173.602 \cdot \text{ft}^3$ 

$$V_{FP} = 71173.602 \, \text{eft}^3$$

Ш6. Estimate electric load.

Reference: DDS 310-1

Estimate Maximum Functional Load based on parametrics for WINTER cruise condition:

Propulsion:

$$kW_P := .00466 \cdot \frac{kW}{hp} \cdot P_{IBRAKE}$$

Steering:

$$kW_S := .00583 \frac{kW}{R^2} LWL T$$

$$kW_S = 32.623 \text{ ekW}$$

Lighting:

$$kW_L := .0002053 \cdot \frac{kW}{e^3} \cdot 1.8 \cdot LWL \cdot T \cdot B$$
  $kW_L = 94.089 \cdot kW$ 

Miscellaneous:

$$kW_{M} := 46.1 \cdot kW$$

$$kW_H := .0013 \cdot \frac{kW}{ft^3} \cdot 1.25 \cdot LWL \cdot T \cdot B$$

Ventilation:

$$kW_{V} := .19 \cdot (kW_{H} + kW_{P}) + kW_{CPS}$$
  $kW_{V} = 291.445 \cdot kW$ 

$$kW_{AC} := .67 \cdot \left( .1 \cdot kW \cdot N_{T} + .0015 \cdot \frac{kW}{R^3} \cdot .47 \cdot 1.3 \cdot LWL \cdot T \cdot B + .1 \cdot kW_{P} \right)$$

 $kW_{AC} = 199.429 kW$ 

Aux Boiler and FW: (electric boiler)

$$kW_B := .94 \cdot N_T \cdot kW$$

$$kW_B = 141 \text{ ekW}$$

Firemain:

$$kW_F := .0001 \cdot \frac{kW}{R^3} \cdot 1.8 \cdot LWL \cdot T \cdot B$$
  $kW_F = 45.83 \cdot kW$ 

Unrep and handling:

$$kW_{RH} := .00002 \cdot \frac{kW}{e^3} \cdot 1.25 \cdot LWL \cdot T \cdot B$$
  $kW_{RH} = 6.365 \cdot kW$ 

$$kW_{RH} = 6.365 \text{ } \text{kW}$$

Aux Machinery:

$$kW_{\Delta} := .22 \cdot N_{T} \cdot kW + kW_{fins}$$

$$kW_A = 33 \text{ ekW}$$

Services and Work Spaces:

$$kW_{SERV} := .35 \cdot N_{T} \cdot kW$$

$$kW_{SERV} = 52.5 \text{ ekW}$$

Non-Payload Functional Load:

 $kW_{NP} := kW_{P} + kW_{S} + kW_{L} + kW_{M} + kW_{H} + kW_{CPS} + kW_{V} + kW_{AC} + kW_{B} + kW_{F} + kW_{RH} + kW_{A} + kW_{S}$ 

Maximum Functional Load:

$$kW_{MFL} := kW_{PAY} + kW_{NP}$$

$$kW_{MFL} = 2508.383 \text{ ekW}$$
  $\frac{kW_{NP}}{kW} = 1968.313$ 

MFL with margins: (design,growth):

Installed Electrical Power Required:

Power available per generator:

$$kW_{G} = 3000 \text{ ekW}$$

$$kW_{GREQ} := \frac{kW_{MFLM}}{(N_{G}-1)\cdot .9}$$
  $kW_{GREQ} = 2006.707 \text{ ekW}$ 

$$W_{GREQ} = 2006.707 \text{ ekW}$$

$$ERR_{KW} := \frac{kW_G - kW_{GREQ}}{kW_{GREQ}}$$

24 hour electrical load:

$$kW_{24} := .5 \cdot (kW_{MFL} - kW_{P} - kW_{S}) + .8 \cdot (kW_{P} + kW_{S})$$
  $kW_{24} = 1411.887 \cdot kW$ 

with margin (design):

III7. Estimate Electric Fuel Rate:

FR 
$$_{G} = 0.113 \circ \frac{lb}{kW \cdot hr}$$

Margin for instrumentation and machinery differences,  $f(P_1)$ :

$$f_{1e} := 1.04$$

Specified fuel rate:

$$FR_{GSP} := f_{le} \cdot FR_{G}$$

Average fuel rate allowing for plant deterioration:

FR 
$$_{GAVG} := 1.05 \cdot FR _{GSP}$$

FR <sub>GAVG</sub> := 1.05 FR <sub>GSP</sub> FR <sub>GAVG</sub> = 0.124 • 
$$\frac{lb}{kW \cdot hr}$$
 FR <sub>GAVG</sub> = 0.092 •  $\frac{lb}{hp \cdot hr}$ 

$$FR_{GAVG} = 0.092 \frac{lb}{hp_1hr}$$

#### III8. Estimate Electrical and Total fuel Required

Burnable electrical endurance fuel weight:

$$W_{Be} := \frac{E}{V_e} \cdot (kW_{24AVG} \cdot FR_{GAVG})$$
  $W_{Be} = 35.119 \cdot lton$ 

Tailpipe allowance and electrical endurance fuel:

$$W_{Fe} := \frac{W_{Be}}{TPA}$$

$$W_{Fe} := \frac{W_{Be}}{TPA}$$
  $W_{Fe} = 36.968 \text{ elton}$ 

Allow for expansion and tank structure in required electrical fuel tank volume:

$$V_{Fe} := 1.02 \cdot 1.05 \cdot \gamma_F \cdot W_{Fe}$$
  $V_{Fe} = 1702.473 \text{ eft}^3$ 

Total ship fuel: (DFM)

$$W_{F41} := W_{FP} + W_{Fe}$$
  $W_{F41} = 1582.439 \text{ olton}$   
 $V_{F} := V_{FP} + V_{Fe}$   $V_{F} = 72876.075 \text{ oft}^{3}$ 

#### IV. Space Estimate

#### IVA. Available Space

IVA1. Underwater Hull Volume Available

$$V_{HUW} := V_{FL}$$
  $V_{HUW} = 108340.212 \text{ eft}^3$ 

IVA2. Sheer Line. (3 criteria)

- 1) Keep deck edge above water at 25 degree heel
- 2) Longitudinal strength
- 3) Contain machinery box height:

$$M := \begin{bmatrix} .21 \cdot B + T \\ \frac{LWL}{15} \\ H_{MBMIN} \end{bmatrix} \qquad M = \begin{bmatrix} 21.853 \\ 30.334 \\ 22 \end{bmatrix} \text{ of } \qquad D_{10MIN} := \max(M) \qquad D_{10MIN} = 30.334 \text{ of }$$

$$D_{10} := \left(D_{10MIN} + 1 \cdot ft\right)$$

$$D_{0MIN} := 1.011827 \cdot T - 6.36215 \cdot \frac{10^{-6}}{ft} \cdot LWL^2 + 2.780649 \cdot 10^{-2} \cdot LWL + T \qquad D_{0MIN} = 36.076 \text{ eft} \qquad D_0 := D_{0MIN}$$

$$D_{20MIN} := .014 \cdot LWL \cdot \left(2.125 + 1.25 \cdot \frac{10^{-3}}{ft} \cdot LWL\right) + T$$
  $D_{20MIN} = 29.458 \text{ eft}$   $D_{20} := D_{20MIN}$ 

IVA3. Above-Water Hull Volume

$$F_0 := D_0 - T$$
  $F_{10} := D_{10} - T$   $F_{20} := D_{20} - T$ 

$$A_{PRO} := LWL \frac{F_0 + 4 \cdot F_{10} + F_{20}}{6}$$
  $F_{AV} := \frac{A_{PRO}}{LWL}$   $F_{AV} = 19.514$  of

$$D_{AV} := F_{AV} + T$$
  $D_{AV} = 31.812 \text{ eft}$  cubic #:  $CN := \frac{LWL \cdot B \cdot D_{AV}}{10^5 \cdot ft^3}$   $CN = 6.586$ 

$$C_W := .236 + .836 \cdot C_P$$
  $C_W = 0.687$ 

flare factor: 
$$f_f := .714599 + .18098 \frac{D_AV}{T} - .018828 \left(\frac{D_AV}{T}\right)^2 M_f := \begin{bmatrix} f_f \\ 1 \end{bmatrix}$$
  $f_f := \max(M_f)$ 

$$V_{HAW} := LWL B \cdot F_{AV} \cdot C_{W} \cdot f_{f}$$
  $V_{HAW} = 293507.825 \text{ eft}^{3}$ 

#### IVA4. Total Hull Volume.

$$V_{HT} := V_{HUW} + V_{HAW}$$
  $V_{HT} = 401848.037 \text{ eft}^3$ 

#### **IVA5. Size Deck House:**

$$V_{DMAX} := .0025 LWL^3 V_{DMAX} = 235516.298 eft^3$$

$$V_{DMIN} := .0005 \cdot LWL^3$$
  $V_{DMIN} = 47103.26 \cdot eft^3$   $V_D = 235516.298 \cdot eft^3$ 

#### IVA6. Calculate Total Ship Volume

$$V_T := V_{HT} + V_D$$
  $V_T = 637364.335 \text{ eft}^3$ 

#### IVB. Space Requirement

IVB1. Machinery Box (assumed near midships) 
$$B_{MB} := B B_{MB} = 45.502 \text{ eft}$$

$$H_{MB} := D_{10}$$
  $L_{MB} = 40 \text{ eft}$   $A_{MB} := B \cdot T \cdot C_{X} + B \cdot (H_{MB} - T)$   $A_{MB} = 1307.129 \text{ eft}^{2}$ 

$$V_{MB} := L_{MB} \cdot A_{MB} \cdot C_{PMB}$$
  $V_{MB} = 52180.608 \text{ eft}^3$   $V_{AUX} := 1.2 \cdot V_{MB}$   $V_{AUX} = 62616.73 \text{ eft}^3$ 

# IVB2. Tankage

Helo:

Helo fuel weight from Payload Spreadsheet: 
$$W_{F42} = 63.8$$
 elton

Allow for tank structure and expansion:  $\gamma_{HF} := 43.\frac{ft^3}{lton}$ 

$$V_{HF} := 1.02 \cdot 1.05 \cdot W_{F42}^{\gamma} HF$$
  $V_{HF} = 2938.181 \text{ eft}^3$ 

#### Lube Oil:

LO weight: 
$$W_{F46} := 7.2 \cdot lton$$
Allow for tank structure and expansion:  $\gamma_{LO} := 39 \cdot \frac{ft^3}{ltor}$ 

$$V_{LO} := 1.02 \cdot 1.05 \cdot W_{F46} \cdot \gamma_{LO} \quad V_{LO} = 300.737 \text{ eft}^3$$

#### Potable Water:

Water weight: 
$$W_{F52} := N_{T} \cdot .15 \cdot lton$$
  $W_{F52} = 22.5 \cdot lton$   
Allow for tank structure:  $\gamma_{W} := 36 \cdot \frac{R^3}{lton}$ 

$$V_W := 1.02 \cdot W_{F52} \cdot \gamma_W \qquad V_W = 826.2 \text{ eR}^3$$

Sewage: 
$$V_{SEW} := N_{T} \cdot 2 \cdot ft^3$$
  $V_{SEW} = 300 \text{ oft}^3$ 

Waste Oil: 
$$V_{WASTE} := .005 V_{FL}$$
  $V_{WASTE} = 541.701 \text{ eft}^3$ 

Clean Balast: 
$$V_{BAL} := .032 \cdot V_{FL}$$
  $V_{BAL} := 0 \cdot ft^3$   $V_{BAL} = 0 \cdot et^3$ 

$$V_{TK} := V_{F} + V_{HF} + V_{LO} + V_{W} + V_{SEW} + V_{WASTE} + V_{BAL}$$
  $V_{TK} = 77782.894 \text{ eft}^{3}$ 

#### IVB3. Payload Deck Areas

$$A_{DPR} := 1.15 \cdot A_{DPA} + 1.23 \cdot A_{DPC}$$
  $A_{DPR} = 10143.981 \text{ eft}^2$ 

$$A_{DPR} = 10143.981 \, \text{eft}^2$$

$$A_{HPR} := 1.15 \cdot A_{HPA} + 1.23 \cdot A_{HPC}$$
  $A_{HPR} = 9797.796 \text{ eR}^2$ 

$$A_{HPR} = 9797.796 \, \text{eft}^2$$

#### IVB4. Living Deck Area

$$A_{COXO} := 225 \cdot ft^2$$
  $A_{DO} := 75 \cdot N_O \cdot ft^2$   $A_{DO} = 1125 \cdot gt^2$ 

$$A_{DL} := A_{COXO} + A_{DO}$$
  $A_{DL} = 1350 \text{ eft}^2$ 

$$A_{DL} = 1350 \, \text{eft}^2$$

$$A_{HAB} := 50 \cdot ft^2$$
  $A_{HL} := \left(A_{HAB} + \frac{LWL}{100} \cdot ft\right) \cdot N_T - A_{DL}$ 

$$A_{HIL} = 6832.524 \, \text{eft}^2$$

#### IVB5. Hull Stores

$$A_{HS} := 300 \cdot \text{ft}^2 + .0158 \cdot \frac{\text{ft}^2}{\text{lb}} \cdot \text{N}_{T} \cdot 9 \cdot \frac{\text{lb}}{\text{day}} \cdot \text{T}_{S}$$
  $A_{HS} = 1259.85 \cdot \text{ft}^2$ 

# IVB6. Other Ship Functions

#### Deckhouse:

$$A_{DM} := .05 \cdot (A_{DPR} + A_{DL})$$
  $A_{DM} = .574.699 \cdot R^2$ 

#### **Bridge and Chartroom:**

$$A_{DB} := 16 \cdot \text{ft} \cdot (B - 18 \cdot \text{ft})$$

$$A_{DB} = 440.026 \text{ eR}^2$$

#### Engine Inlet/Exhaust:

$$A_{DIE} := 1.4 \cdot N_{DIE} \cdot \left(A_{PIE} + A_{eIE}\right) \quad A_{DIE} = 918.4 \text{ eft}^2$$

#### Hull:

#### **Ship Functions:**

$$A_{HSF} := 2500 \cdot ft^2 \cdot CN$$

$$A_{HSF} = 16465.835 \text{ eft}^2$$

#### Engine Inlet/Exhaust:

$$A_{HIE} := 1.4 \cdot \left( N_{HPIE} \cdot A_{PIE} + N_{HeIE} \cdot A_{eIE} \right) \qquad A_{HIE} = 161.28 \text{ eft}^2$$

#### IVB7. Total Required Area and Volume

$$A_{HR} := A_{HPR} + A_{HL} + A_{HS} + A_{HSF} + A_{HIE}$$
  $A_{HR} = 34517.285 \text{ eft}^2$   
 $V_{HR} := H_{DK} \cdot A_{HR}$   $V_{HR} = 310655.563 \text{ eft}^3$ 

$$\mathsf{A}_{\mathsf{DR}} := \mathsf{A}_{\mathsf{DPR}} + \mathsf{A}_{\mathsf{DL}} + \mathsf{A}_{\mathsf{DM}} + \mathsf{A}_{\mathsf{DB}} + \mathsf{A}_{\mathsf{DIE}}$$

 $A_{DR} = 13427.106 \, \text{eft}^2$ 

 $V_{DR} := H_{DK} \cdot A_{DR}$   $V_{DR} = 120843.956 \text{ eft}^3$ 

Total:

$$A_{TR} := A_{HR} + A_{DR}$$

$$A_{TR} = 47944.391 \text{ eft}^2$$

$$V_{TR} := H_{DK} \cdot A_{TR}$$

$$V_{TR} = 431499.519 \, \text{eft}^3$$

IVC. Space Balance

$$V_D = 235516.298 \, \text{eft}^3$$

$$V_{DR} = 120843.956 \, \text{eft}^3$$

$$V_{HA} := V_{HT} - V_{MB} - V_{AUX} - V_{TK} V_{HA} = 209267.805 \text{ eft}^3$$

$$V_{HR} = 310655.563 \text{ eft}^3$$

$$v_{TA} := v_{HA} + v_{D}$$

$$V_{TA} = 444784.103 \text{ eft}^3 >$$

$$V_{TR} = 431499.519 \, \text{eft}^3$$

$$A_{HA} := \frac{V_{HA}}{H_{DK}}$$

$$A_{HA} = 23251.978 \, \text{eft}^2$$

$$A_{HR} = 34517.285 \, \text{eft}^2$$

$$A_{DA} := \frac{V_D}{H_{DK}}$$

$$A_{DA} = 26168.478 \, \text{eft}^2$$

$$A_{DR} = 13427.106 \, \text{eft}^2$$

$$A_{TA} := A_{DA} + A_{HA}$$

$$A_{TA} = 49420.456 \, \text{eft}^2$$

$$A_{TA} = 49420.456 \text{ eft}^2$$
 >  $A_{TR} = 47944.391 \text{ eft}^2$ 

$$ERR_{VOL} := \frac{V_{TA} - V_{TR}}{V_{TR}} \qquad ERR_{VOL} = 3.078702 \,\%$$

$$ERR_{AREA} := \frac{A_{TA} - A_{TR}}{A_{TR}} \cdot \%$$

 $ERR_{AREA} = 0.030787 \%$ 

V. Weight

V1. Propulsion (200)

250-290)

Basic Machinery: 
$$W_{BM} := P_{I} \cdot \frac{1b}{hp} \left[ 9.0 + 12.4 \cdot \left( P_{I} \cdot \frac{10^{-5}}{hp} - 1 \right)^{2} \right]$$
  $W_{BM} = 412.728 \text{ olton}$ 

Shafting: (243)

$$W_S := .356 \frac{lton}{ft} \cdot LWL \cdot f_S$$
  $W_S = 80.993 \cdot lton$ 

$$W_S = 80.993$$
 •lton

(f<sub>S</sub>=0.5 for twin screws, 0.33 for single screw)

Props:

$$W_{PR} := .05575 \cdot lb \cdot \left(\frac{D_{P}}{ft}\right)$$
  $S_{P} = 18.227 \cdot lton$ 

$$W_{PR} = 18.227$$
 elton

Bearings:

$$W_B := .15 (W_S + W_{PR})$$
  $W_B = 14.883$  elton

$$W_B = 14.883$$
 olton

**Total Shafting:** 

$$W_{ST} := W_{S} + W_{B} + W_{PR}$$

$$W_{ST} = 114.103$$
 olton

**Total Propulsion:** 

$$W_2 := W_{BM} + W_{ST} + W_{237}$$

$$W_2 = 526.831$$
 olton

#### V2. Electrical Plant (300)

$$W_3 := 50 \cdot lton + .03214 \cdot \frac{lton}{kW} \cdot N_G \cdot kW_G$$
  $W_3 = 339.26 \cdot lton$ 

#### V3. Command/Control/Surveillance (400)

Gyro/IC/Navigation (420, 430):

 $W_{IC} := 4.65 \cdot CN \cdot lton$ 

 $W_{IC} = 30.626$  elton

Other/Misc Group 400:

 $W_{CO} := 2.24 \cdot CN \cdot Iton$ 

 $W_{CO} = 14.753$  olton

Cabling:

$$W_{CC} := .04 \cdot (W_{P400} + W_{IC} + W_{CO})$$
  $W_{CC} = 7.741$  elton

$$W_A := W_{P400} + W_{IC} + W_{CO} + W_{CC} + W_{498}$$

 $W_a = 289.161$  olton

#### V4. Auxiliary Systems (500)

aux steam (electric aux boiler):

hotel steam:

 $Q_{HS} := 15 \cdot N_T$  distiller:  $Q_{DS} := 6.5 \cdot N_T + 250$ 

 $W_{517} := .0013 \cdot (Q_{HS} + Q_{DS}) \cdot lton$ 

 $W_{517} = 4.518$  olton

aux sys operating fluids:

 $W_{598} := .000075 \cdot V_T \cdot \frac{lton}{a^3}$ 

$$W_{598} = 47.802$$
 olton

$$W_{AUX} := \left[ .000772 \cdot \left( \frac{V_T}{ft^3} \right)^{1.443} + 5.14 \cdot \frac{V_T}{ft^3} + 6.19 \cdot \left( \frac{V_T}{ft^3} \right)^{.7224} + 377 \cdot N_T + 2.74 \cdot \frac{P_I}{hp} \right] \cdot 10^{-4} \cdot lton + 113.8 \cdot lton$$

$$W_{AUX} = 503.173 \cdot lton$$

$$W_{593} := 10 \cdot lton$$
  $W_5 := W_{AUX} + W_{P500} + W_{517} + W_{593} + W_{598} + W_{CPS}$ 

#### V5. Outfit & Furnishings (600)

$$W_{OFH} := \left(31.4 + \frac{.0003187}{ft^3} \cdot V_T\right) \cdot lton \qquad W_{OFH} = 234.528 \cdot lton$$

$$W_{OFP} := .8 \cdot (N_T - 9.5) \cdot lton$$

W OFP = 112.4 •lton

$$W_6 := W_{OFH} + W_{OFP} + W_{P600}$$

 $W_6 = 354.668$  olton

#### V6. Structure (100)

 $W_{BH} := C_{HMAT} \cdot (1.68341 \cdot CN^2 + 167.1721 \cdot CN - 103.283) \cdot ltonW_{BH} = 995.839 \cdot$ 

$$\rho_{DH} := if(C_{DHMAT} = 1,.0007,.001429)$$

 $\rho_{DH} = 0.001$ 

Deckhouse (150): 
$$W_{DH} := \rho_{DH} \cdot \frac{\text{lton}}{R^3} \cdot V_{D}$$

$$W_{DH} = 336.553$$
 olton

$$W_{171} := .0688 \cdot \frac{lton}{ft} \cdot LWL - 13.75 \cdot lton$$

$$W_{180} := .0675 \cdot W_{BM} + .072 \cdot (W_3 + W_4 + W_5 + W_7)$$
  $W_{180} = 127.844 \text{ elton}$ 

$$W_1 := W_{BH} + W_{DH} + W_{171} + W_{180} + W_{165} + W_{164}$$

$$W_1 = 1563.49$$
 elton

#### V7. Single Digit Weight Summary & Weight Balance:

$$i1 := 1, 2...7$$

$$W_{M24} := .1 \cdot \left( \sum_{i=1}^{1} W_{i1} \right)$$

# $W_{M24} := .1 \cdot \left( \sum_{i,1} W_{i,1} \right)$ $W_{M24} = 383.366 \text{ elton}$

#### Lightship:

$$W_{LS} := \sum_{i,1} W_{i,1} + W_{M24}$$
  $W_{LS} = 4217.029 \text{ elton}$ 

#### Additional Loads:

$$W_{F31} := N_{T} \cdot 9 \cdot \frac{lb}{day} \cdot T_{S}$$

$$W_{F31} = 27.121$$
 elton

$$W_{F32} := .0009598 \cdot \frac{lton}{day} \cdot T_S \cdot N_T$$

$$W_{F32} = 6.479$$
 •lton

$$W_{F10} := 236 \cdot lb \cdot N_E + 400 \cdot lb \cdot (N_O + 1)$$
  $W_{F10} = 17.08 \cdot lton$ 

$$W_T := W_{LS} + W_{F41} + W_{F42} + W_{F20} + W_{F46} + W_{F52} + W_{F31} + W_{F32} + W_{F10}$$

$$W_T = 6131.108$$
 elton

Weight Balance: ERR WEIGHT := 
$$\frac{\Delta_{FL} - W_T}{W_T}$$
 ERR WEIGHT = -0.125335 %

#### Weights Independent of the Design Variables:

$$\begin{array}{l} w_{1ND} \coloneqq w_{BM} + w_{B} + w_{237} + w_{3} + w_{P400} + w_{498} + w_{5} + w_{6} + w_{7} \dots \\ + w_{DH} + w_{180} + w_{165} + w_{F31} + w_{F32} + w_{F10} \end{array}$$

### VI. Stability

# VI1. Calculate Light Ship Weight Group Moments:

ip

<u>Weigh</u> t	<u>VCG</u>		<b>Product</b>
W <sub>BH</sub> = 995.839 •lton	$VCG_1 := .527 \cdot D_{10}$	VCG <sub>1</sub> = 16.513 oft	$P_1 := W_{BH} \cdot VCG_1$
W <sub>DH</sub> = 336.553 •lton	$VCG_2 := D_{10} + 1.5 \cdot H_{DK}$	VCG <sub>2</sub> = 44.834 oft	$P_2 := W_{DH} \cdot VCG_2$
W <sub>180</sub> = 127.844 •lton	VCG <sub>3</sub> := .68·D <sub>10</sub>	VCG <sub>3</sub> = 21.307 oft	$P_3 := W_{180} \cdot VCG_3$
$W_{171} = 17.555$ elton	VCG <sub>4</sub> := 2.65·D <sub>10</sub>	$VCG_4 = 83.036  \text{eft}$	$P_4 := W_{171} \cdot VCG_4$
$P_{100} := P_1 + P_2 + P_3$	+ P <sub>4</sub>	VCG <sub>100</sub> :=	$= \frac{P_{100}}{W_1}  VCG_{100} = 22.843 \text{ eft}$
W <sub>BM</sub> = 412.728 •lton	$VCG_5 := .5 \cdot D_{10}$	VCG <sub>5</sub> = 15.667 oft	$P_5 := W_{BM} \cdot VCG_5$
W <sub>ST</sub> = 114.103 •lton	$VCG_6 := 3.9 \cdot ft + .19 \cdot T$	VCG <sub>6</sub> = 6.237 oft	$P_6 := W_{ST} \cdot VCG_6$
W <sub>237</sub> = 0 •lton	VCG <sub>7</sub> := VCG <sub>237</sub>	$VCG_7 = 0$ oft	$P_7 := W_{237} \cdot VCG_7$
$P_{200} := P_5 + P_6 + P_7$	$VCG_{200} := \frac{P_{200}}{W_2}$ $VCC$	G 200 = 13.625 at	
W <sub>3</sub> = 339.26 •lton	VCG <sub>8</sub> := .65·D <sub>10</sub>	VCG <sub>8</sub> = 20.367 oft	$P_8 := W_3 \cdot VCG_8$
W <sub>IC</sub> = 30.626 •lton	VCG <sub>9</sub> :=D <sub>10</sub>	VCG <sub>9</sub> = 31.334 oft	$P_9 := W_{IC} \cdot VCG_9$
$W_{CO} = 14.753$ olton	$VCG_{10} := 5.6 \cdot \Re + .4625 \cdot D_{10}$	VCG <sub>10</sub> = 20.092 •ft	$P_{10} := W_{CO} \cdot VCG_{10}$
$W_{CC} = 7.741$ elton	$VCG_{11} := .5 \cdot D_{10}$	VCG <sub>11</sub> = 15.667 oft	$P_{11} := W_{CC} \cdot VCG_{11}$
$W_{.498} = 87.9$ •lton	VCG <sub>12</sub> := VCG <sub>498</sub>	VCG <sub>12</sub> = -1.2 at	$P_{12} := W_{498} \cdot VCG_{12}$
$W_{AUX} = 503.173$ •lton	$VCG_{13} := .9 \cdot (D_{10} - 7.4 \cdot ft)$	VCG <sub>13</sub> = 21.541 oft	$P_{13} := W_{AUX} \cdot VCG_{13}$
W <sub>517</sub> = 4.518 •lton	$VCG_{14} := .5 \cdot H_{MB}$	VCG <sub>14</sub> = 15.667 नी	$P_{14} := W_{517} \cdot VCG_{14}$
W <sub>OFH</sub> = 234.528 •lton	VCG <sub>15</sub> := .805·D <sub>10</sub>	VCG <sub>15</sub> = 25.224 oft	$P_{15} := W_{OFH} \cdot VCG_{15}$
$W_{OFP} = 112.4$ olton	$VCG_{16} := 8 \cdot ft + .71 \cdot D_{10}$	VCG <sub>16</sub> = 30.247 eft	$P_{16} := W_{OFP} \cdot VCG_{16}$
$ip := 116$ $P_{WG} := \sum P_{in} + \frac{1}{2} P_{in} + $	+ W <sub>P</sub> ·VCG <sub>P</sub> - W <sub>VP</sub> ·VCG <sub>VP</sub>	P <sub>WG</sub> = 80422.723	s elton∙ft
440 <del>/ 1</del> 9			

#### V!2. Light Ship KG

$$VCG_{LS} := \frac{P WG}{\sum_{i1}} VCG_{LS} = 20.978 \text{ eft} KG_{LS} := VCG_{LS} KG_{LS} = 20.978 \text{ eft}$$

#### VI3. Calculate Variable Load Weight Group Moments:

Weigh t	<u>VCG</u>		Product
$W_{F10} = 17.08$ •lton	VCG <sub>17</sub> := .746 D <sub>10</sub>	VCG <sub>17</sub> = 23.375 oft	$P_{17} := W_{F10} \cdot VCG_{17}$
$W_{F31} = 27.121$ elton	VCG <sub>18</sub> := .55·D <sub>10</sub>	VCG <sub>18</sub> = 17.234 oft	$P_{18} := W_{F31} \cdot VCG_{18}$
$W_{F32} = 6.479$ elton	VCG <sub>19</sub> := .65·D <sub>10</sub>	VCG <sub>19</sub> = 20.367 oft	$P_{19} := W_{F32} \cdot VCG_{19}$
$W_{F41} = 1582.439$ olton	VCG <sub>20</sub> := 7.5·ft	$VCG_{20} = 7.5  \text{eft}$	$P_{20} := W_{F41} \cdot VCG_{20}$
$W_{F42} = 63.8$ olton	VCG <sub>21</sub> := 10. ft	VCG <sub>21</sub> = 10 oft	$P_{21} := W_{F42} \cdot VCG_{21}$
$W_{F46} = 7.2$ elton	VCG <sub>22</sub> := .35·D <sub>10</sub>	VCG <sub>22</sub> = 10.967 <b>eft</b>	$P_{22} := W_{F46} \cdot VCG_{22}$
$W_{F52} = 22.5$ elton	VCG <sub>23</sub> := 7.5·ft	VCG <sub>23</sub> = 7.5 oft	$P_{23} := W_{F52} \cdot VCG_{23}$
iL := 17 2	P <sub>WGL</sub> = 21193.169 •lton ft		
	$w_{F20} + w_{F46} + w_{F52} + w_{F31} + w_{F31}$		$W_L = 1914.079$ •lton
	7	$VCG_L := \frac{PWGL}{W_L}$	VCG <sub>L</sub> = 11.072 •ft

#### VI4. Calculate Ship Stability Characteristics:

$$KG_{MARG} := .5 \cdot ft \quad KG := \frac{W_{LS} \cdot KG_{LS} + W_{L} \cdot VCG_{L}}{W_{T}} + KG_{MARG} \quad C_{IT} := -.497 + 1.44 \cdot C_{W} \quad C_{IT} = 0.493$$

$$KB := \frac{T}{3} \cdot \left( 2.5 - \frac{C_{P} \cdot C_{X}}{C_{W}} \right) \quad BM := \frac{LWL \cdot B^{3} \cdot C_{IT}}{12 \cdot V_{FL}} \quad GM := KB + BM - KG \quad C_{GMB} := \frac{GM}{B}$$

$$KG = 18.386 \cdot ft \qquad KB = 7.711 \cdot ft \quad BM = 16.252 \cdot ft \quad GM = 5.577 \cdot ft \quad C_{GMB} = 0.123$$

VIL VERY SIMPLIFIED COST MODEL (Lead-Ship End Cost only)

Mdol:=coul

Bdol:=1000·Mdol

V!!1. Additional charcteristics:

Ship Service Life:

 $L_{S} := 30$ 

**Initial Operational Capability:** 

 $Y_{IOC} := 1998$ 

**Total Ship Acquisition:** 

 $N_S := 25$ 

Production Rate (per year):

 $R_p := 3$ 

Inflation:

Base Year:

Y<sub>R</sub>:=1998

 $iy := 1.. Y_B - 1981$ 

Average Inflation Rate (%):

(from 1981)

 $F_{I} := \prod_{iv} \left( 1 + \frac{R_{I}}{100} \right)$   $F_{I} = 2.292$ 

a. Lead Ship Cost - Shipbuilder Portion:

SWBS costs: (See Table 5 for K N factors)

Structure

$$K_{N1} := \frac{.55 \cdot Mdol}{lton^{.772}}$$

$$C_{L_1} := .03395 \text{ F}_{1} \cdot K_{N1} \cdot (W_1)^{.772}$$

$$C_{L_1} = 12.51 \text{ } \cdot \text{Mdol}$$

+ Propulsion

$$K_{N2} := \frac{1.2 \text{ Mdol}}{\text{hp.}^{808}}$$

$$C_{L_2} = .00186 F_1 K_{N2} P_{IBRAKE}^{.808}$$

+ Electric

$$K_{N3} := \frac{1.0 \cdot Mdol}{lton^{.91}}$$

$$C_{L_3} := .07505 \cdot F_1 \cdot K_{N3} \cdot (W_3)^{.91}$$

+ Command, Control, Surveillance

$$K_{N4} := \frac{2.0 \cdot Mdol}{lton^{.617}}$$

$$C_{L_4} := 10857 \cdot F_1 \cdot K_{N4} \cdot (W_4)^{.617}$$

(less payload GFM cost)

+ Auxiliary

$$K_{N5} := \frac{1.5 \cdot Mdol}{lton^{.782}}$$

$$C_{L_s} := .09487 \cdot F_I \cdot K_{N5} \cdot (W_5)^{.782}$$

+ Outfit

$$K_{N6} := \frac{1.0 \cdot Mdol}{lton^{.784}}$$

$$C_{L_6} := .09859 \cdot F_{I} \cdot K_{N6} \cdot (W_6)^{.784}$$

$$K_{N7} := \frac{1.0 \cdot Mdol}{1 ton^{.987}}$$

$$K_{N7} := \frac{1.0 \cdot Mdol}{1 \cdot con^{.987}}$$
  $C_{L_7} := .00838 \cdot F_1 \cdot K_{N7} \cdot (W_7)^{.987}$   $C_{L_7} = 2.119 \cdot Mdol$ 

$$C_{L_7} = 2.119 \, \text{Mdo}$$

(Less payload GFM cost)

#### + Margin Cost:

$$C_{LM} := \frac{W_{M24}}{\left(W_{LS} - W_{M24}\right)} \cdot \left(\sum_{i1} C_{L_{i1}}\right)$$

C<sub>LM</sub> = 19.807 •Mdol

#### + Integration/Engineering: (Lead ship includes detail design engineering for class)

$$K_{N8} := \frac{10.0 \cdot Mdol}{Mdol^{1.099}}$$

$$K_{N8} := \frac{10.0 \cdot \text{Mdol}}{\text{Mdol}^{1.099}}$$
  $C_{L_8} := .034 \cdot K_{N8} \cdot \left( \sum_{i,1} C_{L_{i1}} + C_{LM} \right)^{1.099}$   $C_{L_8} = 126.231 \cdot \text{Mdol}$ 

#### + Ship Assembly and Support: (Lead ship includes all tooling, jigs, special facilities for class)

$$K_{N9} := \frac{2.0 \cdot Mdol}{(Mdol)^{\cdot 839}}$$

$$K_{N9} := \frac{2.0 \cdot Mdol}{(Mdol)^{.839}}$$
  $C_{L_9} := .135 \cdot K_{N9} \cdot \left(\sum_{i1} C_{L_{i1}} + C_{LM}\right)^{.839}$ 

#### = Total Lead Ship Construction Cost: (BCC) :

$$C_{LCC} := \sum_{i1} C_{L_{i1}} + C_{L_{g}} + C_{L_{9}} + C_{LM}$$

$$C_{LCC} = 368.828 \text{ } \cdot \text{Mdol}$$

#### + Profit:

$$F_{PROFIT} := .10$$
  $C_{LP} := F_{PROFIT} \cdot C_{LCC}$   $C_{LP} = 36.883$  •Mdol

#### = Lead Ship Price :.

$$P_L = C_{LCC} + C_{LP}$$

#### + Change Orders:

$$C_{LCORD} := .12 \cdot P_L$$

#### = Total Shipbuilder Portion:

$$C_{SB} := P_L + C_{LCORD}$$
  $C_{SB} = 454.396 \text{ } \text{ } \text{Mdol}$ 

#### b. Lead Ship Cost - Government Portion

$$C_{I.OTH} := .025 \cdot P_{I}$$

$$C_{LOTH} := .025 \cdot P_{L}$$
  $C_{LOTH} = 10.143 \cdot Mdol$ 

$$C_{LPMG} := .1 \cdot P_{L}$$

$$C_{LPMG} := .1 \cdot P_{L}$$
  $C_{LPMG} = 40.571 \cdot Mdol$ 

Costed Military Payload:

$$W_{MP} := W_4 + W_7 + W_{F20} - W_{IC} - W_{F23}$$

W<sub>MP</sub> = 550.634 •lton

+ Ordnance and Electrical GFE: (Military Payload GFE)

$$C_{LMPG} := \left(.319 \cdot \frac{Mdol}{lton} \cdot W_{MP} + N_{HELO} \cdot 18.71 \cdot Mdol\right) \cdot F_{I}$$

C<sub>LMPG</sub> = 488.366 •Mdol

+ HM&E GFE (boats, IC):

$$C_{I,HMFG} := .02 \cdot P_{I}$$

C<sub>LHMEG</sub> := .02 P<sub>L</sub> C<sub>LHMEG</sub> = 8.114 •Mdol

+ Outfitting Cost:

$$C_{IOIIT} := .04 \cdot P_{I}$$

 $C_{LOUT} := .04 \cdot P_{L}$   $C_{LOUT} = 16.228 \cdot Mdol$ 

= Total Government Cost:

c. Total End Cost: (Must always be less than SCN appropriation)

\* Total End Cost:

$$C_{LEND} := C_{SB} + C_{LGOV}$$

C<sub>LEND</sub> = 1017.818 • Mdol

## SUMMARY: FINAL SYSTHESIS DESIGN

#### ITERATION WEIGHT:

$$W_{FL} = 6123.424$$
 olton

$$W_{FL} \equiv inl_1 \cdot lton$$

#### GROSS CHARACTERISTICS:

$$C_{\Delta L} = 55 \cdot \frac{\text{lton}}{\text{ft}^3} \qquad (45 - 65)$$

$$C_{V} := \frac{V_{FL}}{LWL^3}$$

$$C_{V} = 1.15 \cdot 10^{-3}$$

$$C_V := \frac{V_{FL}}{LWL^3}$$
  $C_V = 1.15 \cdot 10^{-3}$   $V_{FL} = 108340.212 \cdot tt^3$ 

$$B = 45.502 \cdot \text{ft}$$
  $T = 12.298 \cdot \text{ft}$   $C_{LB} = 10$ 

$$(7.5 - 10)$$

$$V_{FL} \equiv B \cdot T \cdot LWL \cdot C_X \cdot C_P$$

$$V_{FL} = 108340.212 \cdot ft^3$$

#### **ENERGY BALANCE:**

$$P_{I} = 102626 \circ hp$$

$$P_{IREQ} = 60939.774 \text{ ohp}$$

$$kW_G = 3000 \text{ e}kW$$

 $E \equiv in2_4 \cdot knt \cdot hr$ 

#### AREA/VOLUME BALANCE:

$$V_D \equiv .0025 \cdot LWL^3$$

$$V_T = 637364.335 \cdot ft$$

$$V_T = 637364.335 \cdot \text{ft}^3$$
  $V_{MB} = 52180.608 \cdot \text{ft}^3$ 

$$V_{TR} = 431499.519 \cdot ft^3$$

$$V_{DMIN} = 47103.26 \, \text{eft}^3$$

$$V_{HT} = 401848.037 \cdot \text{ft}^3 \quad V_{AUX} = 62616.73 \cdot \text{ft}^3$$

$$V_{AIIY} = 62616.73 \cdot ft^{-3}$$

$$V_{TA} = 444784.103 \cdot ft^3$$

$$V_{DMAX} = 235516.298 \text{ eft}^3$$

$$V_{TK} = 77782.894 \cdot \hat{n}^3$$

$$D_{10} = 31.334$$
 of (Must be > D<sub>10MIN</sub>)

$$D_{10MIN} = 30.334 \text{ eft}$$

$$A_{TR} = 47944.391 \cdot \text{ft}^2$$
  $A_{HR} = 34517.285 \cdot \text{ft}^2$   $A_{DR} = 13427.106 \cdot \text{ft}^2$ 

$$A_{HR} = 34517.285 \cdot ft^2$$

$$A_{DD} = 13427.106 \cdot \text{ft}^2$$

$$A_{TA} = 49420.456 \cdot ft^2$$

$$A_{TA} = 49420.456 \cdot \text{ft}^2$$
  $A_{HA} = 23251.978 \cdot \text{ft}^2$   $A_{DA} = 26168.478 \cdot \text{ft}^2$ 

$$A_{DA} = 26168.478 \cdot \text{ft}^2$$

#### WEIGHT BALANCE:

$$W_{FL} = 6123.424$$
 olton  $W_{T} = 6131.108$  olton

$$W_1 = 1563.49$$
 olton

$$W_5 = 642.883$$
 olton

$$W_{LS} = 4217.029$$
 olton

$$W_2 = 526.831$$
 olton

$$W_6 = 354.668$$
 olton

$$W_P = 668.3$$
 elton

$$W_3 = 339.26$$
 •lton

$$W_7 = 117.37$$
 elton

$$W_{F41} = 1582.439$$
 olton

$$W_4 = 289.161$$
 olton

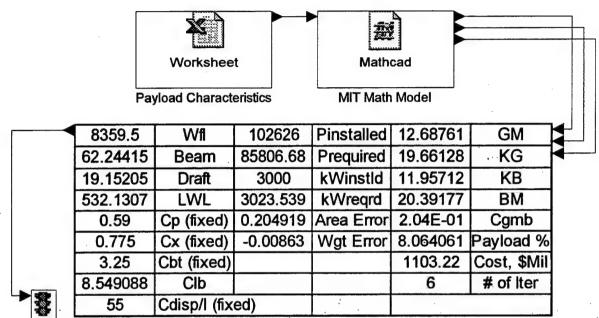
#### STABILITY/PAYLOAD:

$$C_{GMB} = 0.123$$
 (.09 - .122)

$$F_P := \frac{W_P}{W_{EI}} \cdot 100$$
  $F_P = 10.9138$ 

$$F_P = 10.9138$$

# NON-OPTIMZED MATH MODEL



**End of Analysis** 

Final Design Summary, Without Optimization

#### MIT MATH MODEL: NO OPTIMIZATION

$$hp = \frac{33000 \cdot ft \cdot lbf}{min} \qquad knt = 1.69 \cdot \frac{ft}{sec}$$

lton≡2240·lb

#### L INPUT

# = Primary Input Variables

## = Check after every iteration

I1. Requirements:

Payload: (From CS2MP.XLS, Fig 1&2)

 $W_P := in0$ , ·lton

variable:

 $W_{VP} := in0_2 \cdot lton$ 

Payload VCG:

 $VCG_P := in0_3 \cdot ft$ 

Variable Payload VCG:

 $VCG_{VP} := in0_{\checkmark} ft$ 

Command and Surveillance Payload: (W<sub>400</sub> less 420 and 430)

 $W_{P400} := in0_{5} \cdot lton$ 

Armament (all W <sub>700</sub>):

 $W_7 := in0_6 \cdot lton$ 

Armor:  $W_{164} := in0_7 \cdot lton$ 

Mission handling/support:  $W_{P500} := in0_{g} \cdot lton$ 

Mission outfit:  $W_{P600} := in0_9 \cdot lton$ 

Ordnance: W<sub>F20</sub> := in0<sub>10</sub>·lton (incl helo wt, WF23)

Helo Fuel:

 $W_{F42} := in0_{11} \cdot lton$ 

Helo's:

 $N_{HELO} := 2$   $W_{F23} := 12.73 \cdot Iton$ 

Payload Cruise Electric Power Requirement:

 $kW_{PAY} := in0_{12} \cdot kW$ 

Payload Deck Areas:

Deckhouse:

**C&D:**  $A_{DPC} := in0_{13} \cdot ft^2$ 

(W400)

Armament:

 $A_{DPA} := in0_{14} \cdot ft^2$ 

(W500, W600, W700, WF20)

Hull:

**C&D:**  $A_{HPC} := in0_{15} \cdot ft^2$ 

(W400)

Armament:  $A_{HPA} := in0_{16} \cdot ft^2$ 

(W500, W600, W700, WF20)

Manning:

Officers:  $N_O := 15$  Enlisted:  $N_E := 135$  Total:  $N_T := N_E + N_O$   $N_T = 150$ 

Average deck height:

 $H_{DK} := 9 \cdot \hat{\mathbf{n}}$ 

Sustained Speed:

 $V_S = 27 \text{ eknt}$ 

(Use Figure 3 as a guide in selecting V )

Endurance Speed:

 $V_e = 20$  eknt

Range:  $E = 7500 \text{ sknt} \cdot \text{hr}$ 

Stores period:

 $T_S := 45 \cdot day$ 

Sonar Dome/Appendages:

SOS-56 Sonar:

 $A_{SD} := 215 \cdot ft^2$  (SQS-56: 27ft<sup>2</sup>; SQS-53C: 215ft<sup>2</sup>)

water:  $W_{408} := 87.9 \cdot 1 \text{ton}$  VCG  $_{498} := -1.2 \cdot \hat{\text{t}}$  structure:  $W_{165} := 85.7 \cdot 1 \text{ton}$ 

Fin Stabilizers: (for one pair, electric power requirement = 50 kW)

 $kW_{fins} := 0.kW$ 

Hull Material: (OS: C HMAT=1.0; HTS: C HMAT=0.93)

 $C_{HMAT} := .93$ 

CPS: (W CPS=30lton):

 $W_{CPS} := 30 \cdot \text{lton}$  (ie. no CPS)

Machinery:

Number of propellers =  $N_P := 2$   $C_{PROPD} := if(N_P > 1, 1.0, 1.2)$   $C_{PROPD} = 1$ 

Aux Propulsion (APU):

 $W_{237} := 0 \cdot lton$ 

 $VCG_{237} := 0.ft$ 

Propulsion Engines (PE) - standard LM2500's; Generator engines DDA149TI

Number and brake horsepower of propulsion engines:

 $N_{PENG} := 4$   $P_{BPENG} := 26450 \cdot hp$ 

Inlet/exhaust Xsect area for PE:

 $A_{TE} := 135.2 \cdot ft^2$   $A_{PIE} := N_{PENG} \cdot A_{IE}$   $A_{PIE} = 540.8 \cdot ft^2$ 

Deckhouse decks impacted by propulsion and generator inlet/exhaust:

Hull decks impacted by propulsion inlet/exhaust:

 $N_{\text{HPIE}} := 0$ 

Machinery Box:

 $H_{MBMIN} := 22 \cdot ft$   $L_{MB} := 40 \cdot ft$ 

 $C_{P} = 0.59$   $C_{MB} := \frac{L_{MB}}{L_{WI}}$   $C_{MB} = 0.075$   $C_{PMB}$  from Fig. 10:  $C_{PMB} := .998$ 

**Ship Service Generators:** 

 $N_G := 3$   $kW_G := 3000 \cdot kW$ 

Hull decks impacted by generator inlet/exhaust:

Specific fuel rate for generator engines:

 $FR_G := \frac{.288}{2.54} \cdot \frac{lb}{kW \cdot hr}$   $FR_G = 0.085 \cdot \frac{lb}{hp \cdot hr}$ 

Inlet/exhaust X-sect area for gen:

 $A_{GIE} := 38.4 \cdot ft^2$   $A_{eIE} := N_{G} \cdot A_{GIE}$   $A_{eIE} = 115.2 \cdot ft^2$ 

IL GROSS CHARACTERISTICS

**Hull Principle Characteristics:** 

(see Figures 5 and 6)

Adjust in Summary

LWL = 532.131 eft B = 62.244 eft

 $C_{p} = 0.59$   $C_{X} = 0.775$ 

Section at end of file

deckhouse volume:  $V_D = 190000 \text{ eft}^3$   $C_{DHM\Delta T} := 2$ 

(Deckhouse Material: Aluminum - C DHMAT=1; Steel - C DHMAT=2)

#### II1. Complete Principle Characteristics:

Choose Payload Weight Fraction from Figure 4 and Calculate Full Load Weight (1st Iteration only, set  $W_{FL}=W_{FL1}$  in Summary section at end of file).

$$F_P := .1$$
  $W_{FL1} := \frac{W_P}{F_P}$   $W_{FL1} = 6683$  •lton

Specify Full Load Weight (subsequent iterations set W FL=WT from prior iteration in Summary at end of file):

$$W_{FL} = 8287.388 \text{ elton}$$
  $V_{FI} := B \cdot T \cdot LWL \cdot C_{P} \cdot C_{Y}$ 

Calculate Full Load Displacement and Volume at LWL:

$$\Delta_{FL} := W_{FL}$$
  $V_{FL} := \Delta_{FL} \cdot 35 \cdot \frac{\text{ft}^3}{\text{Iton}}$   $V_{FL} = 290058.58 \cdot \text{ft}^3$ 

##

Calculate Draft (LWL):

$$T := \frac{V_{FL}}{C_{P} \cdot C_{X} \cdot LWL \cdot B}$$
 
$$T = 19.152 \text{ eft}$$

II2. Calculate Displacement to Length Ratio and Compare to Figure 5:

$$C_{\Delta L} := \frac{\Delta_{FL}}{\left(\frac{LWL}{100}\right)^3} \qquad C_{\Delta L} = 55 \frac{lton}{st^3}$$
 (45-65)

II3. Calculate Speed to Length Ratio and C v:

$$R_{VL} := \frac{V_S}{\sqrt{LWL}}$$
  $R_{VL} = 1.17 \cdot \frac{knt}{ft^5}$   $C_V := \frac{V_{FL}}{LWL^3}$   $C_V = 0.001925$ 

II4. Calculate Beam to Draft Ratio and Compare to Tables 1-4:

$$C_{BT} := \frac{B}{T}$$
  $C_{BT} = 3.25$  (2.8-3.7)

II5. Calculate Length to Beam Ratio:

$$C_{LB} := \frac{LWL}{R}$$
  $C_{LB} = 8.549$  (7.5-10)

#### III. ENERGY (Uses Taylor Standard Series (TSS)

References: DDS 051-1 and Taylor Reanalysis by Gertler

III1. Calculate TSS Resistance:

III1.1 Estimate propeller diameter and frontal area of ship:

$$C_{PROPD} = 1$$
  $D_P := (.662 \cdot T + .012 \cdot LWL) \cdot C_{PROPD}$   $D_P = 19.064 \cdot ft$ 

Frontal area of ship =  $A_W := B \cdot (3 \cdot T)$   $A_W = 3576.308 \cdot ft^2$   $\rho_A := .0023817 \cdot \frac{slug}{ft^3}$ 

III1.2 Seawater propereties:

$$T_{SW} := 59$$
  $\rho_{SW} := 1.9905 \cdot \frac{\text{slug}}{\text{ft}^3}$   $\nu_{SW} := 1.2817 \cdot 10^{-5} \cdot \frac{\text{ft}^2}{\text{sec}}$ 

III1.3 Resistance calculation parameters:

Correlation Allowance: 
$$C_A := .0005$$
  $C_P = 0.59$ 

Use Figure 7 with  $C_P$  and  $C_{BT}$  for TSS wetted surface coeficient:  $C_{BT} = 3.25$ 
 $C_{BT} = 3.25$ 

 $S_S := S_{TSS}$ 

$$S_{TSS} := C_{STSS} \cdot V_{FL}^{.5} \cdot LWL^{.5}$$
  $S_{TSS} = 31506.581 \cdot R^2$ 

Use Figure 8 or 9 with LWL for Appendage Drag Coeficient:

LWL = 532.131 eft
$$C_{DAPP} := 2.85 \frac{\text{hp} \cdot 10^{-5}}{\text{ft}^2 \cdot \text{kpt}^3}$$
 ##

Air Drag Coeficient:

1.517

Specify or estimate actual ship surface area:

$$C_{AA} := .7$$

Power Margin Factor (margin for concept design = 10%):

$$PMF := 1.05$$

III1.4 Use range of ship speeds for speed to length ratios (R i). Reynold's numbers (RN i) and ITTC friction (RF i):

##

# III1.5 Use Gertler with C $_{P}$ , $C_{V}$ , $R_{i}$ and $C_{BT}$ to interpolate for $C_{R}$ and calcualte TSS resistance:

Form Factor:

$$FF := \frac{4}{3} \cdot (C_{BT} - 3)$$
  $FF = 0.333$ 

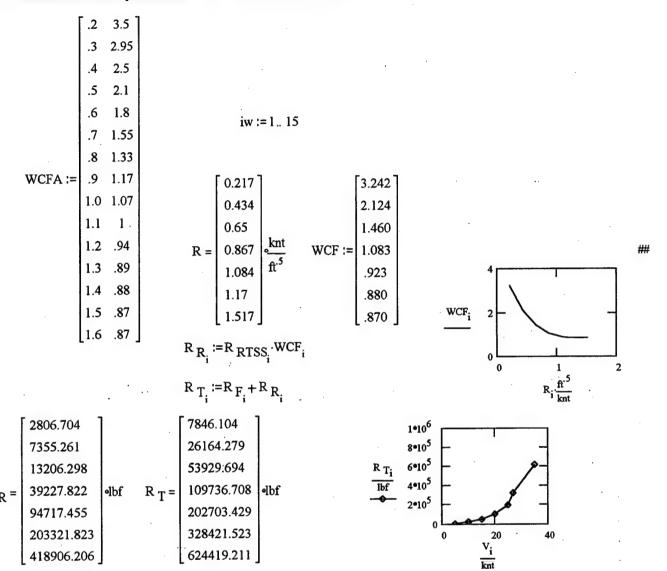
$$C_{RTSS_{i}} := C_{R3.00_{i}} + FF \cdot \left( \frac{C_{R3.75_{i}} - C_{R2.25_{i}}}{2} \right) + FF^{2} \cdot \left( \frac{C_{R2.25_{i}} + C_{R3.75_{i}}}{2} - C_{R3.00_{i}} \right)$$

$$C_{RTSS} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0.001 \\ 0.002 \\ 0.004 \\ 0.004 \end{bmatrix}$$

$$R_{RTSS_{i}} := .5 \cdot \left[ \rho_{SW} \cdot S_{S} \cdot (V_{i})^{2} \cdot C_{RTSS_{i}} \right]$$

$$R_{RTSS} = \begin{bmatrix} 865.732 \\ 3462.929 \\ 9045.41 \\ 36221.442 \\ 102619.128 \\ 231047.526 \\ 481501.386 \end{bmatrix}$$

### III2 Calculate Bare Hull Ship Resistance - Worm Curve data from ASSET:



# III3. Total Ship Effective Horsepower:

hull: 
$$P_{EBH_{i}} := R_{T_{i}} \cdot V_{i}$$
  $\frac{P_{EBH}}{hp} = \begin{bmatrix} 120.545 \\ 803.957 \\ 2485.669 \\ 6743.82 \\ 15571.309 \\ 27247.044 \\ 67153.448 \end{bmatrix}$ 

$$\mathbf{appendage:} \qquad \mathbf{P}_{\ EAPP_{\mathbf{i}}} \coloneqq \left( \mathbf{LWL \cdot D}_{\ P} \cdot \mathbf{C}_{\ DAPP} + .5 \cdot \mathbf{C}_{\ SD} \cdot \mathbf{\rho}_{\ SW} \cdot \mathbf{A}_{\ SD} \right) \cdot \left( \mathbf{V}_{\mathbf{i}} \right)^{3}$$

101.866

air:

$$P_{ET_{i}} := P_{EBH_{i}} + P_{EAPP_{i}} + P_{EAA_{i}}$$

$$P_{ET}_{i} := P_{EBH_{i}} + P_{EAPP_{i}} + P_{EAA_{i}}$$

$$EHP_{i} := PMF \cdot P_{ET_{i}}$$

$$\frac{V_{i}}{knt}$$

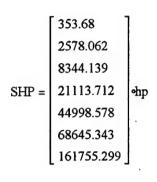
$$\frac{S}{10}$$

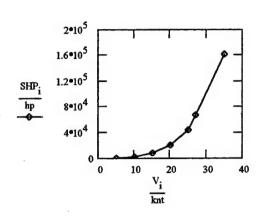
$$\frac{S$$

#### III4. Shaft Horsepower:

Approximate Propulsive Coeficient (PC):

$$SHP_i := \frac{EHP_i}{PC}$$





Endurance Shaft Horsepower:

$$P_e := SHP_4$$

$$P_e = 21113.712 \text{ ohp}$$

Sustained Speed Installed Shaft Horsepower Required (Allows for fouling and sea state):

$$P_S := SHP_6$$

$$P_S := SHP_6$$
  $P_S = 68645.343 hp$ 

$$P_{IREO} = 1.25 \cdot P_{S}$$

$$P_{IREQ} = 1.25 \cdot P_{S}$$
  $P_{IREQ} = 85806.678 \cdot hp$ 

Actual installed SHP must be greater than P IREO

$$P_{IBRAKE} := N_{PENG} \cdot P_{BPENG}$$
  $P_{IBRAKE} = 105800 \cdot hp \eta := .97$ 

$$P_{IBRAKE} = 105800 \text{ shp } \eta := .9$$

$$P_{I} := \eta \cdot P_{IBRAKE}$$

$$P_{I} = 102626 \circ$$

$$(P_I \text{ must be} > P_{IREQ})$$
  $P_I$ 

(P<sub>I</sub> must be > P<sub>IREQ</sub>) 
$$P_{IREQ} = 85806.678 \text{ ohp}$$
  $ERR_{POWER} := \frac{P_{I} - P_{IREQ}}{P_{IREQ}}$   $ERR_{POWER} = 0.196$ 

##ck

III5. Estimate Propulsion Fuel Required:

Reference: DDS 200-1 "Calculate of Surface Ship Endurance Fuel"

Average Endurance Brake SHP Required (Allows for fouling and sea state):

$$P_{eBAVG} := 1.1 \cdot \frac{P_e}{\eta}$$
  $P_{eBAVG} = 23943.385 \cdot hp$ 

Specific fuel rate for propulsion engines: (GT; FR for diesel = .327)

$$FR := 1.97 \cdot \frac{1b}{hp^{.85} \cdot hr} \cdot P_{eBAVG}^{-.15}$$
  $FR = 0.434 \cdot \frac{1b}{hp \cdot hr}$  #

$$FR = 0.434 \circ \frac{lb}{hp \cdot hr}$$
#

Margin for instrumentation and machinery differences,  $f(P_1)$ :

 $FR_{SP} := f_1 \cdot FR$ Specified fuel rate:

Average fuel rate allowing for plant deterioration:

FR AVG := 
$$1.05 \cdot \text{FR}$$
 SP FR AVG =  $0.474 \cdot \frac{\text{lb}}{\text{hp} \cdot \text{hr}}$ 

Burnable propulsion endurance fuel weight:

$$W_{BP} := \frac{E}{V_e} \cdot (P_{eBAVG} \cdot FR_{AVG})$$
  $W_{BP} = 1900.115 \text{ elton}$ 

Tailpipe allowance and propulsion endurance fuel:

$$W_{FP} := \frac{W_{BP}}{TPA}$$

$$W_{FP} = 2000.121$$
 olton

Allow for expansion and tank structure in required propulsion tank volume:

$$\gamma_{\rm F} := 43 \cdot \frac{{\rm ft}^3}{\rm lton}$$

$$V_{FP} := 1.02 \cdot 1.05 \cdot \gamma_{F} \cdot W_{FP}$$
  $V_{FP} = 92111.562 \text{ eft}^3$ 

#### III6. Estimate electric load.

Reference: DDS 310-1

#### Estimate Maximum Functional Load based on parametrics for WINTER cruise condition:

Propulsion:

$$kW_P := .00466 \cdot \frac{kW}{hn} \cdot P_{IBRAKE}$$

$$kW_P = 493.028 \text{ } \text{kW}$$

Steering:

$$kW_S := .00583 \cdot \frac{kW}{R^2} \cdot LWL \cdot T$$

$$kW_S = 59.416 kW$$

Lighting:

$$kW_L := .0002053 \cdot \frac{kW}{R^3} \cdot 1.8 \cdot LWL \cdot T \cdot B$$
  $kW_L = 234.419 \cdot kW$ 

$$kW_{L} = 234.419 \text{ ekW}$$

Miscellaneous:

$$kW_M := 46.1 \cdot kW$$

Heating:

$$kW_{H} := .0013 \frac{kW}{R^3} \cdot 1.25 \cdot LWL \cdot T \cdot B$$
  $kW_{H} = 1030.826 \cdot kW$ 

$$kW_{H} = 1030.826 \text{ e}kW$$

Ventilation:

$$kW_{CPS} := .00026 \cdot \frac{kW}{e^3} \cdot 1.8 \cdot LWL \cdot T \cdot B$$
 (zero if no CPS)  $kW_{CPS} = 296.878 \cdot kW$ 

$$kW_V := .19 \cdot (kW_H + kW_P) + kW_{CPS}$$
  $kW_V = 586.41 \cdot kW$ 

Air Conditioning:

$$kW_{AC} := .67 \cdot \left( .1 \cdot kW \cdot N_{T} + .0015 \cdot \frac{kW}{R^3} \cdot .47 \cdot 1.3 \cdot LWL \cdot T \cdot B + .1 \cdot kW_{P} \right)$$

Aux Boiler and FW: (electric boiler)

$$kW_B := .94 \cdot N_T \cdot kW$$

$$kW_B = 141 \text{ ekW}$$

Firemain:

$$kW_F := .0001 \frac{kW}{A^3} \cdot 1.8 \cdot LWL \cdot T \cdot B$$
  $kW_F = 114.184 \cdot kW$ 

Unrep and handling:

$$kW_{RH} := .00002 \cdot \frac{kW}{R^3} \cdot 1.25 \cdot LWL \cdot T \cdot B$$
  $kW_{RH} = 15.859 \cdot kW$ 

Aux Machinery:

$$kW_A := .22 \cdot N_T \cdot kW + kW_{fins}$$

Services and Work Spaces:

$$kW_{SERV} := .35 \cdot N_{T} \cdot kW$$

$$kW_{SERV} = 52.5 \text{ ekW}$$

#### Non-Payload Functional Load:

 $kW_{NP} := kW_{P} + kW_{S} + kW_{L} + kW_{M} + kW_{H} + kW_{V} + kW_{AC} + kW_{B} + kW_{F} + kW_{RH} + kW_{A} + kW_{SER}$ **Maximum Functional Load:** 

$$kW_{MFL} := kW_{PAY} + kW_{NP}$$

MFL with margins: (design,growth):

$$kW_{MFLM} := 1.2 \cdot 1.2 \cdot kW_{MFL}$$

#### Installed Electrical Power Required:

Power available per generator:

$$kW_{G} = 3000 \text{ e}kW$$

Power required per generator:

$$kW_{GREQ} := \frac{kW_{MFLM}}{(N_{G}-1)..9}$$
  $kW_{GREQ} = 3023.539 \text{ kW}$ 

$$ERR_{KW} := \frac{kW_{G} - kW_{GREQ}}{kW_{GREQ}}$$

24 hour electrical load:

$$kW_{24} := .5 \cdot (kW_{MFL} - kW_{P} - kW_{S}) + .8 \cdot (kW_{P} + kW_{S})$$
  $kW_{24} = 2055.445 \cdot kW$ 

ERR 
$$_{KW} = -0.008$$

.#ck

with margin (design):

$$kW_{24\Delta VG} := 1.2 \cdot kW_{24}$$

$$kW_{24AVG} := 1.2 \cdot kW_{24}$$
  $kW_{24AVG} = 2466.534 \cdot kW$ 

III7. Estimate Electric Fuel Rate:

FR 
$$_{G} = 0.113 \circ \frac{lb}{kW \cdot hr}$$

Margin for instrumentation and machinery differences, f(P /P<sub>I</sub>):

$$f_{1e} := 1.04$$

Specified fuel rate:

$$FR_{GSP} := f_{le} \cdot FR_{G}$$

Average fuel rate allowing for plant deterioration:

$$FR_{GAVG} := 1.05 FR_{GSP}$$

FR <sub>GAVG</sub> := 1.05 FR <sub>GSP</sub> FR <sub>GAVG</sub> = 0.124 
$$\frac{lb}{kW \cdot hr}$$
 FR <sub>GAVG</sub> = 0.092  $\frac{lb}{hp \cdot hr}$ 

FR 
$$_{GAVG} = 0.092 \cdot \frac{lb}{hp \cdot hr}$$

#### III8. Estimate Electrical and Total fuel Required

Burnable electrical endurance fuel weight:

$$W_{Be} := \frac{E}{V_{e}} \cdot (kW_{24AVG} \cdot FR_{GAVG})$$
  $W_{Be} = 51.127 \cdot elton$ 

$$W_{Be} = 51.127$$
 elton

Tailpipe allowance and electrical endurance fuel:

$$W_{Fe} := \frac{W_{Be}}{TPA}$$
  $W_{Fe} = 53.818 \text{ elton}$ 

$$W_{Fe} = 53.818$$
 eltor

Allow for expansion and tank structure in required electrical fuel tank volume:

$$V_{Fe} := 1.02 \cdot 1.05 \cdot \gamma_{F} \cdot W_{Fe}$$
  $V_{Fe} = 2478.484 \text{ eft}^3$ 

Total ship fuel: (DFM)

$$W_{F41} := W_{FP} + W_{Fe}$$
  $W_{F41} = 2053.939 \text{ elton}$   
 $V_F := V_{FP} + V_{Fe}$   $V_F = 94590.046 \text{ eft}^3$ 

#### IV. Space Estimate

#### IVA. Available Space

IVA1. Underwater Hull Volume Available

$$V_{HUW} := V_{FL}$$
  $V_{HUW} = 290058.58 \text{ eft}^3$ 

IVA2. Sheer Line. (3 criteria)

- 1) Keep deck edge above water at 25 degree heel
- 2) Longitudinal strength
- 3) Contain machinery box height:

H<sub>MBMIN</sub> = 22 oft

#ck

 $D_{0MIN} := 1.011827 \cdot T - 6.36215 \cdot \frac{10^{-6}}{ft} \cdot LWL^2 + 2.780649 \cdot 10^{-2} \cdot LWL + T \quad D_{0MIN} = 51.526 \cdot eft \quad D_0 := D_{0MIN}$ 

$$D_{20MIN} := .014 \text{ LWL} \cdot \left(2.125 + 1.25 \cdot \frac{10^{-3}}{\text{ft}} \cdot \text{LWL}\right) + T$$
  $D_{20MIN} = 39.938 \text{ eft}$   $D_{20} := D_{20MIN}$ 

IVA3. Above-Water Hull Volume

$$F_0 := D_0 - T$$
  $F_{10} := D_{10} - T$   $F_{20} := D_{20} - T$ 

$$A_{PRO} := LWL \frac{F_0 + 4 \cdot F_{10} + F_{20}}{6} \qquad F_{AV} := \frac{A_{PRO}}{LWL} \qquad F_{AV} = 20.409 \text{ sft}$$

$$D_{AV} := F_{AV} + T$$
  $D_{AV} = 39.561 \text{ eft}$  cubic #:  $CN := \frac{LWL \cdot B \cdot D_{AV}}{10^5 \cdot ft^3}$   $CN = 13.103$ 

$$C_W := .236 + .836 \cdot C_P$$
  $C_W = 0.729$ 

flare factor: 
$$f_f := .714599 + .18098 \cdot \frac{D_AV}{T} - .018828 \cdot \left(\frac{D_AV}{T}\right)^2 M_f := \begin{bmatrix} f_f \\ 1 \end{bmatrix}$$
  $f_f := \max(M_f)$   $f_f = 1.008$ 

$$V_{HAW} := LWL \cdot B \cdot F_{AV} \cdot C_{W} \cdot f_{f}$$
  $V_{HAW} = 496947.294 \text{ eft}^3$ 

IVA4. Total Hull Volume.

$$V_{HT} := V_{HUW} + V_{HAW}$$
  $V_{HT} = 787005.874 \text{ eft}^3$ 

IVA5. Size Deck House:

$$V_{DMAX} := .0025 LWL^3 V_{DMAX} = 376699.455 eft^3$$

$$V_{DMIN} := .0005 \cdot LWL^3$$
  $V_{DMIN} = 75339.891 \text{ eft}^3$ 

 $V_D = 190000 \, \text{eft}^3$ 

#ck

IVA6. Calculate Total Ship Volume

$$V_T := V_{HT} + V_D$$
  $V_T = 977005.874 \text{ eft}^3$ 

IVB. Space Requirement

IVB1. Machinery Box (assumed near midships) 
$$B_{MB} := B B_{MB} = 62.244$$
 oft

$$H_{MB} := D_{10}$$
  $L_{MB} = 40 \text{ eft}$   $A_{MB} := B \cdot T \cdot C_{X} + B \cdot (H_{MB} - T)$   $A_{MB} = 2002.156 \text{ eft}^{2}$ 

Calculate Machinery Box Volume:

$$V_{MB} := L_{MB} \cdot A_{MB} \cdot C_{PMB}$$
  $V_{MB} = 79926.062 \text{ eft}^3$   $V_{AUX} := 1.2 \cdot V_{MB}$   $V_{AUX} = 95911.274 \text{ eft}^3$ 

IVB2. Tankage

Helo:

Helo fuel weight from Payload Spreadsheet: 
$$W_{F42} = 63.8$$
 olton

Allow for tank structure and expansion:  $\gamma_{HF} := 43.\frac{ft^3}{lton}$ 

$$V_{HF} := 1.02 \cdot 1.05 \cdot W_{F42} \cdot \gamma_{HF}$$
  $V_{HF} = 2938.181 \cdot \text{ft}^3$ 

Lube Oil:

**LO weight:** 
$$W_{F46} := 7.2 \cdot lton$$

Allow for tank structure and expansion: 
$$\gamma_{LO} := 39 \cdot \frac{\text{ft}^3}{\text{Iton}}$$

$$V_{LO} := 1.02 \cdot 1.05 \cdot W_{F46} \cdot \gamma_{LO} \quad V_{LO} = 300.737 \text{ eft}^3$$

Potable Water:

**Water weight:** 
$$W_{F52} := N_{T} \cdot .15 \cdot lton$$
  $W_{F52} = 22.5 \cdot lton$ 

Allow for tank structure: 
$$\gamma_{W} := 36 \cdot \frac{ft^{3}}{1 ton}$$

$$V_W := 1.02 \cdot W_{F52} \cdot \gamma_W$$

$$V_W = 826.2 \text{ eft}^3$$

Sewage: 
$$V_{SEW} := N_T \cdot 2 \cdot ft^3$$
  $V_{SEW} = 300 \text{ eft}^3$ 

Waste Oil: 
$$V_{WASTE} := .005 \cdot V_{FL}$$
  $V_{WASTE} = 1450.293 \text{ eft}^3$ 

Clean Balast: 
$$V_{BAL} := .032 \cdot V_{FL}$$
  $V_{BAL} := 0 \cdot \text{ft}^3$   $V_{BAL} = 0 \cdot \text{ft}^3$ 

Total: (for compensated system)

$$V_{TK} := V_{F} + V_{HF} + V_{LO} + V_{W} + V_{SEW} + V_{WASTE} + V_{BAL}$$
  $V_{TK} = 100405.457 \text{ eft}^{3}$ 

#### IVB3. Payload Deck Areas

$$A_{DPR} := 1.15 \cdot A_{DPA} + 1.23 \cdot A_{DPC}$$
  $A_{DPR} = 10143.981 \text{ eft}^2$ 

$$A_{DPR} = 10143.981 \, \text{eft}^2$$

Hull payload area: (including access)

$$A_{HPR} := 1.15 \cdot A_{HPA} + 1.23 \cdot A_{HPC}$$
  $A_{HPR} = 9797.796 \cdot eft^2$ 

$$A_{LIDR} = 9797.796 \, \text{eft}^2$$

### IVB4. Living Deck Area

$$A_{COXO} := 225 \cdot ft^2$$
  $A_{DO} := 75 \cdot N_{O} \cdot ft^2$   $A_{DO} = 1125 \cdot eft^2$ 

$$A_{DL} := A_{COXO} + A_{DO}$$
  $A_{DL} = 1350 \text{ eft}^2$ 

$$A_{DL} = 1350 \, \text{eft}^2$$

Hull:

$$A_{HAB} := 50 \cdot ft^2$$
  $A_{HIL} := \left(A_{HAB} + \frac{LWL}{100} \cdot ft\right) \cdot N_T - A_{DL}$ 

$$A_{HL} = 6948.196 \, \text{eft}^2$$

#### IVB5. Hull Stores

$$A_{HS} := 300 \cdot ft^2 + .0158 \cdot \frac{ft^2}{lb} \cdot N_T \cdot 9 \cdot \frac{lb}{day} \cdot T_S$$
  $A_{HS} = 1259.85 \cdot eft^2$ 

#### **IVB6. Other Ship Functions**

#### Deckhouse:

$$A_{DM} := .05 \cdot (A_{DPR} + A_{DL})$$
  $A_{DM} = 574.699 \cdot et^2$ 

#### Bridge and Chartroom:

$$A_{DB} := 16 \cdot ft \cdot (B - 18 \cdot ft)$$

$$A_{DB} = 707.906 \text{ eft}^2$$

#### Engine Inlet/Exhaust:

$$A_{DIE} := 1.4 \cdot N_{DIE} \cdot (A_{PIE} + A_{eIE})$$
  $A_{DIE} = 918.4 \text{ eft}^2$ 

#### Hull:

#### **Ship Functions:**

$$A_{HSF} := 2500 \cdot ft^2 \cdot CN$$

$$A_{HSF} = 32758.449 \, \text{eft}^2$$

#### Engine Inlet/Exhaust:

$$A_{HIE} := 1.4 \cdot (N_{HPIE} \cdot A_{PIE} + N_{HeIE} \cdot A_{eIE})$$
  $A_{HIE} = 161.28 \text{ eft}^2$ 

#### IVB7. Total Required Area and Volume

#### Hull:

$$V_{HR} := H_{DK} \cdot A_{HR} \quad V_{HR} = 458330.139 \text{ eft}^3$$

$$\mathsf{A}_{\mathsf{DR}} \coloneqq \mathsf{A}_{\mathsf{DPR}} + \mathsf{A}_{\mathsf{DL}} + \mathsf{A}_{\mathsf{DM}} + \mathsf{A}_{\mathsf{DB}} + \mathsf{A}_{\mathsf{DIE}}$$

$$A_{DR} = 13694.986 \, \text{eft}^2$$

$$V_{DR} := H_{DK} \cdot A_{DR}$$
  $V_{DR} = 123254.878 \text{ eft}^3$ 

$$A_{TR} := A_{HR} + A_{DR}$$
  $A_{TR} = 64620.557 \text{ eft}^2$ 

$$V_{TR} := H_{DK} \cdot A_{TR}$$

$$V_{TR} = 581585.017 \, \text{eft}^3$$

#### IVC. Space Balance

$$V_D = 190000 \, \text{eft}^3$$

$$V_{DR} = 123254.878 \, \text{eft}^3$$

$$V_{HA} := V_{HT} - V_{MB} - V_{AUX} - V_{TK} V_{HA} = 510763.081 \text{ eft}^3$$

$$V_{HR} = 458330.139 \, \text{eft}^3$$

$$V_{TA} := V_{HA} + V_{D}$$

$$V_{TA} = 700763.081 \text{ eft}^3 > V_{TR} = 581585.017 \text{ eft}^3$$

$$V_{TR} = 581585.017 \, \text{eft}^3$$

$$A_{HA} := \frac{V_{HA}}{H_{DK}}$$

$$A_{HA} = 56751.453 \, \text{eft}^2$$

$$A_{HR} = 50925.571 \, \text{eR}^2$$

$$A_{DA} := \frac{V_D}{H_{DK}}$$

$$A_{DA} = 21111.111 \text{ eft}^2$$

$$A_{DR} = 13694.986 \, \text{eft}^2$$

$$A_{TA} := A_{DA} + A_{HA}$$

$$A_{TA} = 77862.565 \text{ eft}^2$$
 >  $A_{TR} = 64620.557 \text{ eft}^2$ 

$$A_{TR} = 64620.557 \, \text{eft}^2$$

$$ERR_{VOL} := \frac{V_{TA} - V_{TR}}{V_{TR}} ERR_{VOL} = 0.204919$$

ERR 
$$_{VOL} := \frac{V_{TA} - V_{TR}}{V_{TR}}$$
 ERR  $_{VOL} = 0.204919$  ERR  $_{AREA} := \frac{A_{TA} - A_{TR}}{A_{TR}}$  ERR  $_{AREA} = 0.204919$ 

### V. Weight

## V1. Propulsion (200)

Basic Machinery: 
$$W_{BM} := P_{I} \cdot \frac{lb}{hp} \cdot \left[ 9.0 + 12.4 \cdot \left( P_{I} \cdot \frac{10^{-5}}{hp} - 1 \right)^{2} \right]$$
  $W_{BM} = 412.728 \text{ elton}$ 

$$W_{BM} = 412.728$$
 •lton

$$f_S := .5$$
  $W_S := .356 \frac{\text{lton}}{\text{ft}} LWL f_S$   $W_S = 94.719 \text{ olton}$ 

## (f<sub>S</sub>=.5 for twin screws)

$$W_{PR} := .05575 \cdot lb \cdot \left(\frac{D_{P}}{ft}\right)$$
  $S_{P}$   $S_{PR} := .05575 \cdot lb \cdot \left(\frac{D_{P}}{ft}\right)$   $S_{PR} := .05575 \cdot lb \cdot \left(\frac{D_{P}}{ft}\right)$ 

## Bearings:

$$W_B := .15 \cdot (W_S + W_{PR})$$

$$W_B = 21.348$$
 olton

$$W_{ST} := W_{S} + W_{B} + W_{PR}$$

$$W_{ST} = 163.666$$
 elton

$$W_2 := W_{BM} + W_{ST} + W_{237}$$

#### V2. Electrical Plant (300)

$$W_3 := 50 \cdot lton + .03214 \cdot \frac{lton}{kW} \cdot N_G \cdot kW_G$$
  $W_3 = 339.26 \cdot lton$ 

#### V3. Command/Control/Surveillance (400)

$$W_{IC} := 4.65 \cdot CN \cdot lton$$

$$W_{IC} = 60.931$$
 olton

$$W_{CO} := 2.24 \cdot CN \cdot Iton$$

$$W_{CO} = 29.352$$
 olton

$$W_{CC} := .04 \cdot (W_{P400} + W_{IC} + W_{CO})$$
  $W_{CC} = 9.537$  •lton

$$W_{\alpha\alpha} = 9.537$$
 elton

$$W_4 := W_{P400} + W_{IC} + W_{CO} + W_{CC} + W_{498}$$

$$W_A = 335.859$$
 •lton

#### V4. Auxiliary Systems (500)

aux steam (electric aux boiler):

hotel steam:

 $Q_{HS} := 15 \cdot N_T$  distiller:  $Q_{DS} := 6.5 \cdot N_T + 250$ 

$$W_{517} = .0013 \cdot (Q_{HS} + Q_{DS}) \cdot lton$$
  $W_{517} = 4.518 \cdot lton$ 

$$W_{517} = 4.518$$
 elton

aux sys operating fluids:

$$W_{598} := .000075 \cdot V_T \cdot \frac{lton}{n^3}$$

W <sub>598</sub> = 73.275 •lton

$$W_{AUX} := \left[ .000772 \cdot \left( \frac{V_T}{ft^3} \right)^{1.443} + 5.14 \cdot \frac{V_T}{ft^3} + 6.19 \cdot \left( \frac{V_T}{ft^3} \right)^{.7224} + 377 \cdot N_T + 2.74 \cdot \frac{P_T}{hp} \right] \cdot 10^{-4} \cdot lton + 113.8 \cdot lton$$

environmental support:

$$W_{593} := 10 \cdot lton$$

$$W_{593} := 10 \cdot Iton$$
  $W_5 := W_{AUX} + W_{P500} + W_{517} + W_{593} + W_{598} + W_{CPS}$ 

V5. Outfit & Furnishings (600)

$$W_{OFH} := \left(31.4 + \frac{.0003187}{\text{ft}^3} \cdot V_T\right) \cdot \text{lton}$$

$$W_{OFH} = 342.772$$
 •lton

$$W_{OFP} := .8 \cdot (N_T - 9.5) \cdot lton$$

$$W_{OFP} = 112.4$$
 elton

$$W_6 := W_{OFP} + W_{OFH} + W_{P600}$$

$$W_6 = 462.912$$
 olton

### · V6. Structure (100)

Hull (110-140, 160, 190): 
$$W_{BH} := C_{HMAT} \cdot (1.68341 \cdot CN^2 + 167.1721 \cdot CN - 103.283) \cdot ltonW_{BH} = 2209.936 \cdot ltonW_{B$$

$$\rho_{DH} := if(C_{DHMAT}=1,.0007,.001429)$$

$$\rho_{DH} = 0.001$$

$$W_{DH} := \rho_{DH} \cdot \frac{lton}{n^3} \cdot V_D$$

$$W_{DH} = 271.51$$
 olton

$$W_{171} := .0688 \cdot \frac{lton}{ft} \cdot LWL - 13.75 \cdot lton$$

$$W_{171} = 22.861$$
 olton

$$W_{180} := .0675 \cdot W_{BM} + .072 \cdot (W_3 + W_4 + W_5 + W_7)$$
  $W_{180} = 146.986 \cdot \text{lton}$ 

$$W_{180} = 146.986$$
 elton

$$W_1 := W_{BH} + W_{DH} + W_{171} + W_{180} + W_{165} + W_{164}$$

$$W_1 = 2736.993$$
 olton

V7. Single Digit Weight Summary & Weight Balance:

$$i1 := 1, 2...7$$

$$W_{M24} := .1 \cdot \left( \sum_{i1} W_{i1} \right)$$
  $W_{M24} = 543.084 \text{ elton}$ 

$$W_{M24} = 543.084$$
 eltor

Lightship:

$$W_{LS} := \sum_{i,1} W_{i1} + W_{M24}$$
  $W_{LS} = 5973.922$  elton

Additional Loads:

$$W_{F31} := N_T \cdot 9 \cdot \frac{lb}{day} \cdot T_S$$

$$W_{F31} = 27.121$$
 elton

$$W_{F32} := .0009598 \cdot \frac{1 \text{ton}}{\text{day}} \cdot \text{T} \cdot \text{S} \cdot \text{N} \cdot \text{T}$$
  $W_{F32} = 6.479 \cdot \text{lton}$ 

$$W_{F32} = 6.479$$
 •lton

$$W_{F10} := 236 \cdot lb \cdot N_E + 400 \cdot lb \cdot (N_O + 1)$$
  $W_{F10} = 17.08 \cdot lton$ 

$$W_{F10} = 17.08$$
 eltor

$$W_T := W_{LS} + W_{F41} + W_{F42} + W_{F20} + W_{F46} + W_{F52} + W_{F31} + W_{F32} + W_{F10}$$

$$W_T = 8359.5$$
 •lton

$$ERR_{WEIGHT} := \frac{\Delta_{FL} - W_{T}}{W_{T}}$$

## VI. Stability

## VI1. Calculate Light Ship Weight Group Moments:

Weigh t	<u>VCG</u>		Product
$W_{BH} = 2209.936$ olton	$VCG_1 := .527 \cdot D_{10}$	VCG <sub>1</sub> = 19.223 at	$P_1 := W_{BH} \cdot VCG_1$
$W_{DH} = 271.51$ elton	$VCG_2 := D_{10} + 1.5 \cdot H_{DK}$	VCG <sub>2</sub> = 49.975 oft	$P_2 := W_{DH} \cdot VCG_2$
$W_{180} = 146.986$ olton	VCG <sub>3</sub> := .68·D <sub>10</sub>	VCG <sub>3</sub> = 24.803 oft	$P_3 := W_{180} \cdot VCG_3$
$W_{171} = 22.861$ olton	VCG <sub>4</sub> := 2.65·D <sub>10</sub>	VCG <sub>4</sub> = 96.66 oft	$P_4 := W_{171} \cdot VCG_4$
$P_{100} := P_1 + P_2 + P_3$	+P <sub>4</sub>	VCG <sub>100</sub> :=	$=\frac{P_{100}}{W_1}$ VCG $_{100} = 22.618$ eft
$W_{BM} = 412.728$ •lton	VCG <sub>5</sub> := .5·D <sub>10</sub>	VCG <sub>5</sub> = 18.238 oft	$P_5 := W_{BM} \cdot VCG_5$
W <sub>ST</sub> = 163.666 •lton	$VCG_6 := 3.9 \cdot ft + .19 \cdot T$	VCG <sub>6</sub> = 7.539 oft	$P_6 := W_{ST} \cdot VCG_6$
W <sub>237</sub> = 0 olton	VCG <sub>7</sub> := VCG <sub>237</sub>	$VCG_7 = 0$ oft	$P_7 := W_{237} \cdot VCG_7$
$P_{200} := P_5 + P_6 + P_7$	$VCG_{200} := \frac{P_{200}}{W_2}$ $VCC$	<sup>3</sup> <sub>200</sub> = 15.2 •ft	
$W_3 = 339.26$ •lton	VCG <sub>8</sub> := .65 D <sub>10</sub>	VCG <sub>8</sub> = 23.709 oft	$P_8 := W_3 \cdot VCG_8$
$W_{IC}$ = 60.931 •lton	VCG <sub>9</sub> :=D <sub>10</sub>	VCG <sub>9</sub> = 36.475 oft	$P_9 := W_{IC} \cdot VCG_9$
$W_{CO} = 29.352$ olton	$VCG_{10} := 5.6 \cdot ft + .4625 \cdot D_{10}$	VCG <sub>10</sub> = 22.47 oft	$P_{10} := W_{CO} \cdot VCG_{10}$
W <sub>CC</sub> = 9.537 •lton	$VCG_{11} := .5 \cdot D_{10}$	VCG <sub>11</sub> = 18.238 oft	$P_{11} := W_{CC} \cdot VCG_{11}$
$W_{498} = 87.9$ olton	VCG <sub>12</sub> := VCG <sub>498</sub>	$VCG_{12} = -1.2$ oft	$P_{12} := W_{498} \cdot VCG_{12}$
$W_{AUX} = 696.867$ •lton	$VCG_{13} := .9 \cdot (D_{10} - 7.4 \cdot \hat{\mathbf{r}})$	$VCG_{13} = 26.168 \text{ eft}$	$P_{13} := W_{AUX} \cdot VCG_{13}$
$W_{517} = 4.518$ elton	VCG <sub>14</sub> := .5 H <sub>MB</sub>	VCG <sub>14</sub> = 18.238 oft	$P_{14} := W_{517} \cdot VCG_{14}$
W <sub>OFH</sub> = 342.772 •lton	VCG <sub>15</sub> := .805·D <sub>10</sub>	VCG <sub>15</sub> = 29.363 oft	$P_{15} := W_{OFH} \cdot VCG_{15}$
W <sub>OFP</sub> = 112.4 •lton	$VCG_{16} := 8 \cdot ft + .71 \cdot D_{10}$	VCG <sub>16</sub> = 33.898 oft	$P_{16} := W_{OFP} \cdot VCG_{16}$

$$ip := 1...16$$

$$P_{WG} := \sum_{ip} P_{ip} + W_{P} \cdot VCG_{P} - W_{VP} \cdot VCG_{VP} \qquad P_{WG} = 122974.982 \text{ olton-ft}$$

#### V!2. Light Ship KG

$$VCG_{LS} := \frac{P_{WG}}{\sum_{i1}} VCG_{LS} = 22.644 \text{ eft} KG_{LS} := VCG_{LS} KG_{LS} = 22.644 \text{ eft}$$

#### VI3. Calculate Variable Load Weight Group Moments:

Weight	<u>vcg</u>		Product
$W_{F10} = 17.08$ elton	VCG <sub>17</sub> := .746 D <sub>10</sub>	VCG <sub>17</sub> = 27.211 oft	$P_{17} := W_{F10} \cdot VCG_{17}$
$W_{F31} = 27.121$ olton	VCG <sub>18</sub> := .55·D <sub>10</sub>	VCG <sub>18</sub> = 20.061 oft	$P_{18} := W_{F31} \cdot VCG_{18}$
$W_{F32} = 6.479 \text{ elton}$	VCG <sub>19</sub> := .65 D <sub>10</sub>	VCG <sub>19</sub> = 23.709 oft	$P_{19} := W_{F32} \cdot VCG_{19}$
W <sub>F41</sub> = 2053.939 •lton	VCG <sub>20</sub> := 7.5 ft	$VCG_{20} = 7.5  \text{eft}$	$P_{20} := W_{F41} \cdot VCG_{20}$
$W_{F42} = 63.8 \text{ elton}$	VCG <sub>21</sub> := 10. ft	VCG <sub>21</sub> = 10 eft	$P_{21} := W_{F42} \cdot VCG_{21}$
$W_{F46} = 7.2$ olton	VCG <sub>22</sub> :=.35·D <sub>10</sub>	VCG <sub>22</sub> = 12.766 oft	$P_{22} := W_{F46} \cdot VCG_{22}$
$W_{F52} = 22.5$ olton	VCG <sub>23</sub> := 7.5·ft	VCG <sub>23</sub> = 7.5 oft	$P_{23} := W_{F52} \cdot VCG_{23}$
iL := 17 2	$P_{WGL} := \sum_{iL} P_{iL} + W_{VP}$	VCG <sub>VP</sub>	P WGL = 24906.211 •lton-ft
$W_L := W_{F41} + W_{F42} + W_{F20} + W_{F46} + W_{F52} + W_{F31} + W_{F32} + W_{F10}$ $W_L = 2385.578 \text{ els}$			
		$VCG_L := \frac{P_{WGL}}{W_L}$	VCG <sub>L</sub> = 10.44 oft

#### VI4. Calculate Ship Stability Characteristics:

$$\begin{split} \text{KG}_{MARG} := .5 \cdot \text{ft} & \quad \text{KG} := \frac{\text{W}_{LS} \cdot \text{KG}_{LS} + \text{W}_{L} \cdot \text{VCG}_{L}}{\text{W}_{T}} + \text{KG}_{MARG} \quad \text{C}_{IT} := -.497 + 1.44 \cdot \text{C}_{W} \quad \text{C}_{IT} = 0.553 \\ \text{KB} := \frac{\text{T}}{3} \cdot \left( 2.5 - \frac{\text{C}_{P} \cdot \text{C}_{X}}{\text{C}_{W}} \right) \quad \text{BM} := \frac{\text{LWL} \cdot \text{B}^{3} \cdot \text{C}_{IT}}{12 \cdot \text{V}_{FL}} \quad \text{GM} := \text{KB} + \text{BM} - \text{KG} \quad \text{C}_{GMB} := \frac{\text{GM}}{\text{B}} \\ \text{KG} = 19.661 \text{ eft} \qquad \text{KB} = 11.957 \text{ eft} \quad \text{BM} = 20.392 \text{ eft} \quad \text{GM} = 12.688 \text{ eft} \quad \text{C}_{GMB} = 0.204 \\ \text{#ck} \end{split}$$

### VIL VERY SIMPLIFIED COST MODEL (Lead-Ship End Cost only)

Mdol:=coul

 $Kdol := \frac{Mdol}{1000}$ 

Bdol:=1000·Mdol

V!!1. Additional charcteristics:

 $L_{S} := 30$ Ship Service Life:

**Initial Operational Capability:** 

 $Y_{IOC} := 1998$ 

**Total Ship Acquisition:** 

 $N_S := 25$ 

Production Rate (per year):

 $R_P := 3$ 

Inflation:

Base Year:

 $Y_{B} := 1998$ 

 $iy := 1.. Y_B - 1981$ 

Average Inflation Rate (%):

(from 1981)

 $F_{I} := \prod_{i=1}^{n} \left( 1 + \frac{R_{I}}{100} \right)$   $F_{I} = 2.292$ 

a. Lead Ship Cost - Shipbuilder Portion:

SWBS costs: (See Table 5 for K N factors)

Structure

$$K_{N1} := \frac{.55 \cdot Mdol}{lton^{.772}}$$

$$C_{L_1} := .03395 \cdot F_1 \cdot K_{N1} \cdot (W_1)^{.772}$$

+ Propulsion

$$K_{N2} := \frac{1.2 \cdot Mdol}{hp^{.808}}$$

$$K_{N2} := \frac{1.2 \cdot \text{Mdol}}{\text{hp.}^{808}}$$
  $C_{L_2} := .00186 \cdot F_1 \cdot K_{N2} \cdot P_{IBRAKE}^{.808}$ 

+ Electric

$$K_{N3} := \frac{1.0 \cdot Mdol}{lton^{.91}}$$

$$C_{L_3} := .07505 \cdot F_1 \cdot K_{N3} \cdot (W_3)^{.91}$$

+ Command, Control, Surveillance

$$K_{N4} := \frac{2.0 \cdot Mdol}{lton^{.617}}$$

$$C_{L_4} := .10857 \cdot F_1 \cdot K_{N4} \cdot (W_4)^{.617}$$

(less payload GFM cost)

+ Auxiliary

$$K_{N5} := \frac{1.5 \cdot Mdol}{lton^{.782}}$$

$$C_{L_5} := .09487 \cdot F_{I} \cdot K_{N5} \cdot (W_5)^{.782}$$

+ Outfit

$$K_{N6} := \frac{1.0 \cdot Mdol}{lton^{.784}}$$

$$C_{L_6} := .09859 \cdot F_{I} \cdot K_{N6} \cdot (W_6)^{.784}$$

+ Armament

$$K_{N7} := \frac{1.0 \cdot Mdol}{lton^{.987}}$$

$$C_{L_7} := .00838 \cdot F_1 \cdot K_{N7} \cdot (W_7)^{.987}$$

(Less payload GFM cost)

+ Margin Cost:

$$C_{LM} := \frac{W_{M24}}{(W_{LS} - W_{M24})} \cdot \left(\sum_{i1} C_{L_{i1}}\right)$$
 $C_{LM} = 22.486 \text{ eMdol}$ 

+ Integration/Engineering: (Lead ship includes detail design engineering for class)

$$K_{N8} := \frac{10.0 \cdot Mdol}{Mdol^{1.099}}$$
  $C_{L_8} := .034 \cdot K_{N8} \cdot \left(\sum_{i1} C_{L_{i1}} + C_{LM}\right)^{1.099}$   $C_{L_8} = 145.12 \cdot Mdol$ 

+ Ship Assembly and Support: (Lead ship includes all tooling, jigs, special facilities for class)

$$K_{N9} := \frac{2.0 \cdot \text{Mdol}}{(\text{Mdol})^{.839}} \qquad C_{L_9} := .135 \cdot K_{N9} \cdot \left( \sum_{i1} C_{L_{i1}} + C_{LM} \right)^{.839} \qquad C_{L_9} = 27.501 \cdot \text{Mdol}$$

= Total Lead Ship Construction Cost: (BCC) :

$$C_{LCC} := \sum_{i,1} C_{L_{i1}} + C_{L_{g}} + C_{L_{g}} + C_{LM}$$
  $C_{LCC} = 419.97 \text{ •Mdol}$ 

+ Profit:

$$F_{PROFIT} := .10$$
  $C_{LP} := F_{PROFIT} \cdot C_{LCC} \cdot C_{LP} = 41.997 \cdot Mdol$ 

= Lead Ship Price:

$$P_{L} := C_{LCC} + C_{LP}$$

$$P_{T} = 461.967 \text{ } \circ \text{Mdol}$$

+ Change Orders:

$$C_{LCORD} := .12 \cdot P_L$$

= Total Shipbuilder Portion:

$$C_{SB} := P_L + C_{LCORD}$$
  $C_{SB} = 517.403 \cdot Mdol$ 

b. Lead Ship Cost - Government Portion

Other support: 
$$C_{LOTH} := .025 P_L$$
  $C_{LOTH} = 11.549 \circ Mdol$ 

+ Program Manager's Growth: 
$$C_{LPMG} := .1 \cdot P_L$$
  $C_{LPMG} = 46.197 \cdot Mdol$ 

Costed Military Payload: 
$$W_{MP} := W_4 + W_7 + W_{F20} - W_{IC} - W_{F23}$$
  $W_{MP} = 567.028$  elton

+ Ordnance and Electrical GFE:  
(Military Payload GFE)

$$C_{LMPG} := \left(.319 \cdot \frac{\text{Mdol}}{\text{lton}} \cdot \text{W}_{MP} + \text{N}_{HELO} \cdot 18.71 \cdot \text{Mdol}\right) \cdot \text{F}_{I}$$

$$C_{LMPG} = 500.352 \cdot \text{Mdol}$$

+ HM&E GFE (boats, IC):

 $C_{LHMEG} = .02 \cdot P_{L}$   $C_{LHMEG} = 9.239 \cdot Mdol$ 

+ Outfitting Cost:

 $C_{LOUT} := .04 \cdot P_{L}$   $C_{LOUT} = 18.479 \cdot Mdol$ 

= Total Government Cost:

C<sub>LGOV</sub> := C<sub>LOTH</sub> + C<sub>LPMG</sub> + C<sub>LMPG</sub> + C<sub>LHMEG</sub> + C<sub>LOUT</sub> C<sub>LGOV</sub> = 585.816 •Mdol

c. Total End Cost: (Must always be less than SCN appropriation)

\* Total End Cost:

 $C_{LEND} := C_{SB} + C_{LGOV}$ 

C<sub>LEND</sub> = 1103.22 •Mdol

## SUMMARY: WITHOUT OPTIMIZATION

$$W_{FL}$$
 = 8287.388·lton

$$V_{FL} = W_{FL} \cdot 35 \cdot \frac{ft^3}{lton}$$

# $W_{FL1} = 6683$ elton

$$W_T = 8359.5$$
 •lton

# **GROSS CHARACTERISTICS:**

$$C_{\Delta L} = 55 \cdot \frac{\text{lton}}{\text{ft}^3}$$
 (45 - 65)  $LWL = 100 \cdot \left(\frac{W_{FL}}{C_{\Delta L}}\right)^{\frac{1}{3}}$   $LWL = 532.131 \cdot \text{ft}$ 

$$C_V := \frac{V_{FL}}{LWL^3}$$
  $C_V = 1.925 \cdot 10^{-3}$   $V_{FL} = 290058.58 \cdot ft^3$ 

$$C_{V} = 1.925 \cdot 10^{-3}$$

$$V_{FL} = 290058.58 \cdot ft^3$$

$$C_{BT} = 3.25 (2.8 - 3.7)$$
  $B = \begin{cases} C_{BT} \cdot V_{FL} \\ C_{P} \cdot C_{X} \cdot LWL \end{cases}$   $B = 62.244 \cdot \text{ft}$   $T = 19.152 \cdot \text{ft}$   $C_{LB} = 8.549 \quad (7.5 - 10)$ 

$$B = 62.244 \cdot ft$$
  $T = 19.152 \cdot ft$ 

$$C_{LB} = 8.549$$
 (7.5 - 10)

### **ENERGY BALANCE:**

$$P_{I} = 102626 \text{ hp}$$

$$ERR_{POWER} = 0.196$$

$$kW_G = 3000 \text{ ekW}$$

kW 
$$_{GREQ}$$
 = 3023.539 kW  $_{ERR}$   $_{KW}$  = -0.008

ERR 
$$_{KW} = -0.008$$

E≡7500·knt·hr

## AREA/VOLUME BALANCE:

$$V_D \equiv 190000 \cdot ft^3$$

$$V_T = 977005.874 \cdot \text{ft}^3$$
  $V_{MB} = 79926.062 \cdot \text{ft}^3$   $V_{TR} = 581585.017 \cdot \text{ft}^3$ 

$$V_{DMIN} = 75339.891 \, \text{eR}^3$$

$$V_{HT} = 787005.874 \cdot ft^3 \quad V_{AUX} = 95911.274 \cdot ft^3$$

$$V_{TA} = 700763.081 \cdot ft^3$$

$$V_{DMAX} = 376699.455 \text{ eft}^3$$

$$V_{TK} = 100405.457 \cdot \hat{n}^3$$

$$ERR_{AREA} = 0.204919$$

D 
$$_{10}$$
 = 36.475•ft (Must be > D  $_{10MIN}$ )

$$D_{10MIN} = 35.475 \, \text{eft}$$

$$A_{TR} = 64620.557 \cdot \text{ft}^2$$
  $A_{HR} = 50925.571 \cdot \text{ft}^2$   $A_{DR} = 13694.986 \cdot \text{ft}^2$ 

$$A_{DR} = 13694.986 \cdot \text{ft}^2$$

$$A_{TA} = 77862.565 \cdot \text{ft}^2$$
  $A_{HA} = 56751.453 \cdot \text{ft}^2$   $A_{DA} = 21111.111 \cdot \text{ft}^2$ 

$$A_{DA} = 21111.111 \cdot ft^2$$

## WEIGHT BALANCE:

$$W_{FL} = 8287.388$$
 elton

$$W_1 = 2736.993$$
 olton

$$W_5 = 862.05$$
 •lton

$$W_{LS} = 5973.922$$
 olton

$$W_2 = 576.394$$
 •lton

$$W_6 = 462.912$$
 olton

$$W_P = 668.3$$
 olton

$$W_3 = 339.26$$
 elton

$$W_7 = 117.37$$
 elton

$$W_{F41} = 2053.939$$
 •lton

# $W_4 = 335.859$ •lton

# STABILITY/PAYLOAD:

$$F_P := \frac{W_P}{W_{FI}} \cdot 100 \qquad F_P = 8.0641$$

#### APPENDIX G. INTEGRATED SHIP DESIGN SYSTEM USER'S GUIDE

#### INTEGRATED SHIP DESIGN SYSTEM USER'S GUIDE

## 1. <u>Computer System Requirements.</u>

The ISDS was developed using the following software products:

- Microsoft Excel, Version 7.0 for Windows 95 for the Payload Spreadsheet.
- Mathcad 7 Professional for Windows 95 for the MIT Math Model and the MathConnex working environment.
- Matlab 5 with the Optimization Toolbox for the Numerical Optimizer.

## 2. <u>Getting Started.</u>

First and foremost it is strongly encouraged that the user become familiar with the mechanics of the application programs and the supporting documentation for the MIT Math Model prior to using ISDS.

- 2.1. Open ISDS in MathConnex. The worksheet will display the block and wire diagram of the ISDS, and by following the arrows you can step through the program logic path that connects the different application modules. The two view boxes display the intermediate results from the optimizer and the final design summary.
- 2.2. Open the file "outopt" in the Matlab editor/debugger. This file contains the diary output of the optimizer that is normally displayed in the Matlab command screen. When using MathConnex, the Matlab command screen is not viewed, so this permits the optimization details to be stored for later viewing and reviewing.
- 2.3. Each time the ISDS is run, "outopt" is updated and its contents should be viewed by the user to ensure the optimizer is producing feasible results.
- 2.4. To de-clutter the file after each session, "outopt" can be cleared by selecting all in the edit menu and then deleting.

## 3. Modify Payload Spreadsheet.

- 3.1 Double-click on the Excel icon to activate the Payload spreadsheet for editing.
- 3.2 Delete the contents of the cells of the combat systems that will NOT be installed in the design. Remember only to delete the cells with numerical values, not the system name, so that the data can be reloaded for different designs later on.
- 3.3 A complete Payload spreadsheet is included in the ISDS program files under the heading "mit\_payload". By using the cut and paste command, data can be easily reloaded into the MathConnex Excel spreadsheet from "mit\_payload".
- 3.4 Selected payload values are then loaded into the global variable "Payload" for

transfer to the Initial Values and Final Design Synthesis Mathcad worksheets.

## 4. Modify the Initial Values Mathcad Worksheet.

- 4.1 Double-click on the Initial Values Mathcad icon to open the Mathcad worksheet.
- 4.2 Inspect and modify, as required, the yellow highlighted sections. Cross-check highlighted values between Initial Values and Final Design Synthesis modules to ensure consistency between the two.
- 4.3 Three arrays are output from this module;
- The design variable independent weights and center of gravity data are output as "out0". This has a change variable name in Matlab to "w".
- The first guess at the design variable values for beam, draft and waterline length are output as "out1".
- Additional design specifics that need to be passed to the Matlab optimizer and The Final Design Synthesis Mathcad module are output as "out2". This has a change of variable name in Matlab to "z".

## 5. Modify the Matlab Optimizer Worksheet.

- 5.1 Double-click on the Matlab icon to activate the Matlab worksheet.
- 5.2 This Matlab worksheet contains the variables that control the optimization process. There are two choices for assigning the initial guess of the design variables, "x0". The first uses the guess generated by the Initial Values Mathcad worksheet, and the second can be manually input by the designer. To switch between the two, place a "%" in front of the line you want to inactivate and delete the "%" on the line you want to activate. Make sure you click the "check" button on the toolbar to save the change to the Matlab worksheet.
- 5.3 The side constraints of the design variables, vlb and vub, can be modified to ensure a global vice local minimum is being sought. Only the first three bounds should be modified, as the last two are constrained to keep the Math Model valid when using the Taylor Standard Series. Make sure you click the "check" button on the toolbar to save the change to the Matlab worksheet.

## 6. Cross-Check the Final Design Synthesis Mathcad Worksheet.

6.1 Make sure all the yellow highlighted sections match between the Initial Values and the Final Design Synthesis worksheets.

## 7. <u>Interpreting Results.</u>

7.1 Results are displayed in two view boxes within the ISDS MathConnex

- worksheet. The first view box contains the output from the Matlab optimizer. Additional optimization details are contained in the "outopt" file in the Matlab editor/debugger.
- 7.2 The second view box contains a summary of the Final Synthesis Design Mathcad worksheet. The Design Checks column should be scrutinized by the designer to ensure that the installed power plant is sufficient and that the area weight errors are reasonable.
- 7.3 If the area error is excessive, it can be adjusted by the designer to bring it into compliance. The deckhouse volume (V<sub>D</sub>) is the variable that is modified to adjust this error. In the Area/Volume Balance section of the Summary page in the Final Design Synthesis Mathcad worksheet there is a range for the value of V<sub>D</sub>. The model can be set up so that the value is calculated using the equation for V<sub>DMIN</sub> or V<sub>DMAX</sub> or any numerical value can be chosen between V<sub>DMIN</sub> and V<sub>DMAX</sub> and assigned as the value of V<sub>D</sub> in the worksheet. The Matlab function M-file "cubicnum\_calc" must also be modified so that the value of V<sub>D</sub> is consistently calculated. Change the value and run the ISDS again and check the area error, if it is still unreasonable, adjust V<sub>D</sub> up or down within the range until it reaches a reasonable error.
- 7.4 The entire detailed design can be reviewed by double-clicking on the Final Design Synthesis Mathcad icon.

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